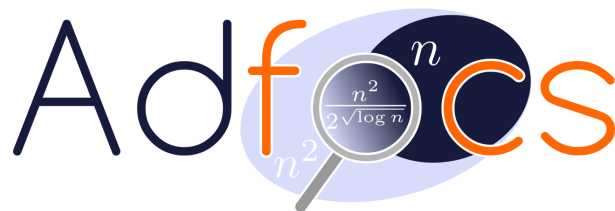


Consensus needs *Broadcast*
in Noiseless Models
but can be Exponentially Easier
in the Presence of Noise

Emanuele Natale

Joint work with A. Clementi, L. Gualà, F. Pasquale,
G. Scornavacca and L. Trevisan

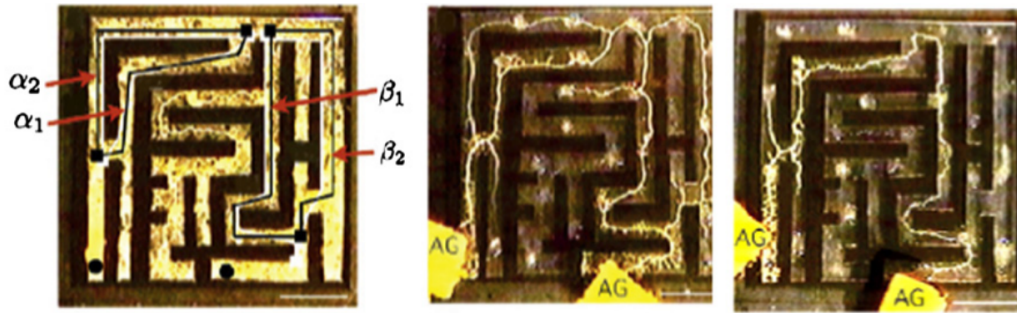


August 15th, 2018

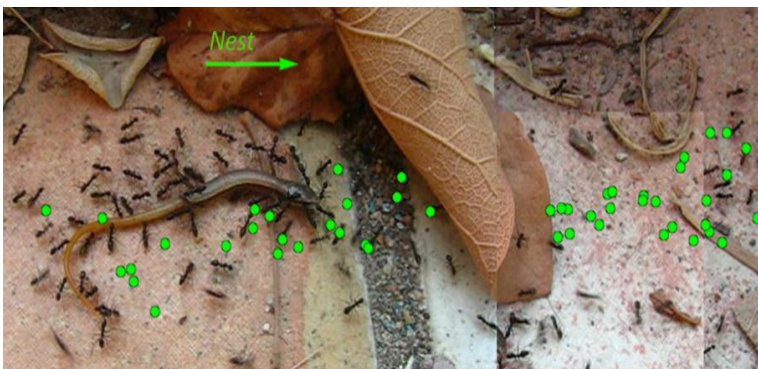
Natural Algorithms



How do flocks of birds
synchronize their flight?
[Chazelle '09]



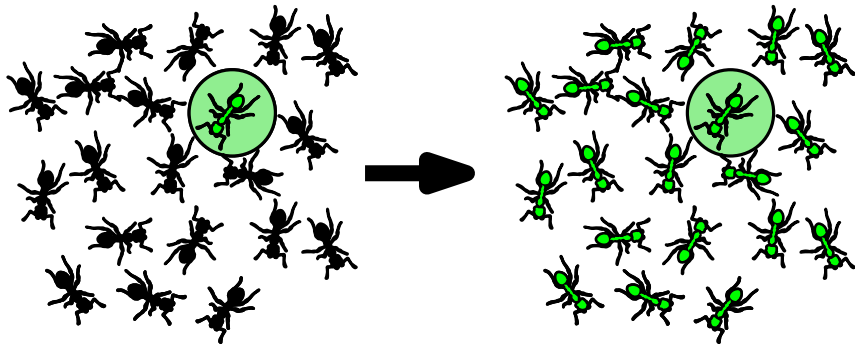
How does *Physarum polycephalum*
finds shortest paths? [Mehlhorn et al. 2012-...]



