

What can be Computed in a Simple Chaotic Way?

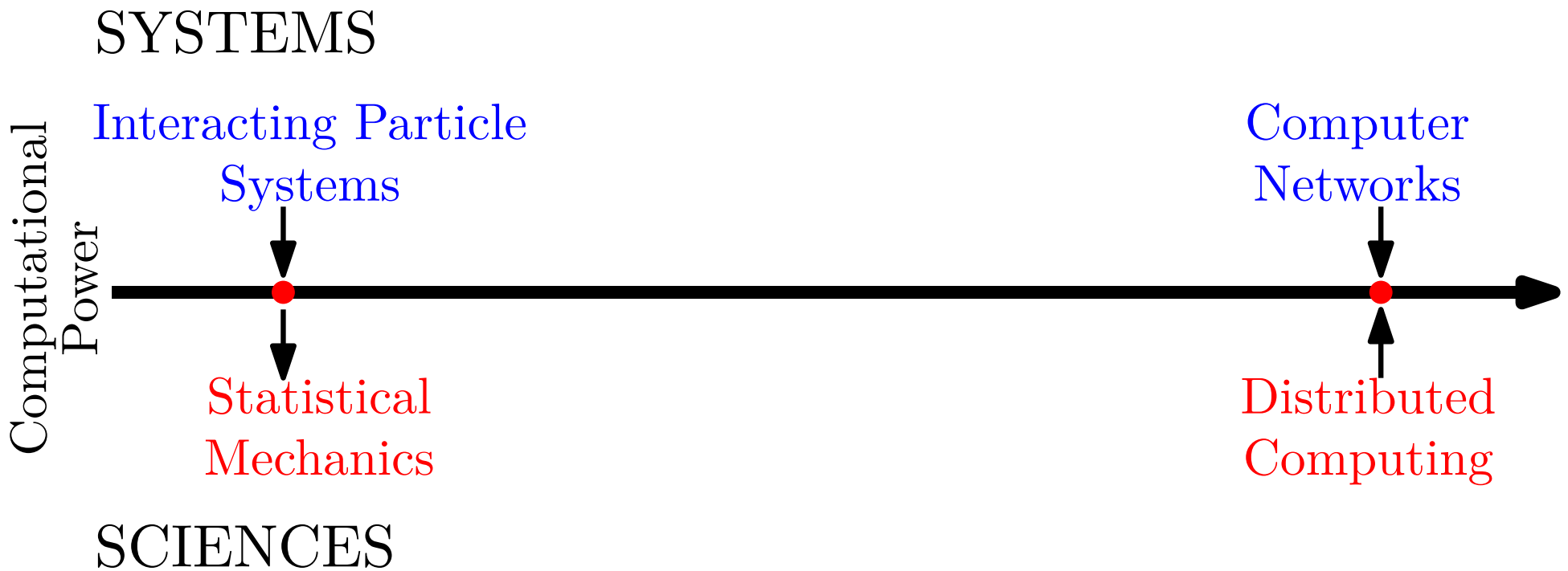
Emanuele Natale



Adfocs
2017

ADFOCS 25 August 2017,
MPII, Saarbrücken

What can *Simple* Systems do?



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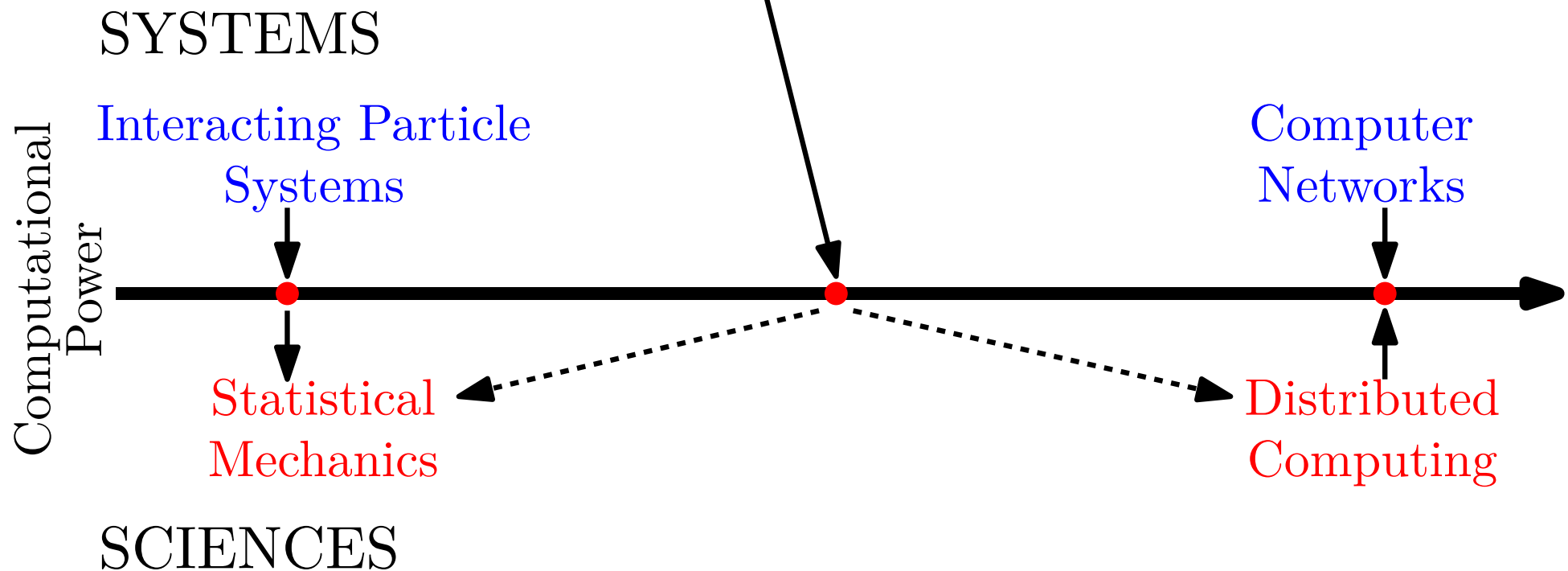


Schools of fish
[SKJCW'08]



Flocks of birds
[BDDS'14]

Biological Systems



Dynamics

(informal) *Very simple* distributed algorithms:
For every graph, agent and round, states are updated according to fixed (random) rule of current state and symmetric function of states of neighbors.

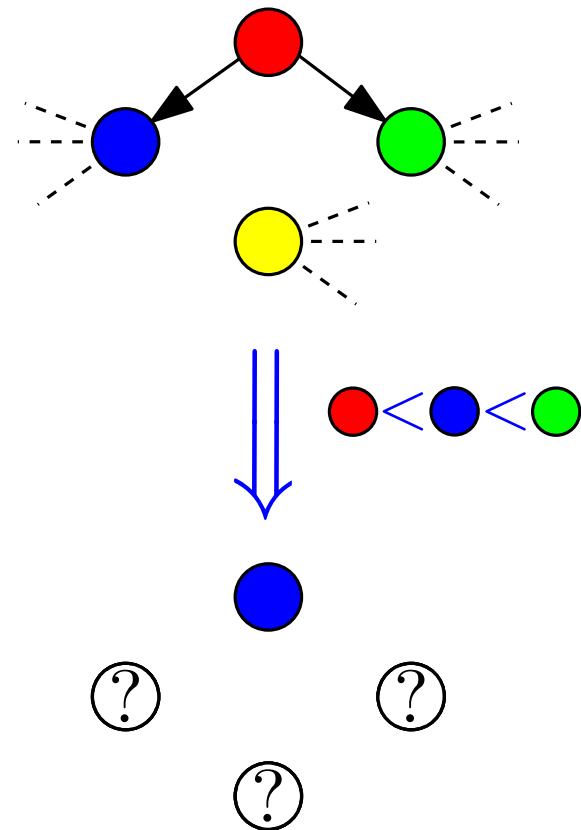
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Examples of Dynamics

