

Natural Distributed Algorithms

- Lecture 2 - Rumor Spreading in the Noisy PUSH Model



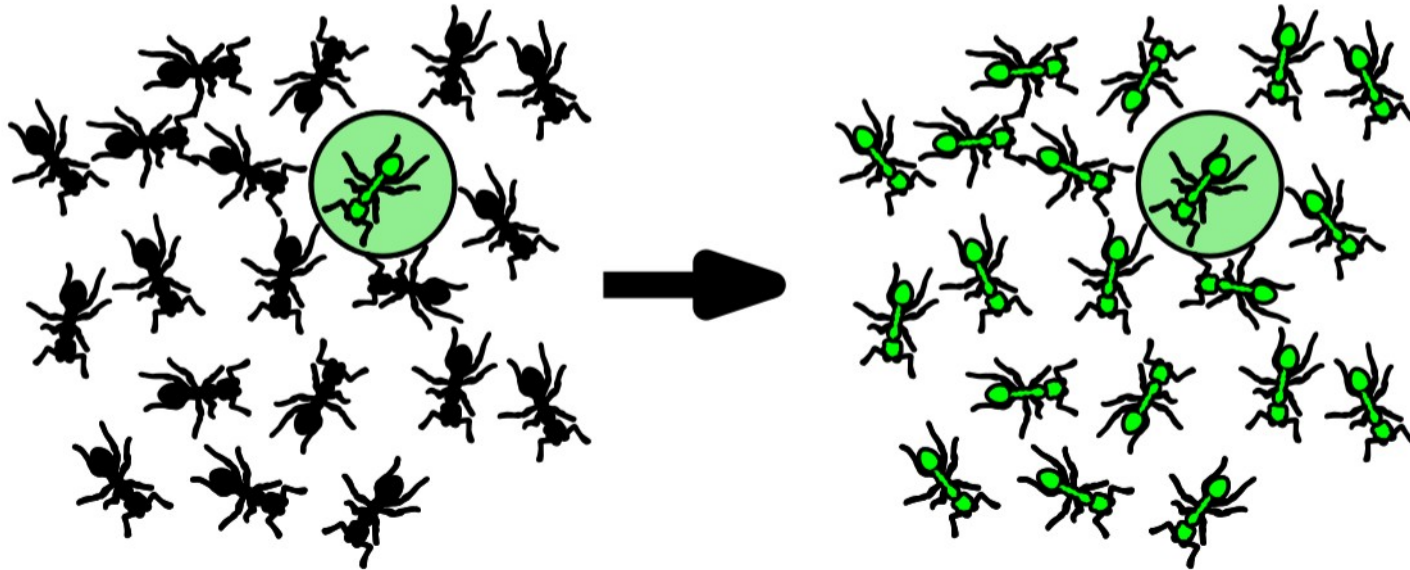
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CdL in Informatica
Università degli Studi di Roma "Tor Vergata"



Rumor Spreading Problem



- One **source** node in a **special state**
- **Goal configuration**: all agents in the **special state**

Stochastic Interactions: **PUSH** Model



Desired features

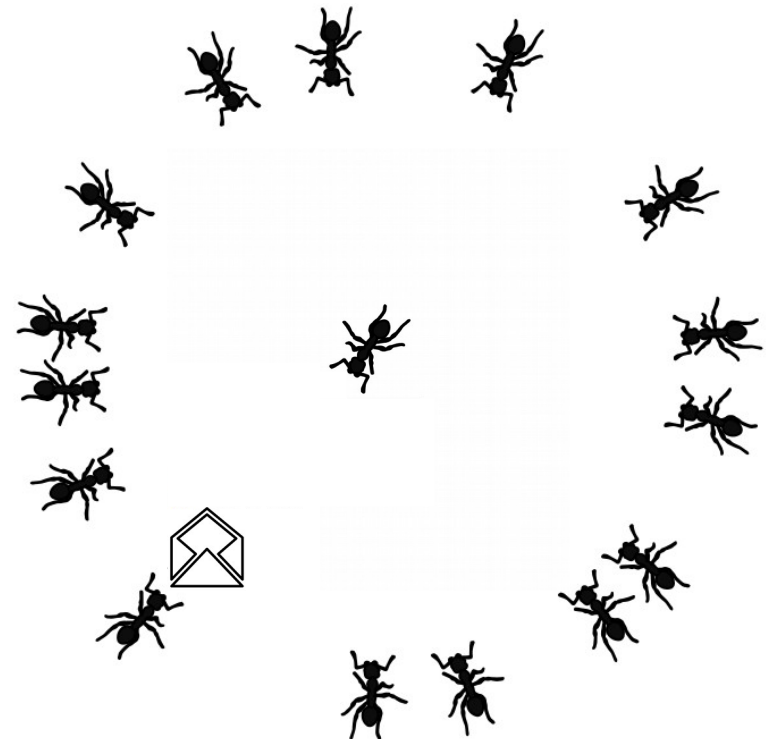
- Stochastic
- Parsimonious (Anonymous)
- **Active** (uni-directional)