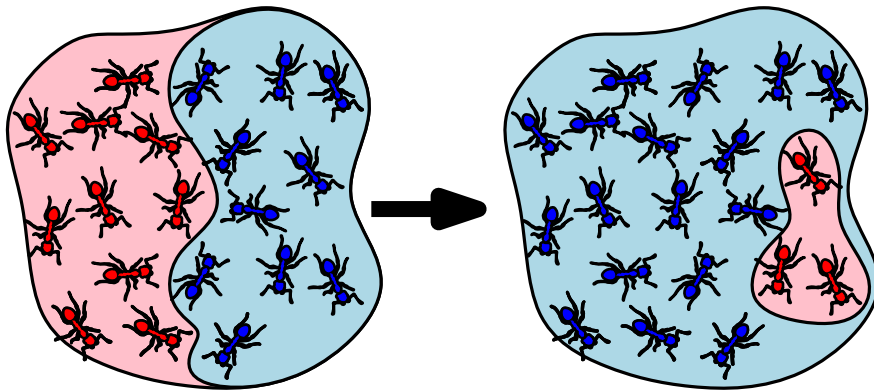
How ants perform
collective
navigation? How
do they decide
where to relocate
their nest?



Noisy vs Noiseless Broadcast and Consensus



Broadcast. All agents eventually receive the message of the source.

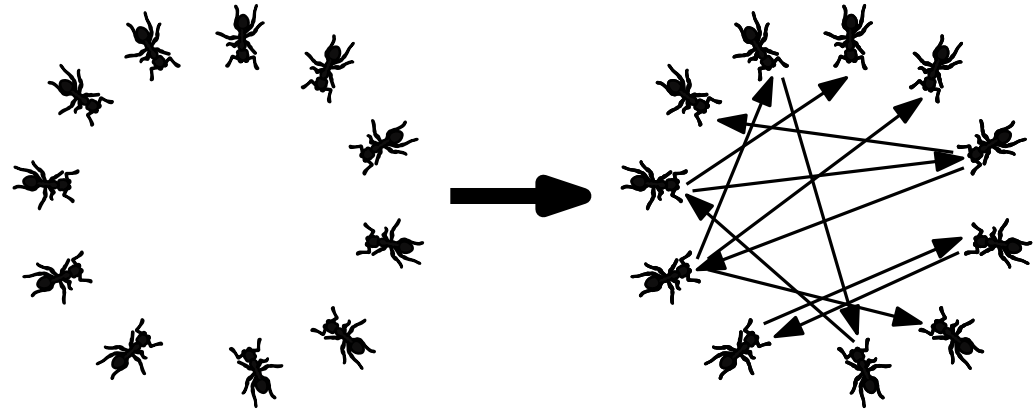


(Valid) δ -Consensus. All agents but a fraction δ , eventually support the value initially supported by one of them.

Noisy & Stochastic Interactions

Stochastic Interactions.

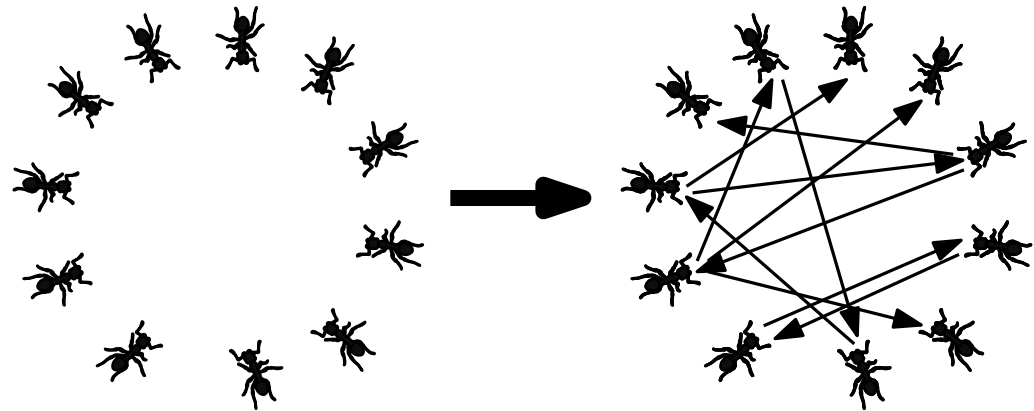
At each round, each agent receives a message from another random agent.