- 3-Median dynamics



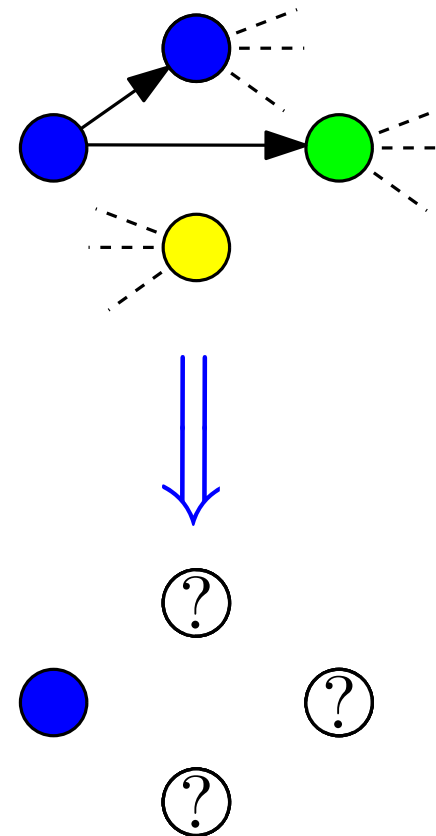
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- 3-Median dynamics
- 2-Choice dynamics



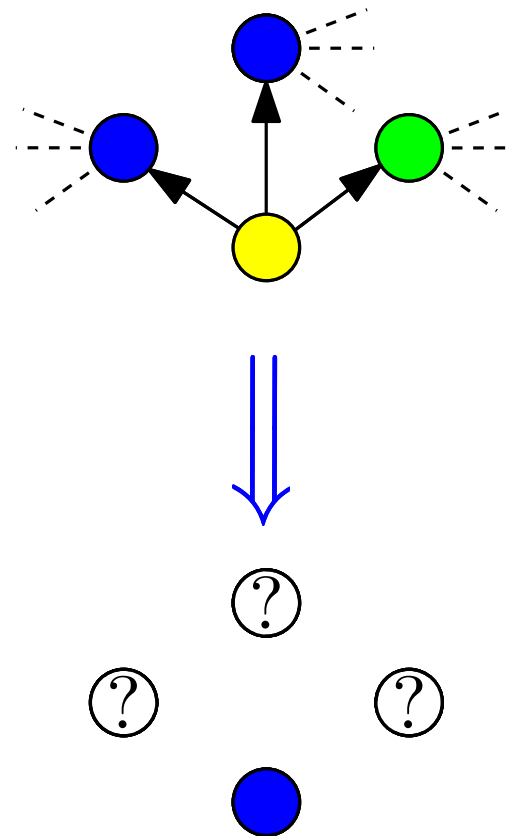
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- 2-Choice dynamics
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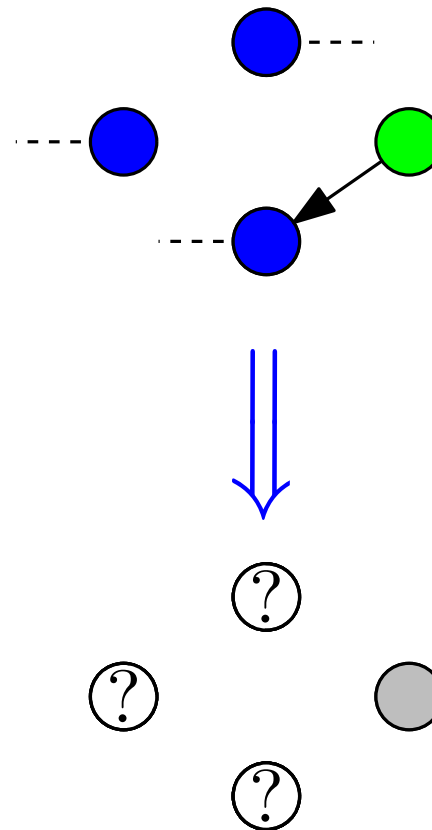
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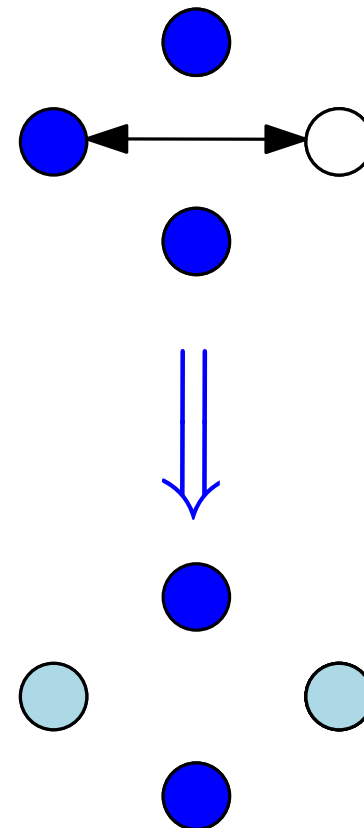
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Examples of Dynamics

- 3-Median dynamics
- 2-Choice dynamics
- 3-Majority dynamics
- Undecided-state dynamics
- Averaging dynamics

(asynchronous)



Some Results on Dynamics

On the **complete graph**:

3-Median dynamics [DGMSS '11]. Converge to $\mathcal{O}(\sqrt{n \log n})$ approximation of **median** of system in $\mathcal{O}(\log n)$ rounds w.h.p.

3-Majority dynamics [BCNPS '14, BCNPT '16, BCEKMN '17]. If **plurality** has **bias** $\mathcal{O}(\sqrt{kn \log n})$, converges to it in $\mathcal{O}(k \log n)$ rounds w.h.p., even against $o(\sqrt{n/k})$ -bounded adversary.

Without bias, converges in $\text{poly}(k)$. When k is large, polynomial separation w.r.t. **2-Choice**.

Undecided-State dynamics [BCNPST '15]. If majority/second-majority is at least $1 + \epsilon$, system converges to **plurality** within $\tilde{\Theta}(\sum_i (\frac{\#\{\text{majority nodes}\}}{\#\{i\text{-colored nodes}\}})^2)$ rounds w.h.p.,

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Dynamics can solve Consensus, Median, Majority, in a robust way, but this is trivial in centralized setting.. **Can they solve a problem non-trivial in centralized setting?**

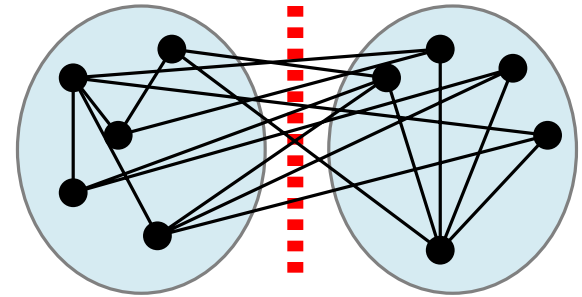
Community Detection

Min. Bisection Problem.

Given a graph G with $2n$ nodes. Find

$$S = \arg \min_{\substack{S \subset V \\ |S|=n}} E(S, V - S).$$

[GJS '76]: **Min. Bisection** is *NP-Complete*.



