Pooling or Sampling: Collective Dynamics for Electrical Flow Estimation

Emanuele Natale joint work with L. Becchetti[†] and V. Bonifaci*





AG1 Mittagsseminar 24 May 2018

Electrical Networks for Optimization

Computation of currents and voltages in resistive electrical network is a crucial primitive in many optimization algorithms

- Maximum flow
 - Christiano, Kelner, Madry, Spielman and Teng, STOC'11
 - Lee, Rao and Srivastava, STOC'13
- Network sparsification
 - Spielman and Srivastava, SIAM J. of Comp.
 2011
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 - Kelner and Madry, FOCS'09



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and as model of biological computation

Physarum

implicitly solving electrical polycephalum flow while forming

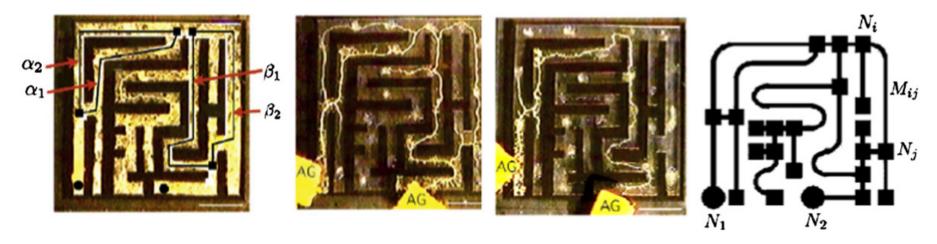
Ants

food-transportation networks

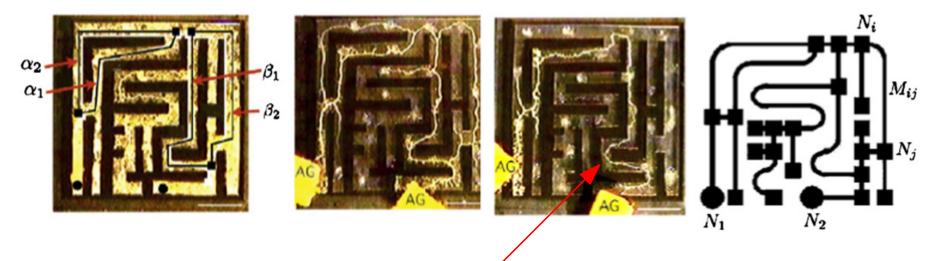
Many nice videos on Youtube:

https://bit.ly/1T5cSSY

Nakagaki, Yamada and Toth, Nature 2000 Tero, Kobayashi and Nakagaki J. of Theo. Bio. 2007

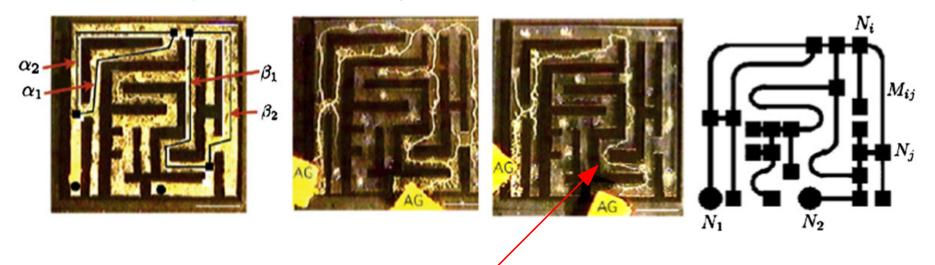


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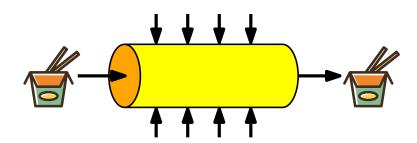


Physarum polycephalum builds *tubes* to transport food. The amount of food flowing in the tube determines its growth or deterioration.