Noisy & Stochastic Interactions

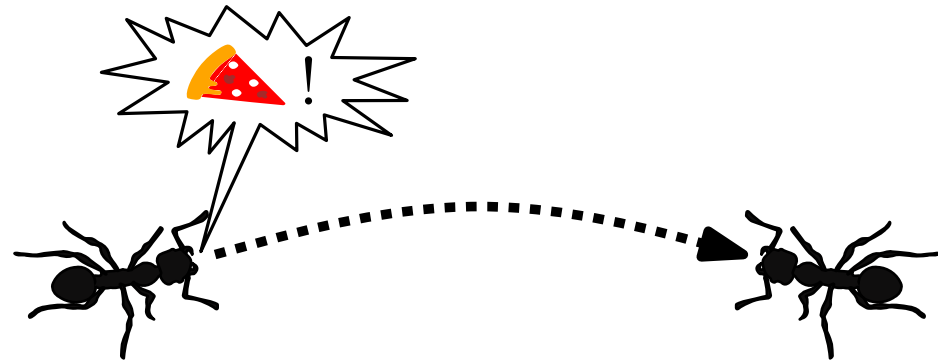
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Noisy Communication.

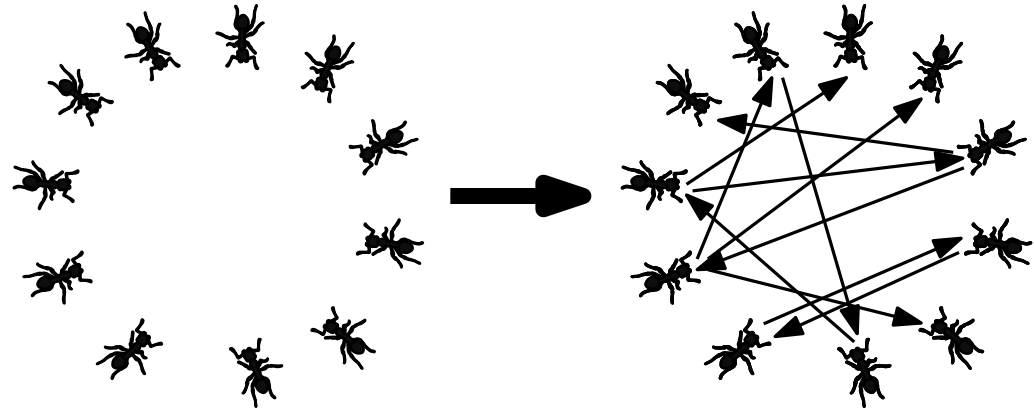
Before being received, each bit is **flipped** with probability $1/2 - \epsilon_n$.