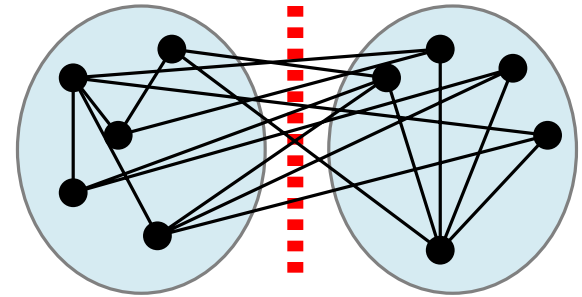
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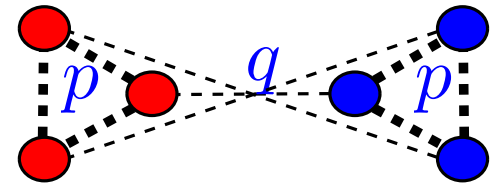
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Stochastic Block Model. Two “communities” of equal size V_1 and V_2 , each edge inside a community included with probability p , each edge across communities included with probability $q < p$.



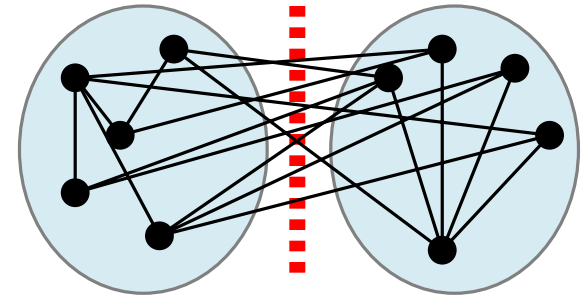
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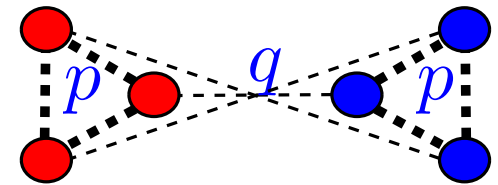
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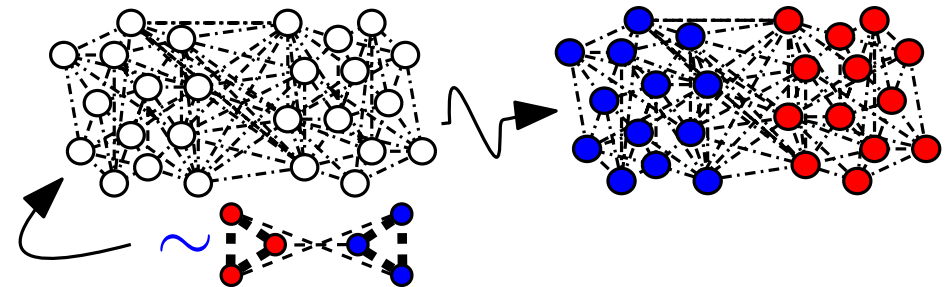
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Reconstruction problem. Given graph generated by SBM, find original partition.



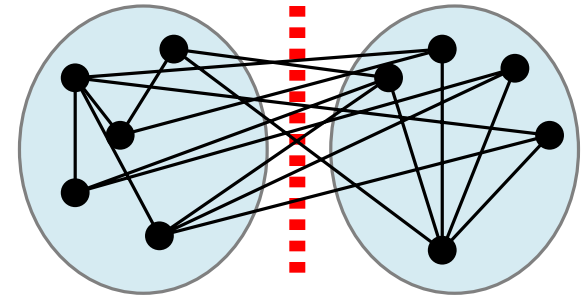
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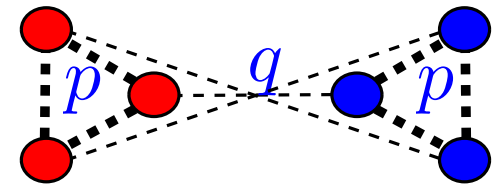
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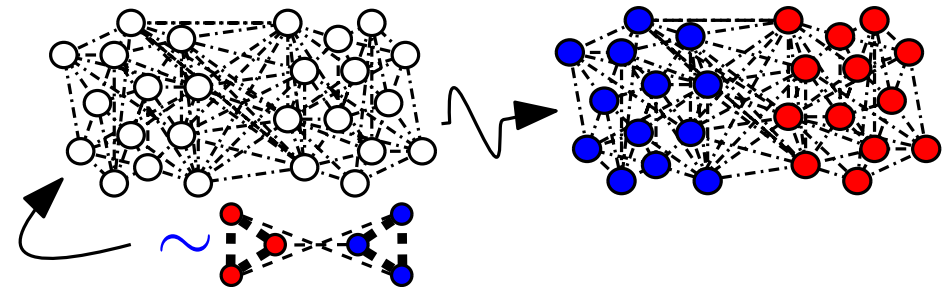
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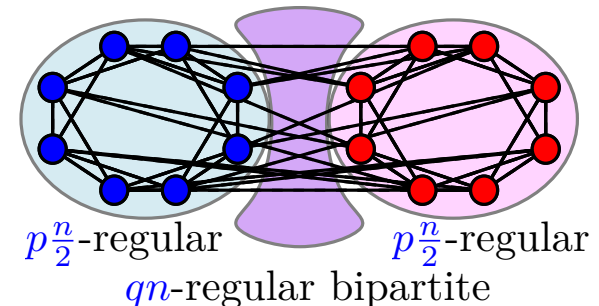
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Regular SBM [BDGHT '15]. Graph induced by communities are $p\frac{n}{2}$ -regular random, graph induced by cut is qn -regular random.

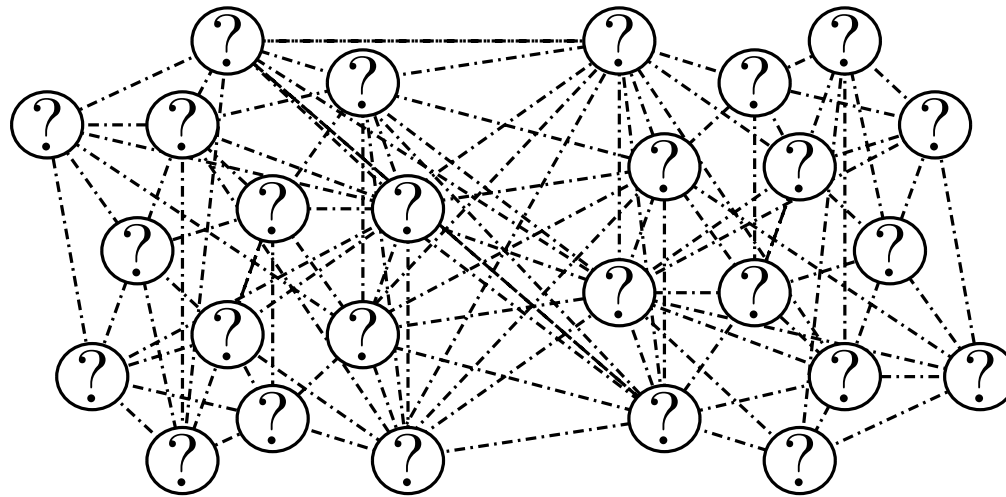


The Averaging Dynamics

Asynchronous Averaging Protocol:

At each round a random edge is chosen.

- At the **first activation**, each node picks at random $+1$ or -1 .
- (**Dynamics**) At each activation, the nodes **averages** their values.