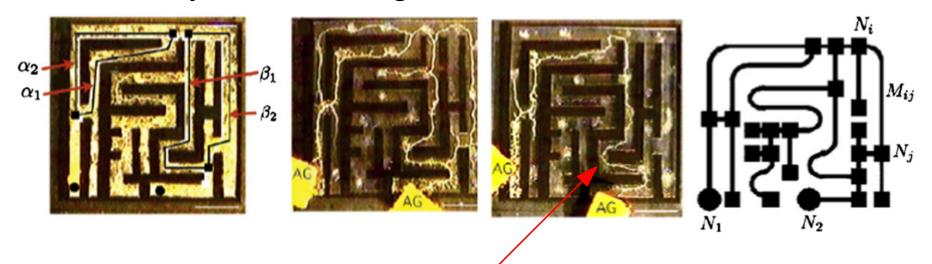
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- $r_e = \ell_e/x_e$ resistance to flow

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- there are demands b(u) such that
 - 1 on source,
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- flow conservation: $\sum_{v \sim u} q_{(u,v)} = b(u)$

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Dynamics: $\dot{x}_e = |q_e| - x_e$

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For each edge e and node u

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Is the model *good*?
See Slime Mold
Graph Repository,
Dirnberger et al.

Electrical Networks as Biological Models?...

hydraulic	electric
volume V [m 3]	charge q [C]
pressure p [Pa=J/m 3 =N/m 2]	potential ϕ [V=J/C=W/A]
Volumetric flow rate Φ_V [m 3 /s]	current I [A=C/s]
velocity $v \ [\mathrm{m/s}]$	current density j [C/(m ² ·s) = A/m ²]
Poiseuille's law $\Phi_V = rac{\pi r^4}{8\eta} rac{\Delta p^\star}{\ell}$	Ohm's law $j=-\sigma abla\phi$

(stolen from Wikipedia/Hydraulic_analogy)

electric network	Physarum	ant trails
length in space	length in space	length in space
potential/voltage	amount of nutrient	number of ants
current	flow of nutrient	flow of ants
conductivity	thickness of tube	pheromone concentration
capacitance	transport efficiency	total pheromone density
reinforcement intensity	tube expansion rate	pheromone drop rate
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For each edge e and node u

- q_e current
- resistance

- ℓ_e length b(u) 1 on source, -1 on sink, 0 o/w
- x_e conductivity Kirchhoff current law:

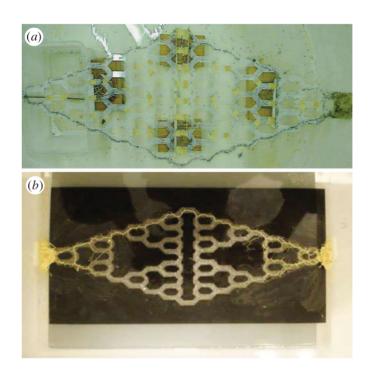
$$\sum_{v \sim u} q_{(u,v)} = b(u)$$

- $r_e = \ell_e/x_e$ Kirchhoff potential law: there are p(u)s
 - Ohm's law: $q_{(u,v)} = (p_u p_v)/r_e$

Dynamics: $\dot{x}_e = |q_e| - x_e$

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Ma, Johansson, Tero, Nakagaki and Sumpter, J. of the Royal Society Interface '13



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no ant traversing edge?...

Physarum Dynamics as an Algorithm

Bonifaci, Mehlhorn and Varma SODA'12: Physarum dynamics converges on all graphs (elegant proof in Bonifaci IPL'13)

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Euler's discretization

$$x(t+1) - x(t) = h(|q(t)| - x(t))$$

Becchetti, Bonifaci, Dirnberger, Karrenbauer and Mehlhorn ICALP'13:

Discretized physarum computes $(1 + \epsilon)$ -apx. in $\mathcal{O}(mL(\log n + \log L)/\epsilon^3)$

More Research on Physarum

Many sequels in TCS

- Bonifaci IPL'13,
- Straszak and Vishnoi ITCS'16,
- Straszak and Vishnoi SODA'16
- Becker et al. ESA'17

- ...

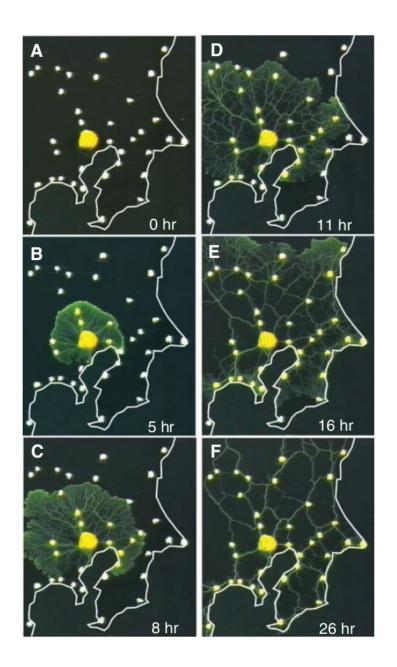
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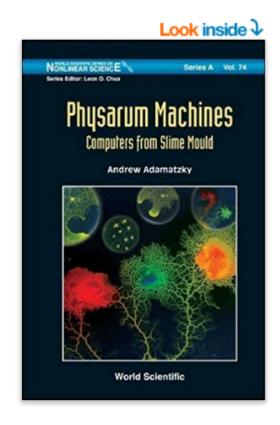
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- Becker et al. ESA'17