Noisy & Stochastic Interactions

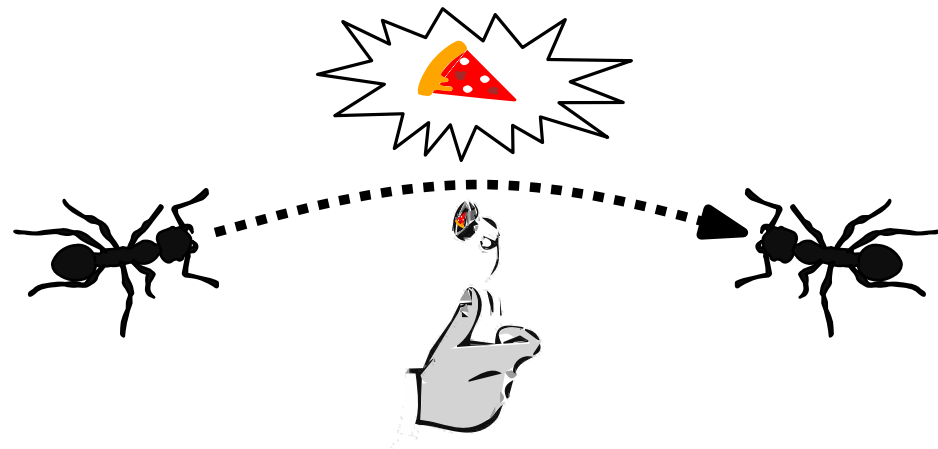
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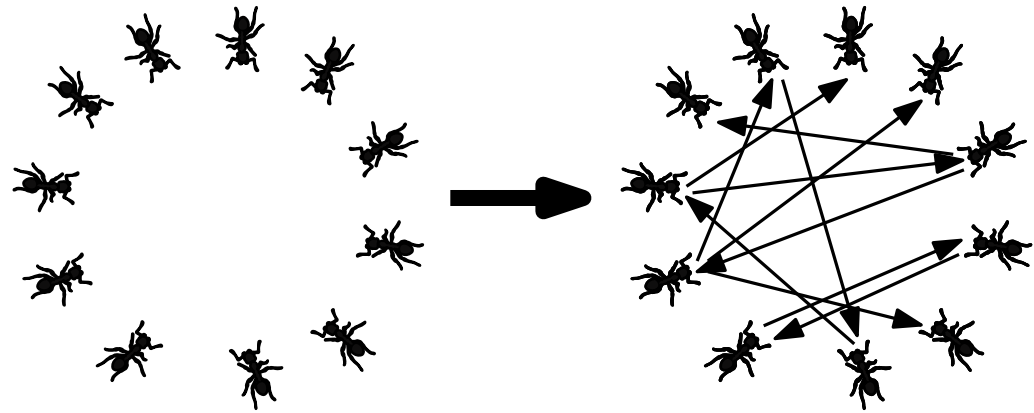
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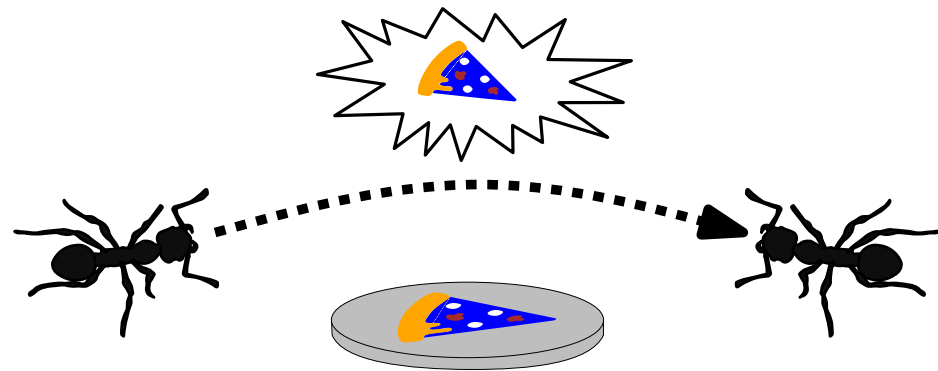
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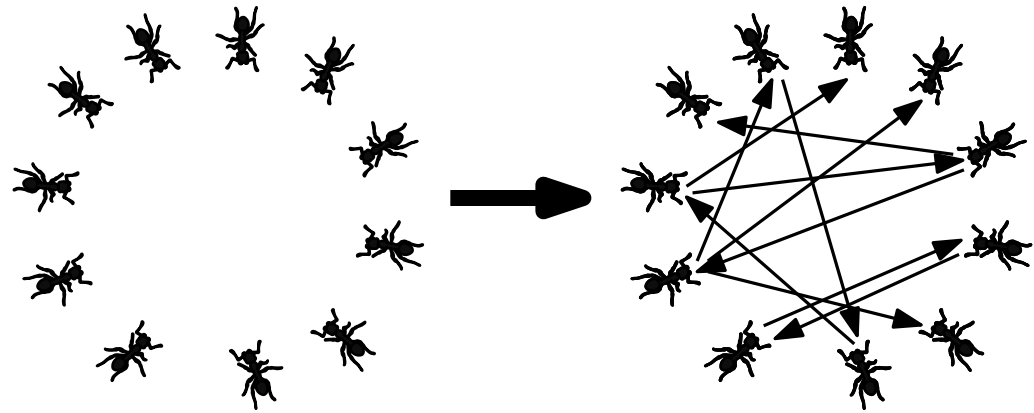
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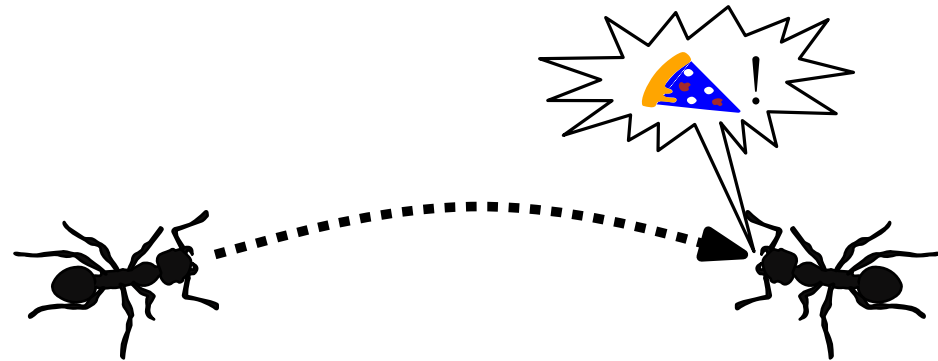
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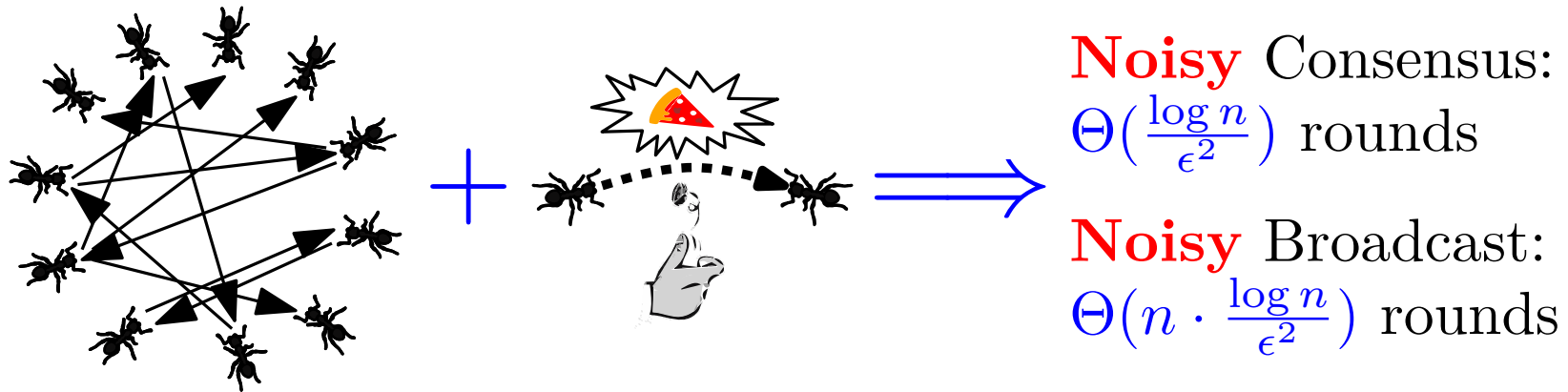