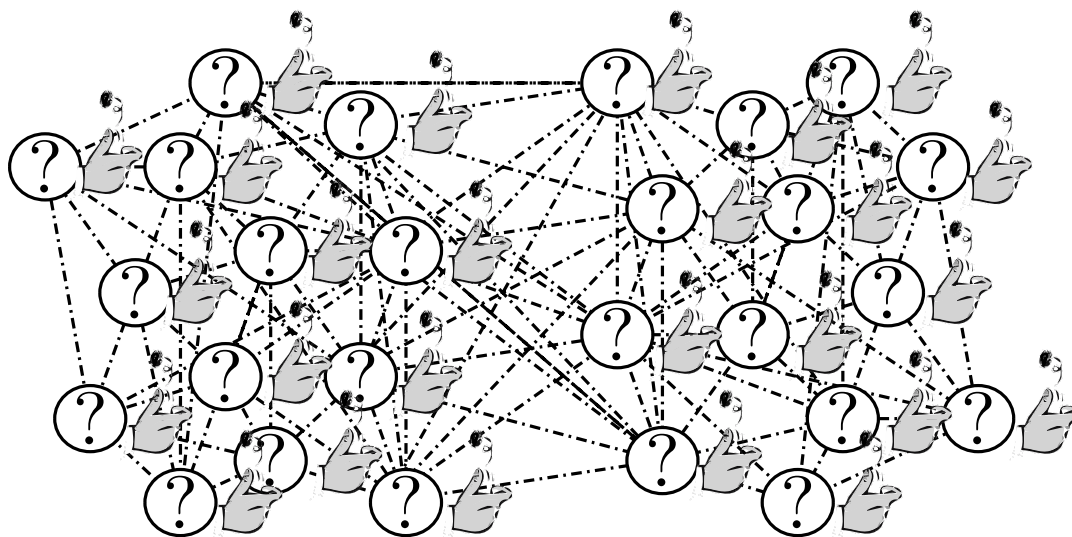


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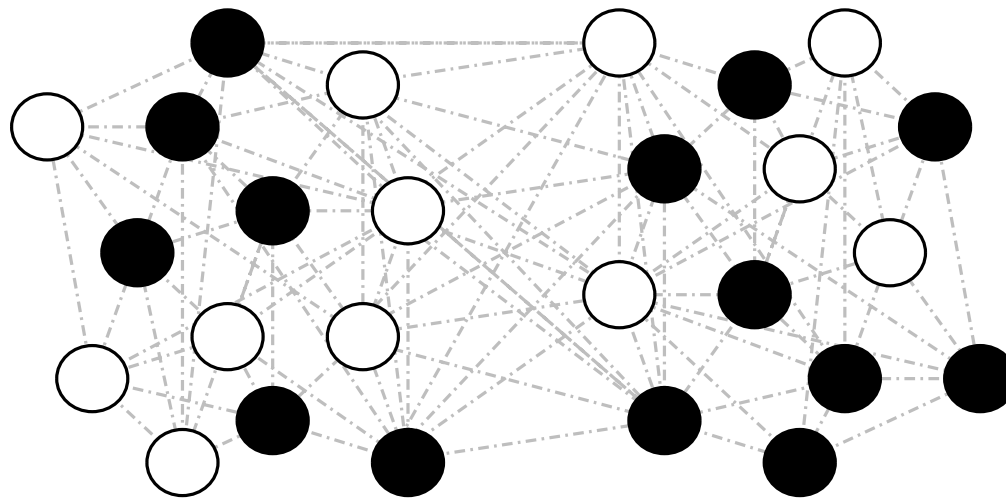


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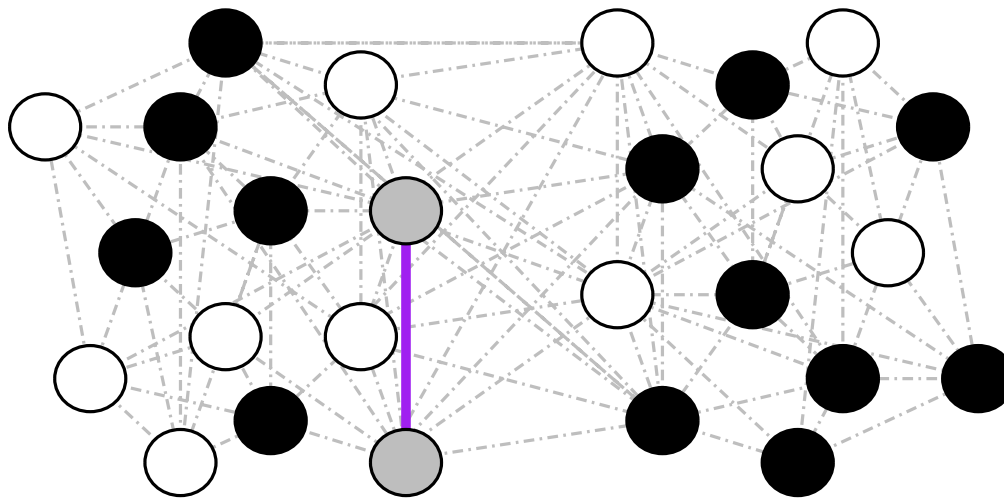


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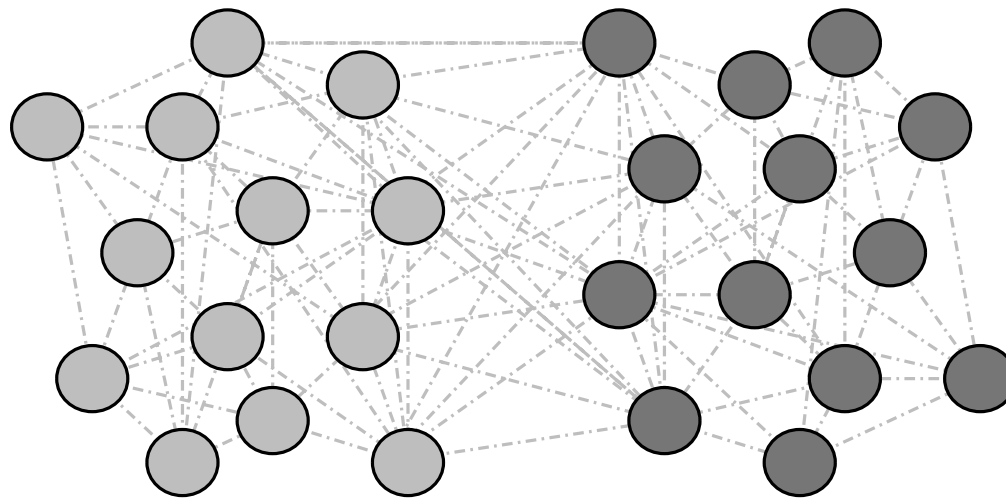