- ...

Some sequels elsewhere...
Tero et al. Science 2010:
Physarum re-builds
Tokyo's rail network!



More Research on Physarum









See all 3 images

Physarum Machines: Computers from Slime Mould (World Scientific Nonlinear Science, Series A) Hardcover – August 26, 2010

by Andrew Adamatzky ▼ (Author)

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A Physarum machine is a programmable amorphous biological computer experimentally implemented in the vegetative state of true slime mould Physarum polycephalum. It comprises an amorphous yellowish mass with networks of protoplasmic veins, programmed by spatial configurations of attracting and repelling gradients.

This book demonstrates how to create experimental Physarum machines for computational geometry and optimization, distributed manipulation and transportation, and general-purpose computation. Being very cheap to make and easy to maintain, the machine also functions on a wide range of substrates and in a broad scope of environmental conditions. As such a Physarum machine is a green and environmentally friendly unconventional computer.

The book is readily accessible to a nonprofessional reader, and is a priceless source of experimental tips and inventive theoretical ideas for anyone who is inspired by novel and emerging non-silicon computers and robots.

Read less

How to Compute with Electrical Networks

Physarum have to solve Kirchhoff's equations

$$\sum_{v \sim u} q_{(u,v)} = \sum_{v \sim u} (p_u - p_v)/r_e = b(u)$$

or Lp = b

- edge's weight x_e/ℓ_e
- D diagonal matrix of nodes' volumes
- A weighted incidence matrix
- L = D A

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Previous approaches: centralized computation

- Can be accomplished if every node is agent that follows elementary protocol? (biologically: what happens microscopically?)
- If yes, what is convergence time and communication overhead?

Distributed Jacobi's Method

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Jacobi's iterative method (Varga, 2009):
Bound on convergence rate w.r.t. graph conductance exploiting structure of laplacian (cfr. also DeGroot's model)
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 transition matrix

Jacobi's: $\tilde{p}(t+1) = P\tilde{p}(t) + b$

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Error
$$e(t) = p - \tilde{p}(t) = e_{\perp}(t) + \alpha \mathbf{1}$$

(p doesn't care about α : $L\mathbf{1} = 0$!)

$$p - e_{\perp} (t+1) - \alpha(t+1) \cdot \mathbf{1} = \tilde{p}(t+1)$$

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thus
$$e_{\perp}(t+1) = Pe_{\perp}(t) - (\alpha(t+1) - \alpha(t))\mathbf{1}$$

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thus
$$e_{\perp}(t+1)=Pe_{\perp}(t)-(\alpha(t+1)-\alpha(t))\mathbf{1}$$
 and $e_{\perp}(t)=\left(I-\frac{1}{n}\mathbf{1}\mathbf{1}^{\intercal}\right)P^{t}e_{\perp}(0).$

 $P=D^{-1}A$ is similar to $N=D^{-1/2}AD^{-1/2}$. Thus

$$P^{t} = (D^{-1}A)^{t} = (D^{-\frac{1}{2}}ND^{\frac{1}{2}})^{t} = D^{-\frac{1}{2}}N^{t}D^{\frac{1}{2}}.$$

Observe that

- N has n orthonormal eigenvec. $\vec{x}_1, \ldots, \vec{x}_n$, corresponding to eigenvectors $\vec{y}_1, \ldots, \vec{y}_n$ of P via $\vec{x}_i = D^{1/2} \vec{y}_i$ for each i.
- Both \vec{x}_i and \vec{y}_i , for each i, are associated to the same eigenvalue ρ_i of P.