(Uniform) PUSH model

[Demers '88]

(single binary message)

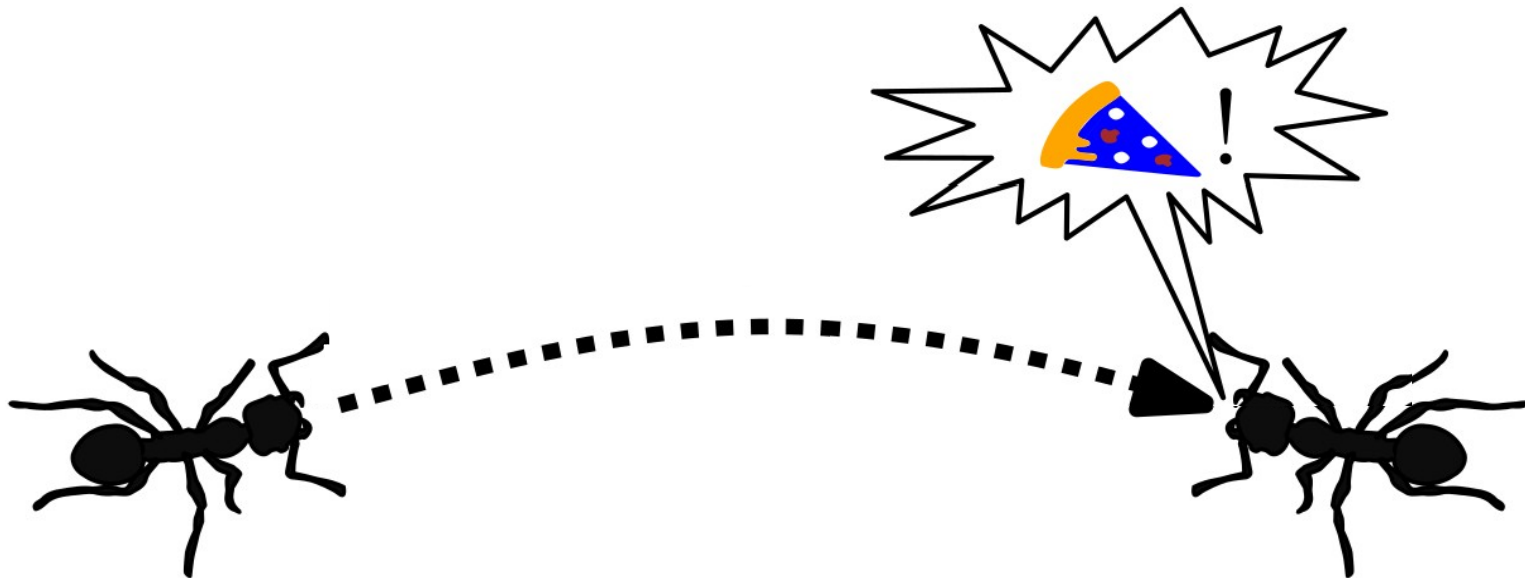
- Discrete parallel time
- At each round each agent **can send one bit** message
- **Each message is received by one agent** chosen independently and uniformly at random



Noisy Communication



Before being received,
each bit is flipped with probability $\frac{1}{2} - \epsilon$



1 bit per message,
noise flips it with prob $\frac{1}{2} + \epsilon$

Rumor Spreading in the **Noisy** PUSH Model: “Chinese-Whispers” **Does Not Work**



If each agent sends the **rumor** as soon as it receives it...

If $M^{(t)}$ is the received message, $p_t := \Pr(M^{(t)} = 1)$
and $q_t := 1 - p_t = \Pr(M^{(t)} = 0)$

$$\begin{pmatrix} p_t \\ q_t \end{pmatrix} = \begin{pmatrix} \frac{1}{2} + \epsilon & \frac{1}{2} - \epsilon \\ \frac{1}{2} - \epsilon & \frac{1}{2} + \epsilon \end{pmatrix} \begin{pmatrix} p_{t-1} \\ q_{t-1} \end{pmatrix} = \begin{pmatrix} \frac{1}{2} + \epsilon & \frac{1}{2} - \epsilon \\ \frac{1}{2} - \epsilon & \frac{1}{2} + \epsilon \end{pmatrix}^t \begin{pmatrix} p_0 \\ q_0 \end{pmatrix} \approx \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

Breathe-Before-Speaking Algorithm

Feinerman, Ofer, Bernhard Haeupler, and Amos Korman. 2017. "Breathe before Speaking: Efficient Information Dissemination despite Noisy, Limited and Anonymous Communication." Distributed Computing 30 (5): 339–55. <https://doi.org/10.1007/s00446-015-0249-4>.