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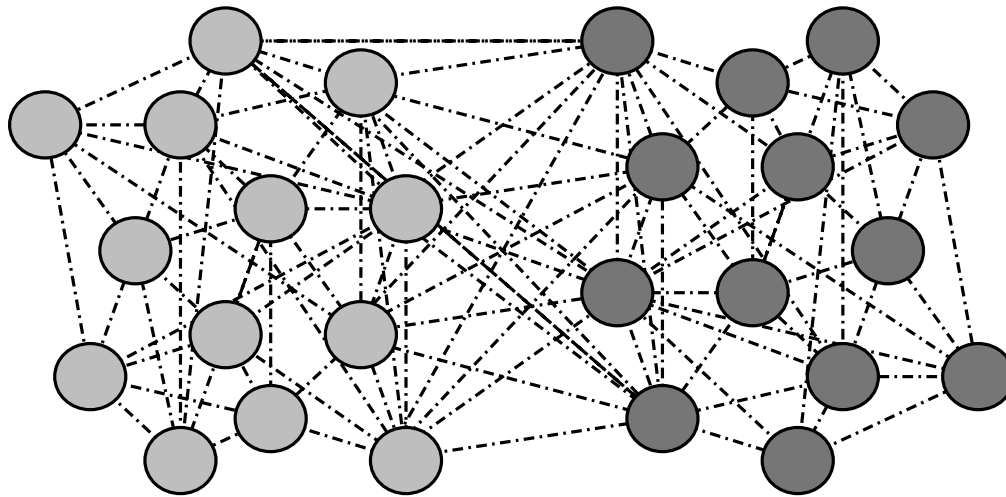


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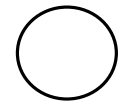
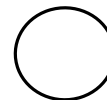
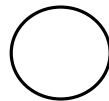
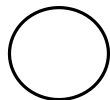
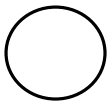
Theorem (Corollary of [BCMNPRT'17(Soon on Arxiv)]).

There exist τ_1, τ_2 s.t., if each node **labels** itself with the **sign of the difference of its value at two activation times τ_1 and τ_2** , then with prob. $1 - \epsilon$, after $O_\epsilon(n \log n + \frac{n}{\lambda_2})$ rounds, we get a correct reconstruction up to an ϵ -fraction of nodes.

“ \mathbb{E} [Averaging Dynamics]”

All nodes at the same time:

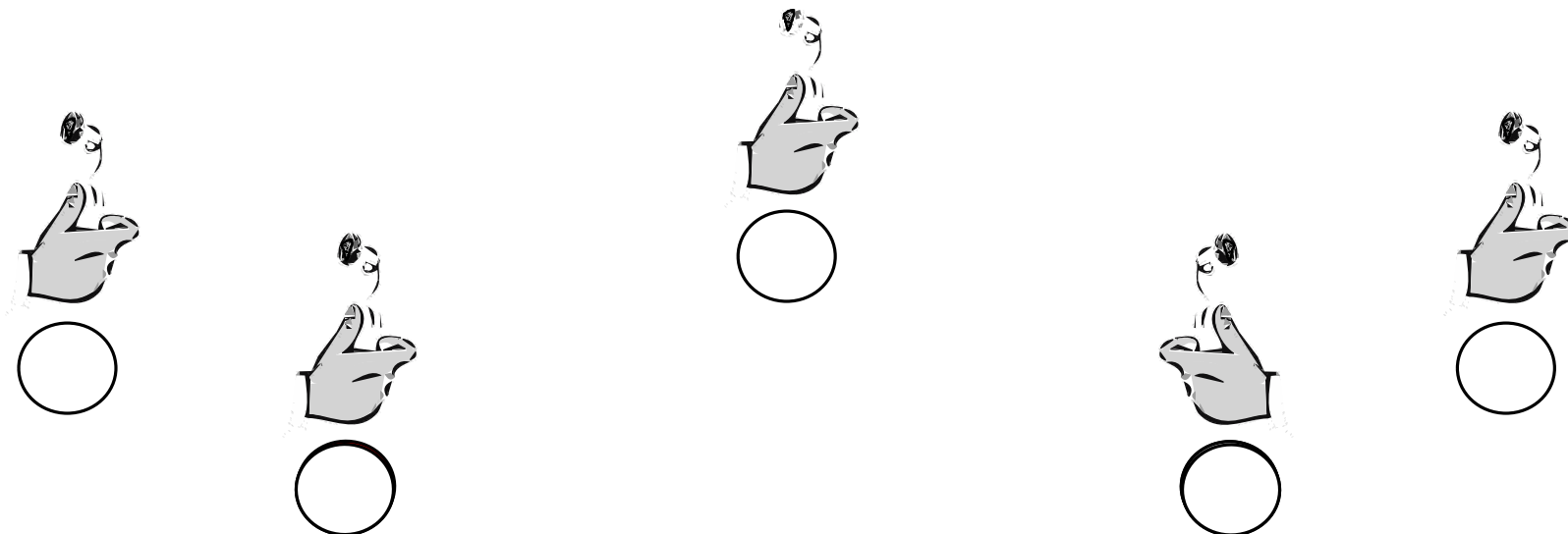
- At $t = 0$, randomly pick value $x^{(t)} \in \{+1, -1\}$.
- Then, at each round
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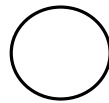
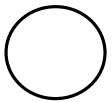
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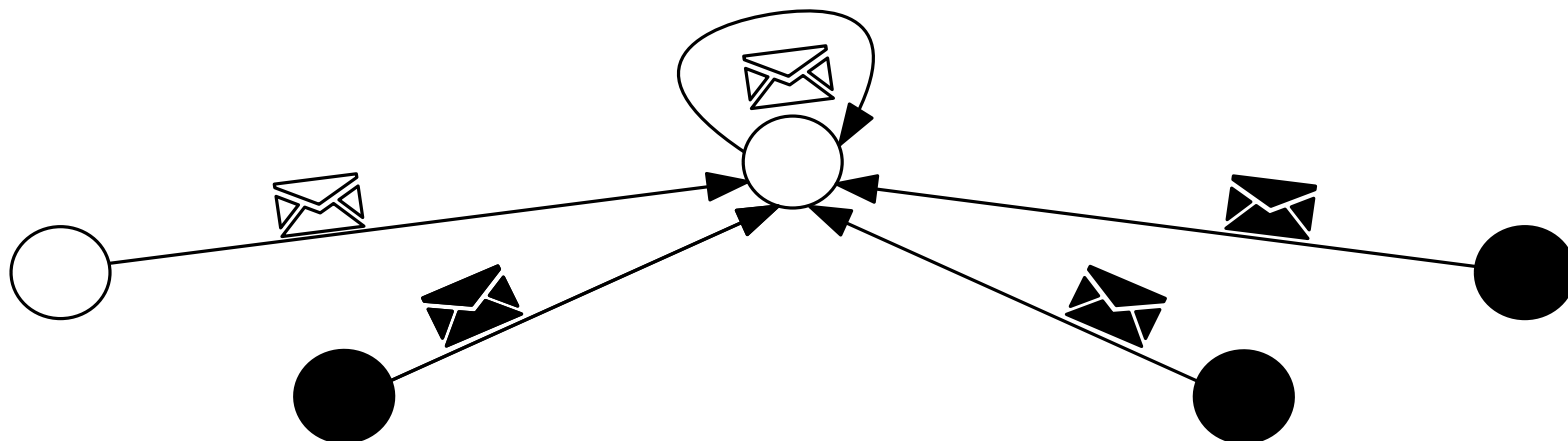
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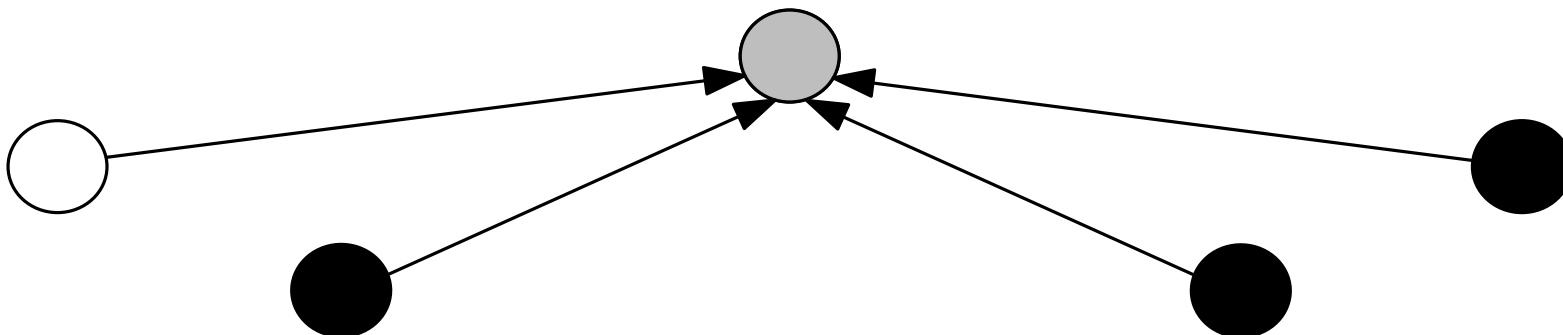