$$\begin{aligned} &\|e_{\perp}\left(t\right)\| \\ &= \left\| \left(I - \frac{1}{n} \mathbf{1} \mathbf{1}^{\mathsf{T}}\right) P^{t} e_{\perp}(0) \right\| \\ &= \left\| \left(I - \frac{1}{n} \mathbf{1} \mathbf{1}^{\mathsf{T}}\right) D^{-\frac{1}{2}} N^{t} D^{\frac{1}{2}} e_{\perp}(0) \right\| \end{aligned}$$

Jacobi's Convergence

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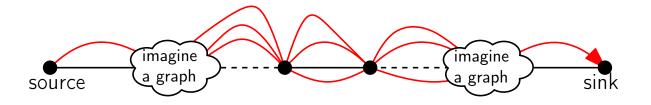
Conductance by Cheeger's inequality

Randomized Token Diffusion Process

Doyle and Snell, '84 & Tetali, '91:

Times a random walk transits through given edge until hitting the sink

- global requirement
- no accuracy and msg. complexity bounds

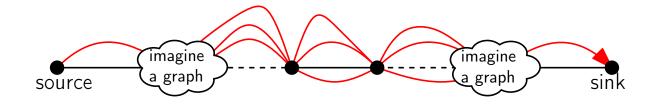


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Our's:

How many tokens are on a node

- *local* requirement
- accuracy and msg. complexity w.r.t. edge expansion

Randomized Token Diffusion Process

Process

- At the beginning of each step, K new tokens appear at the source
- Each token independently performs a weighted random walk at each step
- Each token that hits the sink disappears

Estimator

$$V_K^{(t)} = rac{Z_K^{(t)}(u)}{K \cdot \mathrm{vol}(u)}$$
 where $Z_K^{(t)}(u)$ number of tokens on u

Expected Behavior

Define inductively $\mathbf{p}^{(t)}$ by

$$p_u^{(0)} = 0, \qquad \text{for all } u \in \mathcal{V},$$

$$p_u^{(t+1)} = \begin{cases} \frac{1}{\text{vol}(u)} \left(\sum_{v \sim u} w_{uv} p_v^{(t)} + b_u \right) & \text{if } u \neq \text{sink}, \\ 0 & \text{if } u = \text{sink}. \end{cases}$$

Lemma. If
$$V_K^{(t)}(u)=\frac{Z_K^{(t)}(u)}{K\mathrm{vol}(u)},$$
 then $\mathbb{E}[V_K^{(t)}(u)]=p_u^{(t)}$.

Correctness of Token Diffusion

We can write

$$\begin{cases} \mathbf{p}^{(0)} &= \vec{0}, \\ \mathbf{p}^{(t+1)} &= \underline{P} \mathbf{p}^{(t)} + D^{-1} \underline{\vec{b}}, \end{cases}$$

with \underline{P} and $\underline{\vec{b}}$ obtained by zeroing out entries on row and column of sink.

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Theorem. System above converges to a valid potential with rate ρ .

Time and Message Complexity

Theorem.
$$1 - \underline{\rho} \ge \frac{\overline{\lambda}_2}{2 \text{vol}_{\max}(n-1)} \sum_i \frac{w_{in}}{w_{in} + \overline{\lambda}_2}$$

where $\overline{\lambda}_2$ is 2nd smallest eigenvalue of non-normalized laplacian of graph with sink removed.

Connecting with *edge expansion*: it is known
$$\lambda_2(\mathcal{G}) \geq \operatorname{vol}_{\max} - (\operatorname{vol}_{\max}^2 - \theta(\mathcal{G})^2)^{1/2}.$$

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Remark. As $t \to \infty$, the expected message complexity per round of Token Diffusion Algorithm is $O(K \, n \, \text{vol}_{\text{max}} \cdot E)$, where $E = \vec{p}^\intercal L \vec{p}$ is the energy of the electrical flow.

Stochastic Accuracy

X gives (ϵ, δ) -approximation of Y if $\mathbf{P}(|X - Y| > \epsilon Y) \le \delta$.

Lemma. For any K, $0 < \epsilon, \delta < 1$, t and u, such that $p_u^{(t)} \ge \frac{3}{\epsilon^2 K \text{vol}(u)} \ln \frac{2}{\delta}$, the estimator provides an (ϵ, δ) -approximation of $p_u^{(t)}$.