Idea. Reduce number of “message hops” from the source.

Algorithm “Breathe-Before-Speaking” (informal description)

Stage 1:

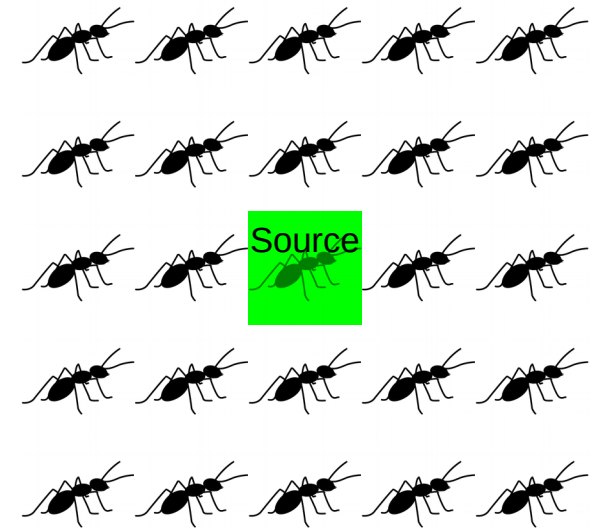
For $O(\log n)$ **phases**:

At each round of each phase:

- each **informed** agent **sends** its **opinion**
- each **uninformed** agent **only listens** to incoming messages

At the end of the phase each **uninformed** that has received a message becomes **informed** with the **opinion** that it has received

Stage 2:



Example with phases
of 3 steps

Breathe-Before-Speaking Algorithm: Core Idea of Stage 1

If a phase lasts $k \geq 2$ rounds (each agent sends k messages)

$$\mathbb{E} \left[I^{(t)} \mid I^{(t-1)} = i \right] = i + (n - i) \left(1 - \left(1 - \frac{1}{n} \right)^{ik} \right)$$

$$\text{using } 1 - x \leq e^{-x} \quad \geq i \left(1 + \left(\frac{n}{i} - 1 \right) \left(1 - e^{-k \frac{i}{n}} \right) \right)$$

$$\begin{array}{l} \text{using } e^{-x} \geq 1 - \frac{x}{2} \\ \text{and assuming } i \leq \frac{n}{k} \end{array} \quad \geq i \left(1 + \left(\frac{n}{i} - 1 \right) \frac{k}{2} \frac{i}{n} \right)$$

$$\geq i \left(1 + \left(1 - \frac{i}{n} \right) \frac{k}{2} \right)$$

$$\geq i \left(1 + \frac{k}{4} \right) \quad \text{How large should } k \text{ be?}$$

From Stage 1 to Stage 2: How Many Rounds in a Phase?

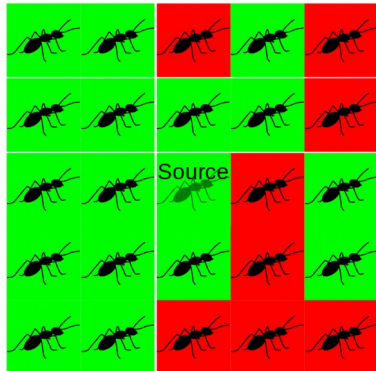
If $M^{(t)}$ is the received message,

$p_t := \Pr(M^{(t)} = 1)$ and

$q_t := 1 - p_t = \Pr(M^{(t)} = 0)$

RECALL

$$\begin{pmatrix} p_t \\ q_t \end{pmatrix} = \begin{pmatrix} \frac{1}{2} + \epsilon & \frac{1}{2} - \epsilon \\ \frac{1}{2} - \epsilon & \frac{1}{2} + \epsilon \end{pmatrix} \begin{pmatrix} p_{t-1} \\ q_{t-1} \end{pmatrix}$$



We want the *bias* $\delta_t = |p_t - q_t|$
to be as large as possible

What bias is enough? \rightarrow Typically $\Omega(\sqrt{n \log n})$

How are we going to *use* the bias?