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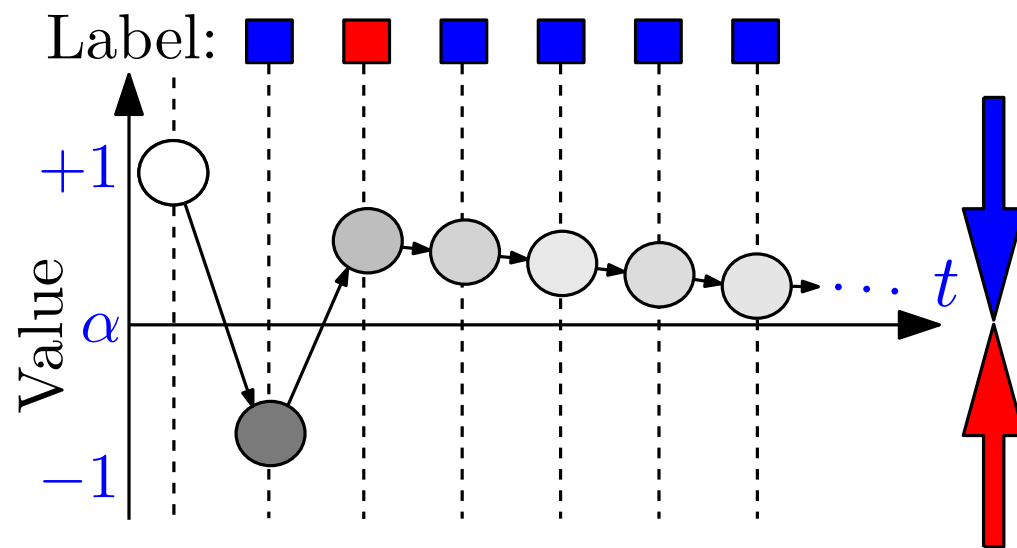
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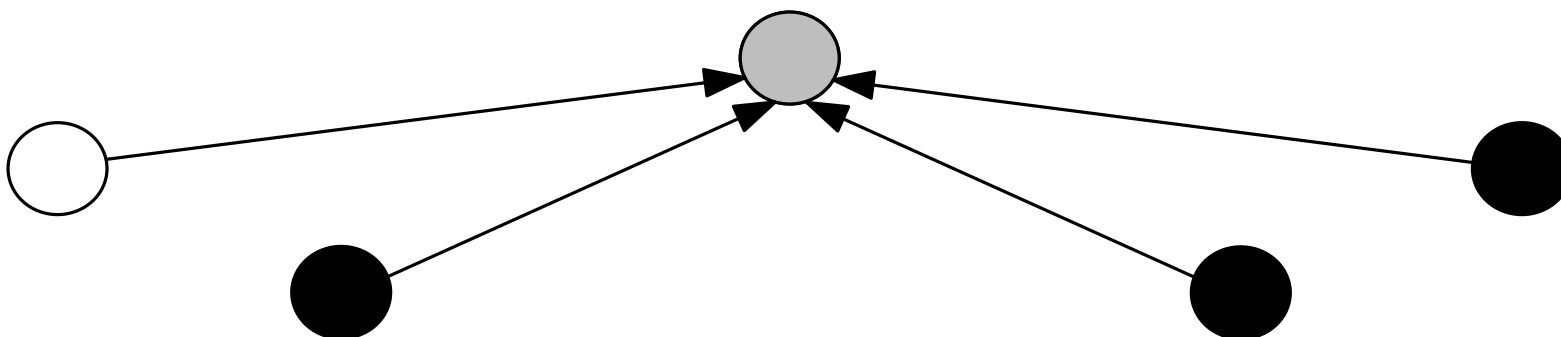
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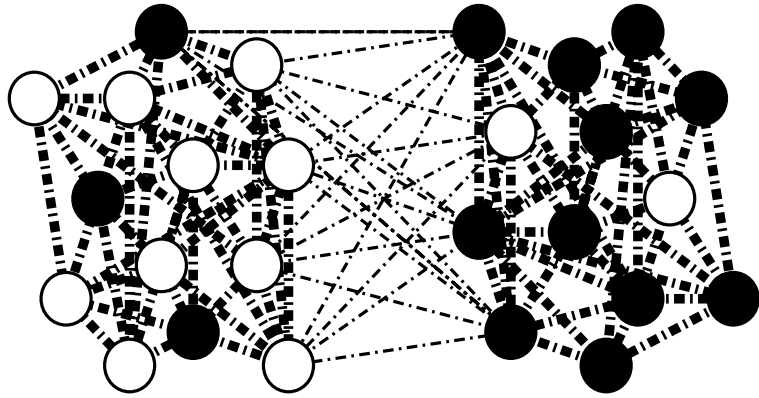
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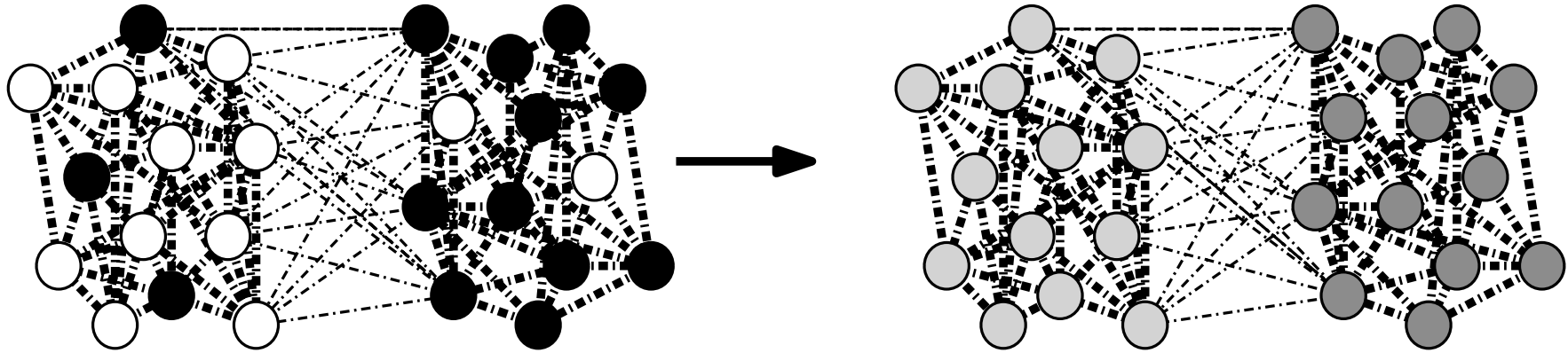
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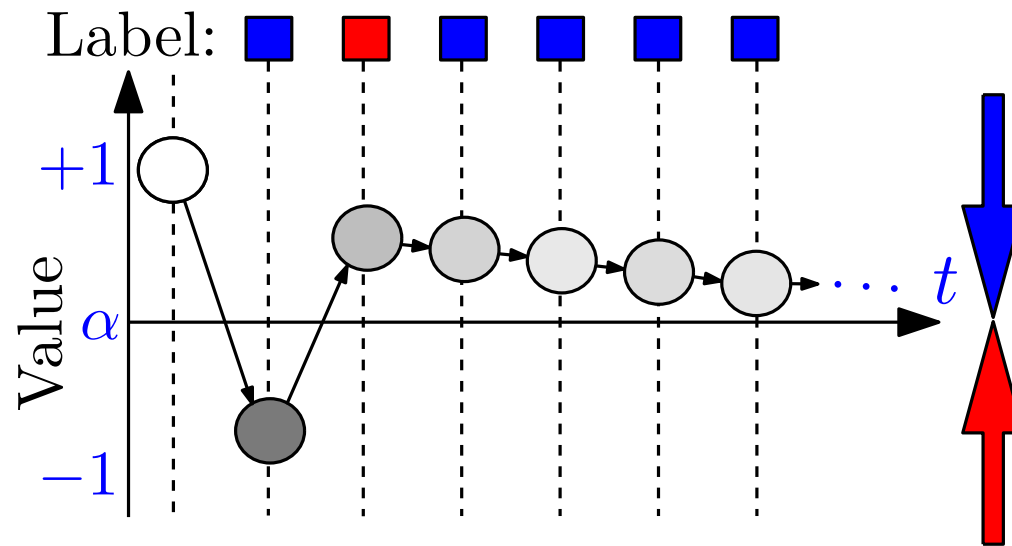
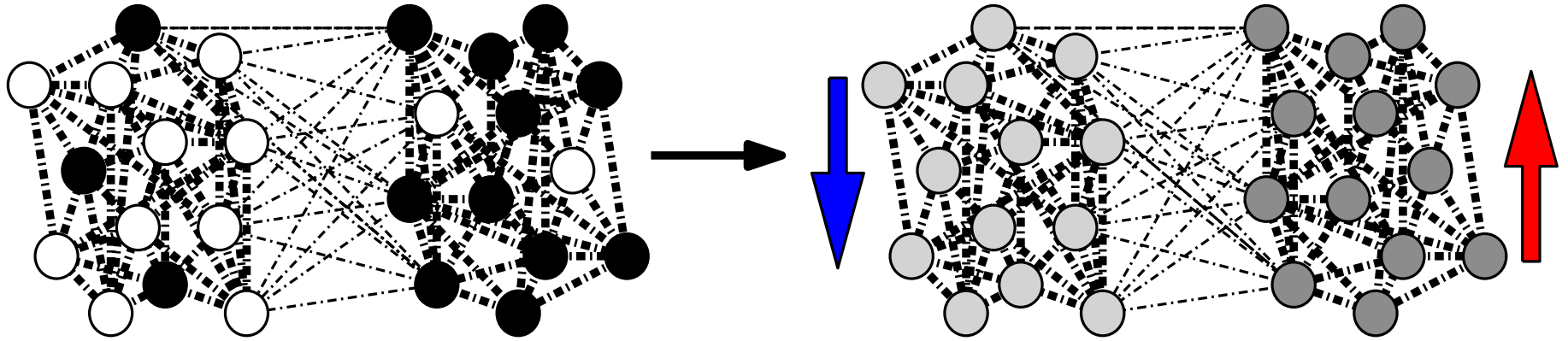
Community Detection via (Parallel) Averaging