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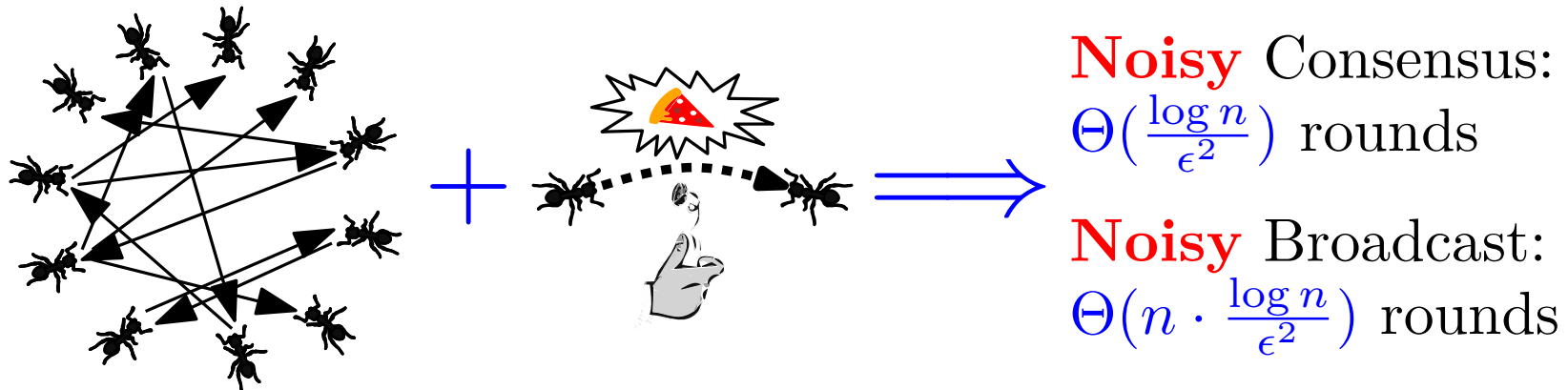