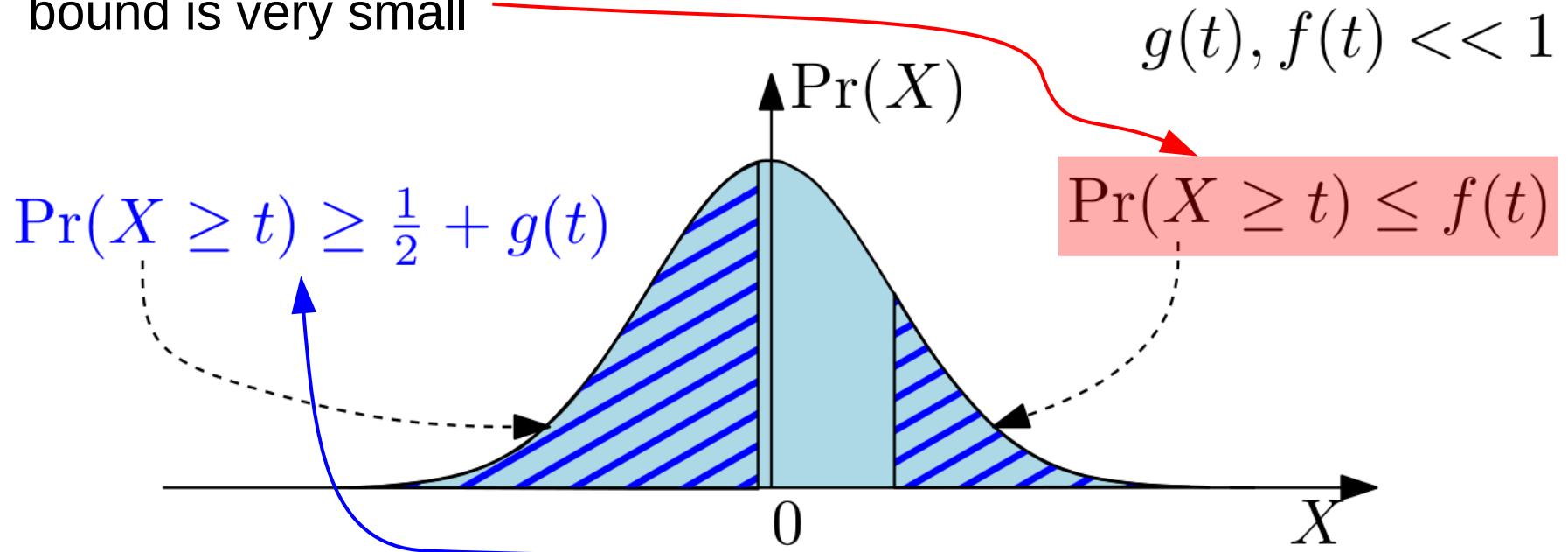
Algorithm “Breathe-Before-Speaking” (informal description)

Stage 1: (all agents got an **opinion**)

Stage 2: For $O(\log n)$ **phases**, at each round each agent **sends** its **opinion** and **counts** the **opinions** of received messages. At the end of the phase each agent takes the **most frequent opinion**.

Mathematical Challenge: Small Deviations Theory

There is a well-established **large deviations theory** concerned with showing that the probability that a r.v. exceeds a certain bound is very small



Warning: In Multi-Agent Systems (MAS), ensuring that a node doesn't make an error can be computationally expensive (e.g. needs many messages).

Since in MAS we have many agents, if we can easily solve the **majority consensus problem**, it is enough that the **majority is right**.

Majority Amplification of Small Deviations

Idea of Stage 2. Use majority rule to amplify bias (reduce noise).

optimal rule

If $M^{(t)}$ is the received message,

$p_t := \Pr(M^{(t)} = 1)$ and

$q_t := 1 - p_t = \Pr(M^{(t)} = 0)$

$$\delta_t = |p_t - q_t|$$

$$= \left| \left(\frac{1}{2} + \epsilon \right) p_{t-1} + \left(\frac{1}{2} - \epsilon \right) q_{t-1} - \left(\left(\frac{1}{2} - \epsilon \right) p_{t-1} + \left(\frac{1}{2} + \epsilon \right) q_{t-1} \right) \right|$$

(Recall: bias decreases exponentially if we forward directly!) $\longrightarrow = 2\epsilon\delta_{t-1}$
 effective bias

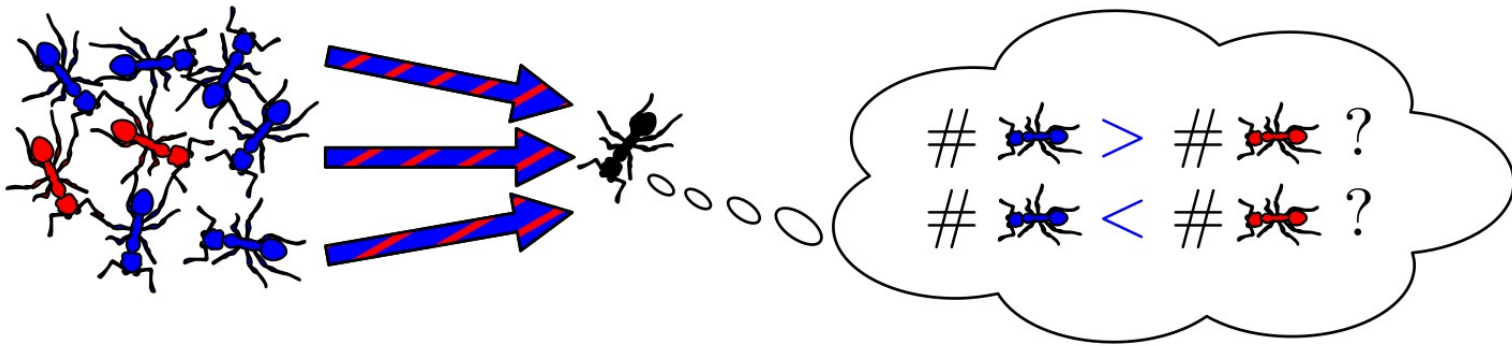
How much does bias increases if we wait that we receive k messages and then send the majority? (*Breathe before speaking!*)