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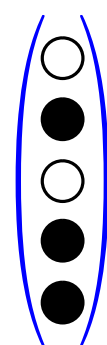
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Averaging
is a **linear** dynamics $\mathbf{x}^{(t)} =$ 

$$\mathbf{x}^{(t)} = P \cdot \mathbf{x}^{(t-1)} = P^t \cdot \mathbf{x}^{(0)}$$

P transition matrix
of lazy random walk

Analysis on Regular SBM

$$a = p \frac{n-1}{2}, b = qn \quad \chi = (1, \dots, 1, -1, \dots, -1)$$


P symmetric \implies orthonormal eigenvectors $\mathbf{v}_1, \dots, \mathbf{v}_n$ and real eigenvalues $\lambda_1, \dots, \lambda_n$.

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$$\text{Regular SBM} \implies P \frac{1}{\sqrt{n}} \chi = \left(\frac{a-b}{a+b} \right) \cdot \frac{1}{\sqrt{n}} \chi$$

$$\frac{1}{a+b} \begin{pmatrix} \dots\dots\dots & \dots\dots\dots \\ \dots a \text{ "1"s" } \dots & \dots b \text{ "1"s" } \dots \\ \dots\dots\dots & \dots\dots\dots \\ \dots\dots\dots & \dots\dots\dots \\ \dots b \text{ "1"s" } \dots & \dots a \text{ "1"s" } \dots \\ \dots\dots\dots & \dots\dots\dots \end{pmatrix} \cdot \begin{pmatrix} 1 \\ \vdots \\ 1 \\ -1 \\ \vdots \\ -1 \end{pmatrix} = \frac{a-b}{a+b} \begin{pmatrix} 1 \\ \vdots \\ 1 \\ -1 \\ \vdots \\ -1 \end{pmatrix}$$

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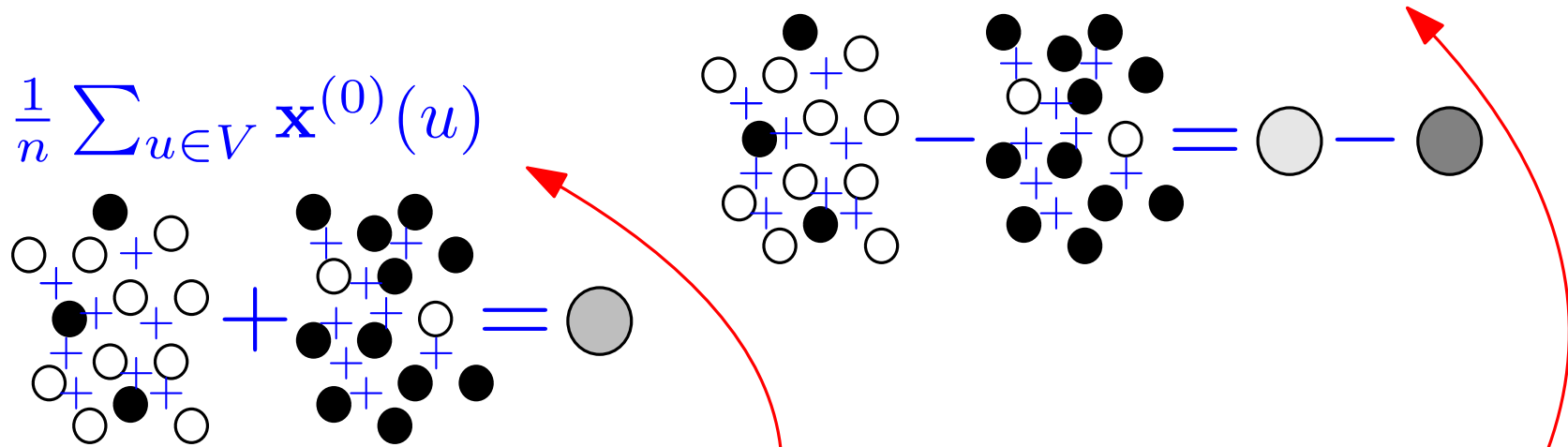
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with $\|\mathbf{e}^{(t)}\| \leq \lambda_3^t \sqrt{n}$