Lower Bounds and Reductions



Noisy Broadcast is *exponentially harder*
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Lower Bounds and Reductions



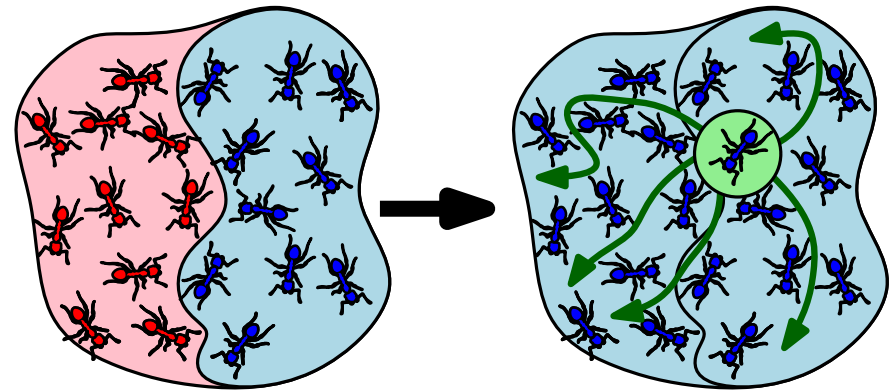
Noisy Broadcast is *exponentially harder*
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Broadcast \Rightarrow Consensus

Noiseless Consensus

\Rightarrow **Noiseless**

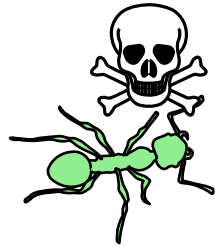
(variant of) Broadcast



Noiseless Consensus and Broadcast are “*equivalent*”

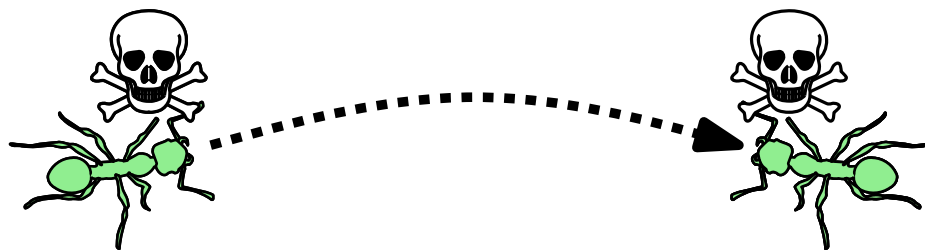
Consensus \Rightarrow “Broadcast”

Def. Given agent s , we call an agent infected if it is s or it receives any message from an infected agent. Protocol \mathcal{P} is δ -infective w.r.t. s if *infects* all but a fraction δ of agents.



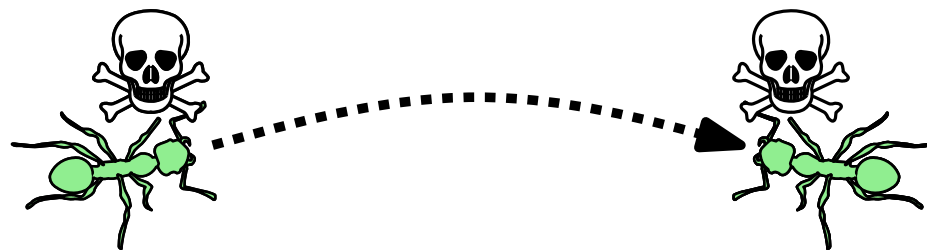
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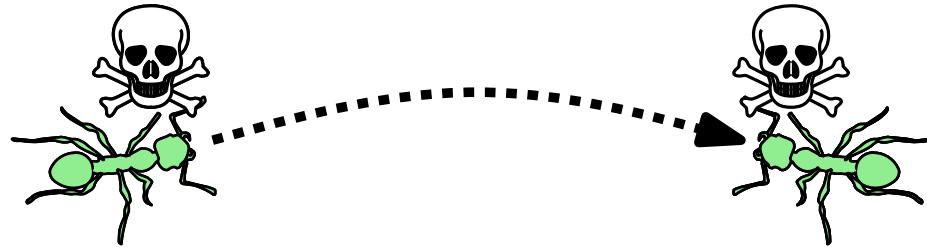
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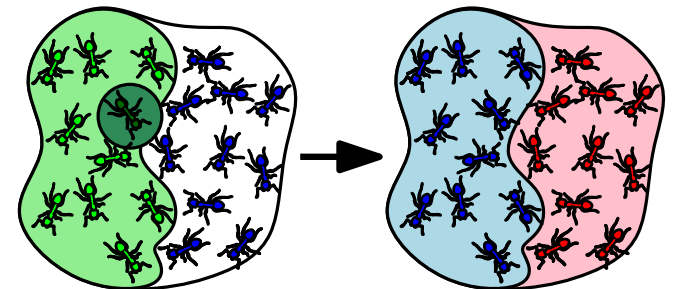
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Corollary. Let \mathcal{T} be a resource of the distributed system S . If no protocol can infect more than $(1 - 2\delta)$ fraction of agents with high probability, w.r.t. any source, without exceeding t_b units of \mathcal{T} , then any δ -consensus protocol with high probability must exceed t_b .