Attention! If we wait k rounds we can only say that the majority of nodes will receive at least $k/2$ messages (Why? Chernoff bound...)

Majority Amplification Lemma (1/2)

RECALL

Stage 2: For $O(\log n)$ **phases**, at each round each agent **sends** its **opinion** and **counts** the opinions of received messages. At the end of the phase each agent takes **the most frequent** opinion.



Lemma

If X_1, \dots, X_n are i.i.d. binary r.v.s with bias $\lambda = |\Pr(X_i = 1) - \Pr(X_i = 0)|$ then the majority value m has bias

$$|\Pr(m = 1) - \Pr(m = 0)| \geq \min \left\{ \sqrt{n}\lambda, \frac{1}{4} \right\}.$$

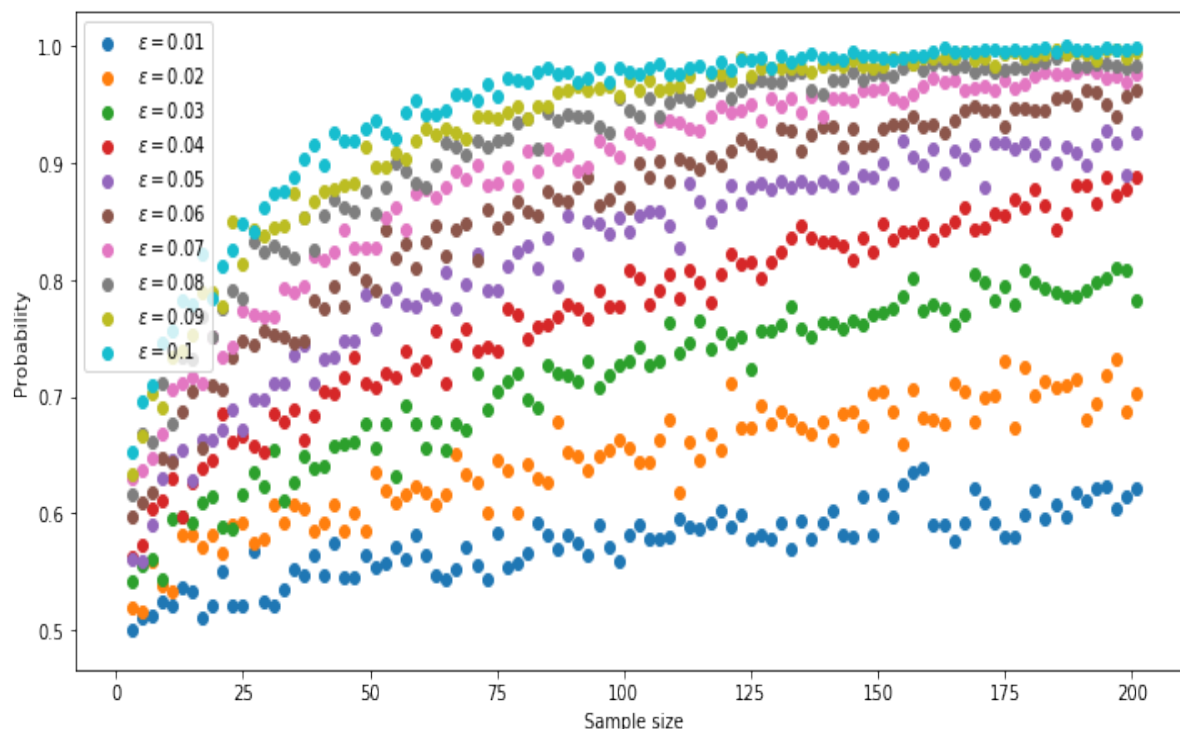
How is the Lemma used?