Analysis on Regular SBM

$$\frac{1}{n} \sum_{u \in V_1} \mathbf{x}^{(0)}(u) - \frac{1}{n} \sum_{u \in V_2} \mathbf{x}^{(0)}(u)$$



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with $\|\mathbf{e}^{(t)}\| \leq \lambda_3^t \sqrt{n}$

Analysis on Regular SBM

$$\mathbf{x}^{(t)} = \frac{1}{n}(\mathbf{1}^\top \mathbf{x}^{(0)})\mathbf{1} + \underbrace{\left(\frac{a-b}{a+b}\right)^t}_{=\lambda_2} \frac{1}{n}(\chi^\top \mathbf{x}^{(0)})\chi + \mathbf{e}^{(t)}$$

Analysis on Regular SBM

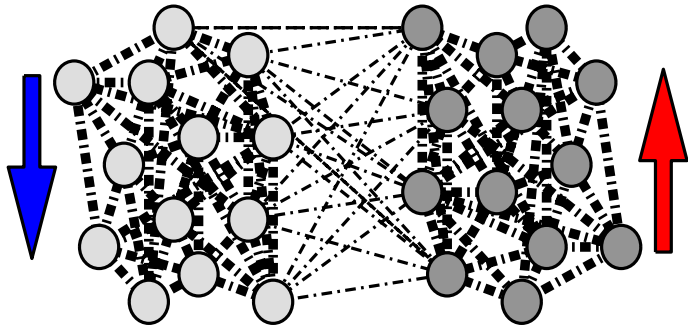
$$\mathbf{x}^{(t)} = \frac{1}{n}(\mathbf{1}^\top \mathbf{x}^{(0)})\mathbf{1} + \underbrace{\left(\frac{a-b}{a+b}\right)^t}_{=\lambda_2} \frac{1}{n}(\chi^\top \mathbf{x}^{(0)})\chi + \mathbf{e}^{(t)}$$

$$\mathbf{x}^{(t)} - \mathbf{x}^{(t-1)} = (\chi^\top \mathbf{x}^{(0)})\lambda_2^{t-1}(\lambda_2 - 1)\chi + \underbrace{\mathbf{e}^{(t)} - \mathbf{e}^{(t-1)}}_{o(\lambda_2^t) \text{ if } t=\Omega(\log n)}$$

Analysis on Regular SBM

$$\mathbf{x}^{(t)} = \frac{1}{n}(\mathbf{1}^\top \mathbf{x}^{(0)})\mathbf{1} + \underbrace{\left(\frac{a-b}{a+b}\right)^t}_{=\lambda_2} \frac{1}{n}(\chi^\top \mathbf{x}^{(0)})\chi + \mathbf{e}^{(t)}$$

$$\mathbf{x}^{(t)} - \mathbf{x}^{(t-1)} = (\chi^\top \mathbf{x}^{(0)})\lambda_2^{t-1}(\lambda_2 - 1)\chi + \underbrace{\mathbf{e}^{(t)} - \mathbf{e}^{(t-1)}}_{o(\lambda_2^t) \text{ if } t=\Omega(\log n)}$$

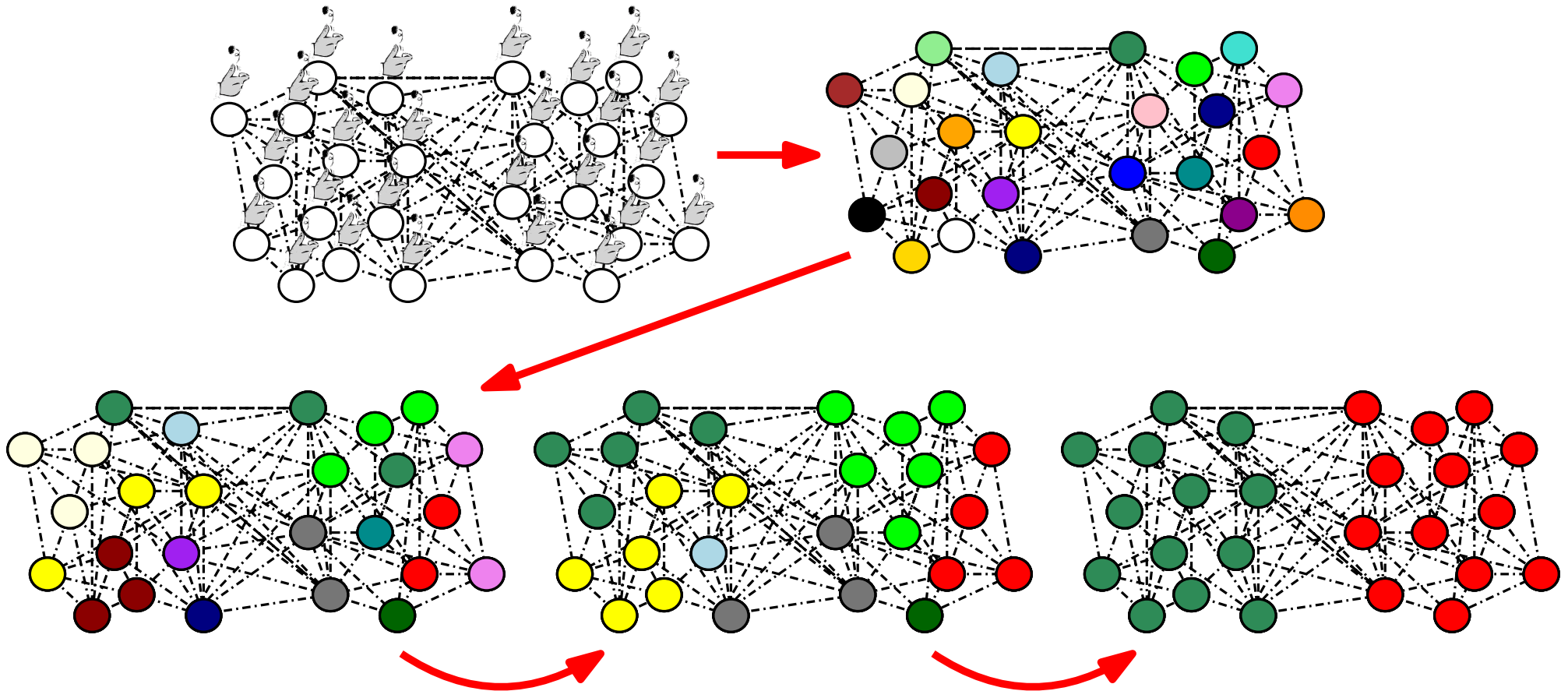


$$\text{sign}(\mathbf{x}^{(t)}(u) - \mathbf{x}^{(t-1)}(u)) \propto \text{sign}(\chi(u))$$

Open Problem: Analyzing LPAs

Averagins is a “linearization” of Label Propagation Algorithms:

- Each node initially sample a random color, then
- at each round, each node switch to the majority label of a sample of neighbors.



Thank you!