Proof in 9 Steps

1. Label nodes v_1, \dots, v_n . x_k is initial configuration with v_1, \dots, v_k having input 0, while others have input 1.

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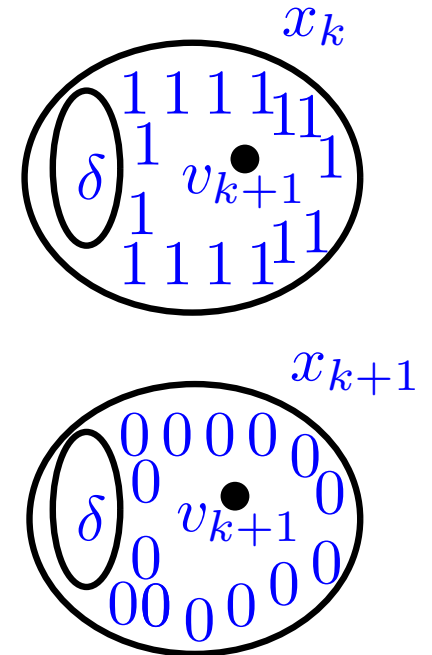
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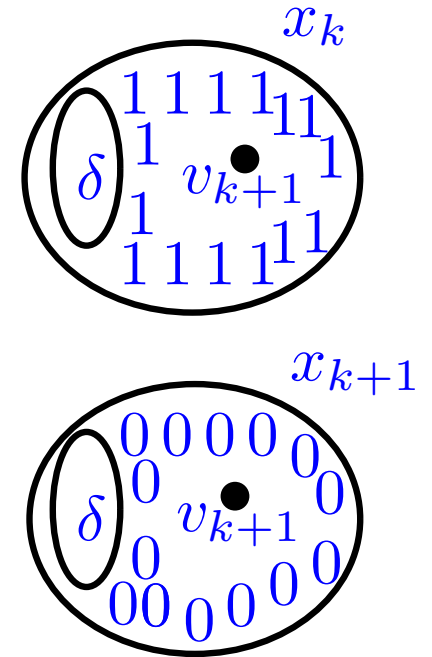
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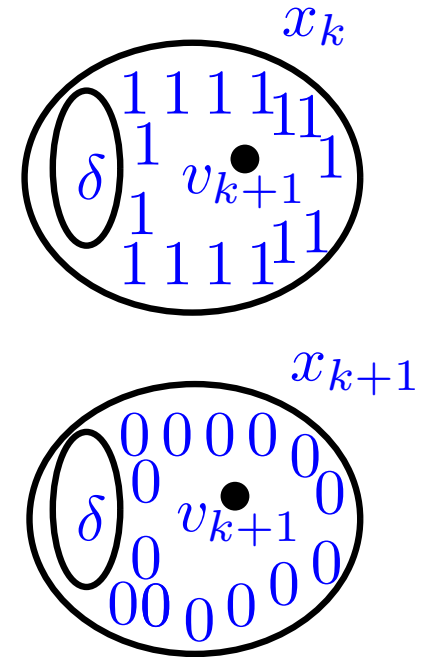
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9. $\leq P(\neg \mathcal{S} \vee |I_{k+1}| > (1 - 2\delta)n) \leq o(1/n) + P(|I_{k+1}| > (1 - 2\delta)n) \quad \square$



Thank
you