Application of Majority Amplification Lemma (2/2)

$$|\Pr(m = 1) - \Pr(m = 0)| \geq \min \left\{ \sqrt{n\lambda}, \frac{1}{4} \right\}.$$

Let $X_1 = M^{(t)}, \dots, X_n = M^{(t+n)}$ be the noisy messages received during a phase of Stage 2

The effective bias is $\lambda = 2\epsilon\delta$, where δ is the difference between the fraction of nodes with correct and wrong opinion



$$|\Pr(m = 1) - \Pr(m = 0)| \geq \min \left\{ \sqrt{\text{phase length} \cdot 2\epsilon\delta}, \frac{1}{4} \right\}.$$

If phase length $> \frac{4}{\epsilon^2}$ then δ grows by a factor 2 at each phase.

Once the effective bias is $> \frac{1}{4}$, one phase of $O(\log n)$ is enough.
(Chernoff bounds)

Breathe-Before-Speaking Algorithm: Summary

Stage 1:

→ For $O(\log n)$ **phases:** $\rightarrow (t_i = O(\frac{1}{\epsilon^2})$ except first and last phase)

At each of the t_i rounds of each phase:

- each **informed** agent **sends** its **opinion**
- each **uninformed** agent **only listens** to incoming messages

At the end of the phase each **uninformed** that has received a message becomes **informed** with the **opinion** that it has received

Stage 2:

For $O(\log n)$ **phases:** $\rightarrow (t_i = O(\frac{1}{\epsilon^2})$ except first and last phase)

At each of the t_i rounds of each phase:

- each agent **sends** its **opinion**
- each agent **counts** the **opinions** of received messages.

At the end of the phase each agent takes **the most frequent opinion**.

(Half of the) Proof of Majority Amplification

If X_1, \dots, X_n are i.i.d. binary r.v.s with n odd and bias $\lambda = |\Pr(X_i = 1) - \Pr(X_i = 0)|$ then the majority value m has bias

$$|\Pr(m = 1) - \Pr(m = 0)| \geq \min \left\{ \sqrt{n}\lambda, \frac{1}{4} \right\}.$$

(Half-)Proof

Two cases: $n > \frac{1}{\lambda^2}$ and $n < \frac{1}{\lambda^2}$

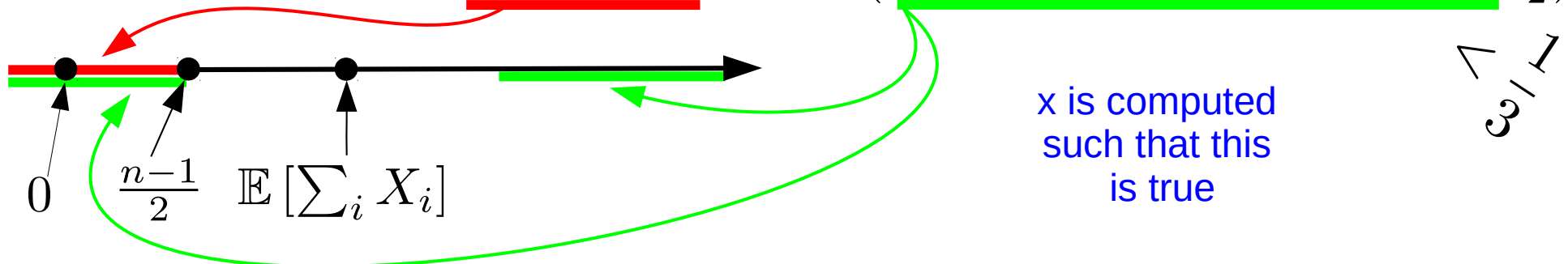
First case: We use **Chebyshev's inequality** $\rightarrow P(|Y - \mathbb{E}[Y]| \geq x) \leq \frac{\text{Var}[Y]}{x^2}$

$$\mathbb{E}[\sum_i X_i] = n \left(\frac{1}{2} + \lambda \right)$$

$$\text{Var}[\sum_i X_i] = n \left(\frac{1}{4} - \lambda^2 \right)$$

(Correct opinion is w.l.o.g. 1)

$$P(m = 0) = P\left(\sum_i X_i \leq \frac{n-1}{2}\right) \leq P\left(|\sum_i X_i - \mathbb{E}[\sum_i X_i]| > n\lambda - \frac{1}{2}\right)$$



The $n < \frac{1}{\lambda^2}$ Case: Intuition

Observation:

We can simulate a coin C_p with probability p using a uniform random variable

```
[1]: from random import uniform
```