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Vice versa. (ϵ, δ) -approximation of the potentials $p_u^{(t)}$ greater than $p_\star^{(t)}$ is achieved by setting $K \geq \frac{3}{\epsilon^2 p_\star^{(t)} \operatorname{vol}(u)} \ln \frac{2}{\delta}$.

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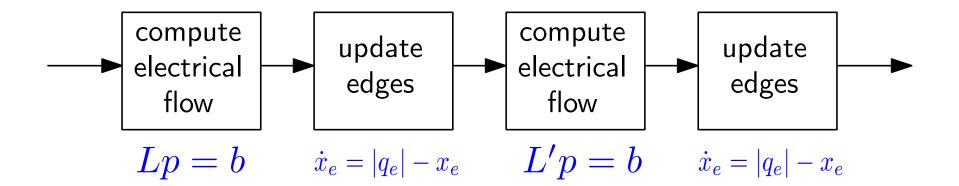
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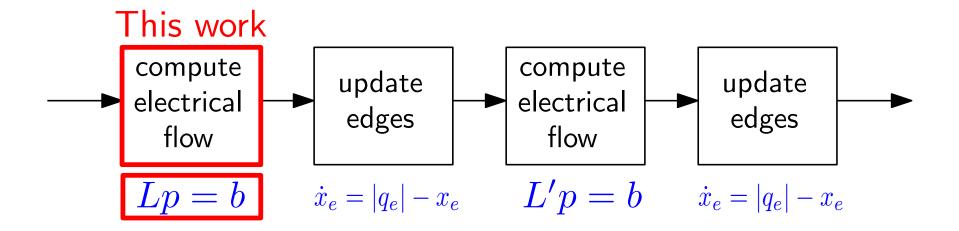
Vice versa. (ϵ, δ) -approximation of the potentials $p_u^{(t)}$ greater than $p_\star^{(t)}$ is achieved by setting $K \geq \frac{3}{\epsilon^2 p_\star^{(t)} \operatorname{vol}(u)} \ln \frac{2}{\delta}$.

Proof. Chernoff bound requires $Y > 1/\epsilon^2$.

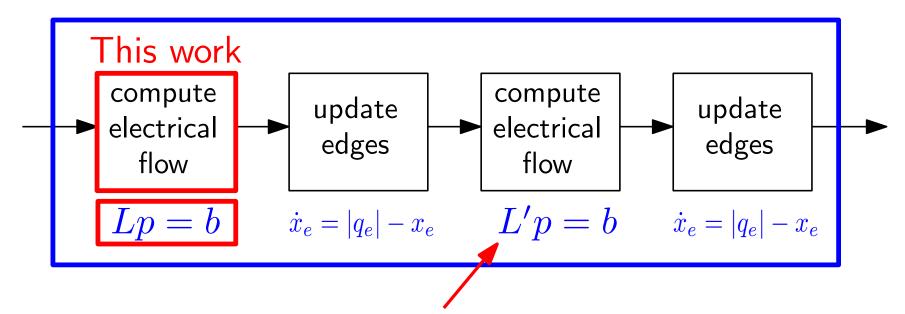
Physarum dynamics et sim.: Compute electrical flow, then *update edge-weigths*



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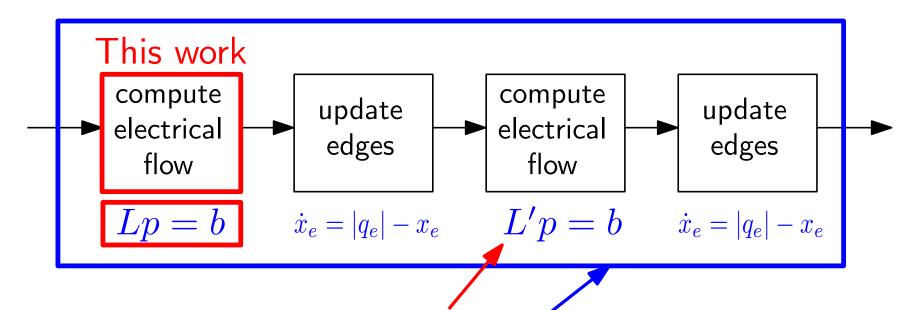
Physarum dynamics et sim.: Compute electrical flow, then *update edge-weigths*



• Spectral structure of L'?

Physarum dynamics et sim.:

Compute electrical flow, then update edge-weigths



- Spectral structure of L'?
- Global convergence timé?