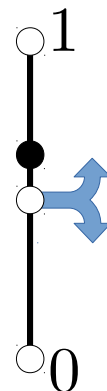
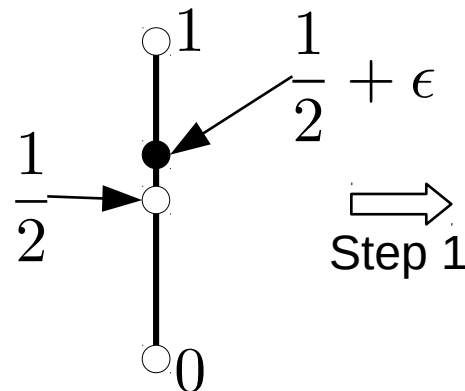
```
[11]: def coin(p):  
       return uniform(0,1)<p
```

```
[12]: [coin(1/3) for i in range(10)]
```

```
[12]: [False, False, False, False, False,  
       True, False, True, False, False]
```

(Correct opinion is w.l.o.g. 1)

We can simulate $C_{\frac{1}{2}+\epsilon}$ as follows:



Is the uniform variable less than .5?
Yes \rightarrow 1
No \rightarrow continue

Given that the uniform variable is more than .5, is it **here?**
Yes \rightarrow 1
No \rightarrow 0

Step 1: Flip $C_{\frac{1}{2}}$

Step 2: Flip coin with prob.

$$P(U \in (\frac{1}{2}, \frac{1}{2} + \epsilon) | U \geq \frac{1}{2}) \\ = \frac{P(U \in (\frac{1}{2}, \frac{1}{2} + \epsilon))}{P(U \geq \frac{1}{2})} = 2\epsilon$$

$$C_{\frac{1}{2}+\epsilon} = C_{\frac{1}{2}} + (1 - C_{\frac{1}{2}})C_{2\epsilon}$$

Throw n variables $C_{\frac{1}{2}}$ and n corresponding variables $C_{2\epsilon}$. If the majority of $C_{\frac{1}{2}}$ s is 1, ok, otherwise, if we miss z 1s for the majority to be 1, we look at the prob that at least z $C_{2\epsilon}$ s are 1.

...Project Idea

As for the case $n < \frac{1}{\lambda^2}$,
there are two proofs, both accessible but with lots of
calculations:

- Feinerman, Ofer, Bernhard Haeupler, and Amos Korman. 2017. “Breathe before Speaking: Efficient Information Dissemination despite Noisy, Limited and Anonymous Communication.” *Distributed Computing* 30 (5): 339–55. <https://doi.org/10.1007/s00446-015-0249-4>.
- Fraigniaud, Pierre, and Emanuele Natale. 2019. “Noisy Rumor Spreading and Plurality Consensus.” *Distributed Computing* 32 (4): 257–76. <https://doi.org/10.1007/s00446-018-0335-5>.

Project: (First, understand and then) write
a detailed exposition of either one of the
proofs.



More Project Ideas

- Write the analysis **in expectation** of Phase 1 of the Breathe-Before-Speaking algorithm.

The reasoning is similar to what we have done for the “Chinese-whispers protocol” in order to solve the non-noisy rumor spreading problem. You can also check the analysis w.h.p. (much, much harder than in expectation!), in

- Feinerman, Ofer, Bernhard Haeupler, and Amos Korman. 2017. “Breathe before Speaking: Efficient Information Dissemination despite Noisy, Limited and Anonymous Communication.” *Distributed Computing* 30 (5): 339–55. <https://doi.org/10.1007/s00446-015-0249-4>.
- Fraigniaud, Pierre, and Emanuele Natale. 2019. “Noisy Rumor Spreading and Plurality Consensus.” *Distributed Computing* 32 (4): 257–76. <https://doi.org/10.1007/s00446-018-0335-5>.

- Simulate the Breathe-Before-Speaking algorithm on Erdős-Rényi graphs (random graphs where each edge is added with probability p), varying p , the noise parameter ϵ and the duration of the time-windows. *Simulations should be performed using open-source software with some effort to make them efficient (e.g. coded in Python using Numpy), and the source code should be made publicly available (e.g. on Gitlab) and GPL licensed.*

Likelihood Ratio Test (Neyman-Pearson Lemma)

X_1, \dots, X_n i.i.d. r.v.s, all with distribution either P_0 or P_1 .

$\psi(\mathbf{x}) \in \{0, 1\}$ with $\mathbf{x} = (x_1, \dots, x_n)$ is any function that guesses whether the distribution is P_0 (when $\psi = 0$) or P_1 (when $\psi = 1$).

$$P_0(\psi = 1) + P_1(\psi = 0)$$

$$= P_0(\psi = 1) + 1 - P_1(\psi = 1) = 1 + \sum_{\substack{\mathbf{x} \text{ s.t.} \\ \psi(\mathbf{x})=1}} (P_0(\mathbf{x}) - P_1(\mathbf{x}))$$

$$= 1 + \sum_{\substack{\mathbf{x} \text{ s.t.} \\ \psi(\mathbf{x})=1 \\ P_0(\mathbf{x}) \geq P_1(\mathbf{x})}} (P_0(\mathbf{x}) - P_1(\mathbf{x})) + \sum_{\substack{\mathbf{x} \text{ s.t.} \\ \psi(\mathbf{x})=1 \\ P_0(\mathbf{x}) < P_1(\mathbf{x})}} (P_0(\mathbf{x}) - P_1(\mathbf{x}))$$

If we define $\psi = \mathbf{1}[P_0(\mathbf{x}) < P_1(\mathbf{x})]$, error is minimized

Back to
Majority
Amplification

Chebyshev's Inequality

Recall **Markov's inequality**: Given positive random variable X

$$\begin{aligned}\mathbb{E}[X] &= \sum_{i=1}^{\infty} i \Pr(X = i) \geq \sum_{i=t}^{\infty} i \Pr(X = i) \\ &\geq \sum_{i=t}^{\infty} t \Pr(X = i) = t \Pr(X \geq t)\end{aligned}$$

To prove **Chebyshev's inequality**, given a r.v. Y , set

$$X = (Y - \mathbf{E}[Y])^2$$

...and apply Markov's inequality

$$\begin{aligned}P(|Y - \mathbb{E}[Y]| \geq t) &= \\ P\left((Y - \mathbb{E}[Y])^2 \geq t^2\right) &\leq \frac{\mathbb{E}\left[(Y - \mathbb{E}[Y])^2\right]}{t^2} = \frac{\text{Var}[Y]}{t^2}\end{aligned}$$

Back to
Proof of
Lemma

Experiments on Majority Amplification

```
In [1]: import numpy as np
```

```
In [2]: x = [2*i+1 for i in range(1,101)]
```

```
In [3]: eps = [0.01*i for i in range(1,11)]
```

```
In [4]: bias = [2*epsilon for epsilon in eps]
```

```
In [5]: trials = 1000
result = np.empty([len(eps), len(x)])
for i in range(len(eps)):
    prob = 1/2+eps[i]
    for j in range(len(x)):
        experiments = np.random.binomial(x[j], prob, trials)
        successes = list(map(lambda y: y>x[j]/2, experiments))
        result[i][j] = sum(successes)/trials
```

```
In [6]: import matplotlib.pyplot as plt
```

```
In [7]: plt.figure(figsize=(12,6))
for i in range(len(eps)):
    plt.scatter(x, result[i][:], label='$\epsilon='+str(eps[i]))
plt.xlabel('Sample size')
plt.ylabel('Probability')
plt.legend()
```

Jupyter-lab notebook (included in the [Anaconda Python distribution](#))

Back to
the Lemma
Application

Computing t

$$\mathbb{E} \left[\sum_i X_i \right] = (2\gamma + 1) \left(\frac{1}{2} + \delta \right) = \gamma \left(1 + \delta + \frac{1}{\gamma} \left(\frac{1}{2} + \delta \right) \right)$$

$$\begin{aligned} t &= \gamma \left(1 + \delta + \frac{1}{\gamma} \left(\frac{1}{2} + \delta \right) \right) - \gamma \\ &= \gamma \left(\delta + \frac{1}{2\gamma} (1 + 2\delta) \right) < 2\gamma\delta (1 + \delta) \end{aligned}$$

$$\begin{aligned} P \left(\left| \sum_i X_i - \mathbb{E} \left[\sum_i X_i \right] \right| > 2\gamma\delta (1 + \delta) \right) &< \frac{\gamma (1 + \delta)}{2 (2\gamma\delta (1 + \delta))^2} \\ &= \frac{1}{8\gamma} \frac{1}{\delta^2 (1 + \delta)} < \frac{1}{8\gamma\delta^2} < \frac{1}{3} \end{aligned}$$

Requirement for Concentration via CB

Let X_i be independent r.v.s with $|X_i| \leq M$, then

$$\Pr \left(\left| \sum_i X_i - \mathbb{E} \left[\sum_i X \right] \right| \geq \Delta \right) \leq 2e^{-\frac{\Delta^2}{2(\sum_i \mathbb{E}[X_i^2] + \frac{M}{3} \Delta)}}$$

Since we want “w.h.p.” we need that on the r.h.s. $e^{\text{quantity}} \leq \frac{1}{n}$, that is

$$\text{quantity} = -\frac{\Delta^2}{2\mathbb{E}[\sum_i X_i] + \frac{2}{3}\Delta} \leq \log \frac{1}{n} = -\log n$$

that is $3\Delta^2 - 2\log n\Delta - 6\log n\mathbb{E}[\sum_i X_i] \geq 0$, which requires that

$$\Delta \geq \frac{1}{3} \log n \left(1 + \sqrt{1 + 18 \frac{\mathbb{E}[\sum_i X_i]}{\log n}} \right)$$

Note that we need at least $\Delta \leq \mathbb{E}[\sum_i X_i]$.

