

Plurality Consensus in the Gossip Model

Emanuele Natale[†]

joint work with

L. Becchetti[†], A. Clementi*,
F. Pasquale* and R. Silvestri[†]



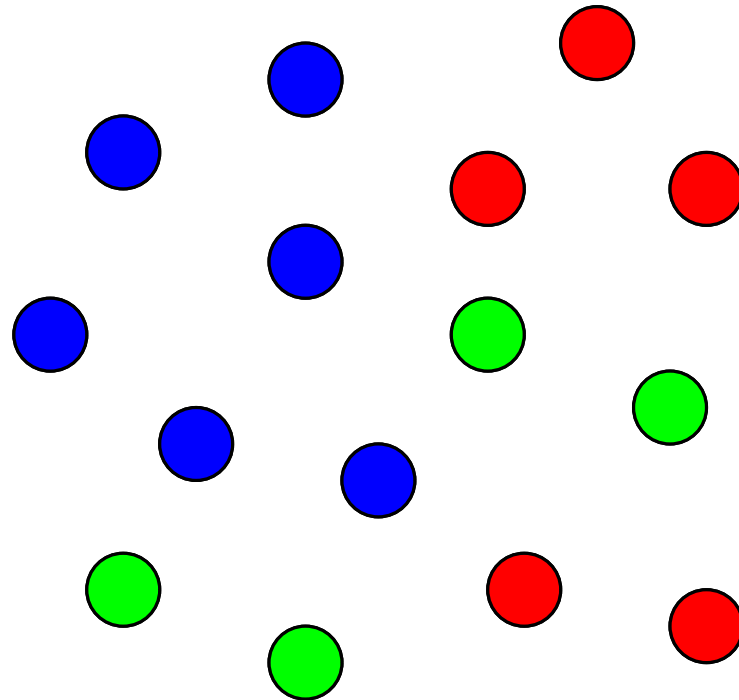
SAPIENZA
UNIVERSITÀ DI ROMA

Efficient Algorithms Group, CS Department, Salzburg University,
February 20th, 2015



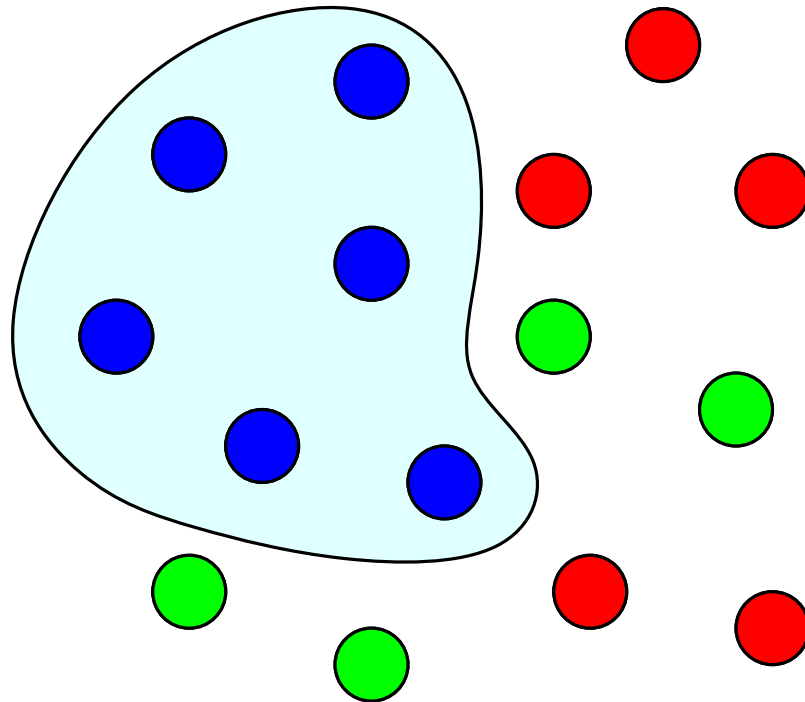
The Plurality Consensus Problem

We have a set of nodes each having one color out of $\{1, \dots, k\}$.



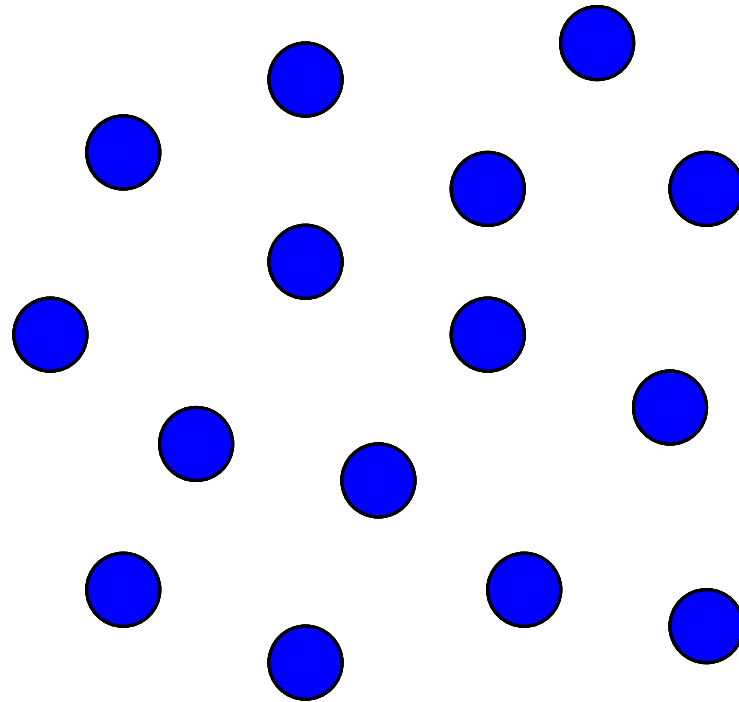
The Plurality Consensus Problem

There is a plurality of nodes having the same color.



The Plurality Consensus Problem

We want to reach consensus on the plurality color.



Motivations and Applications

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- **Chemestry:** chemical reaction networks/population protocols (Angluin et al. '07).

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Voter Model ('70). Each node with a Poisson clock. When rings, takes the opinion of a random neighbor.

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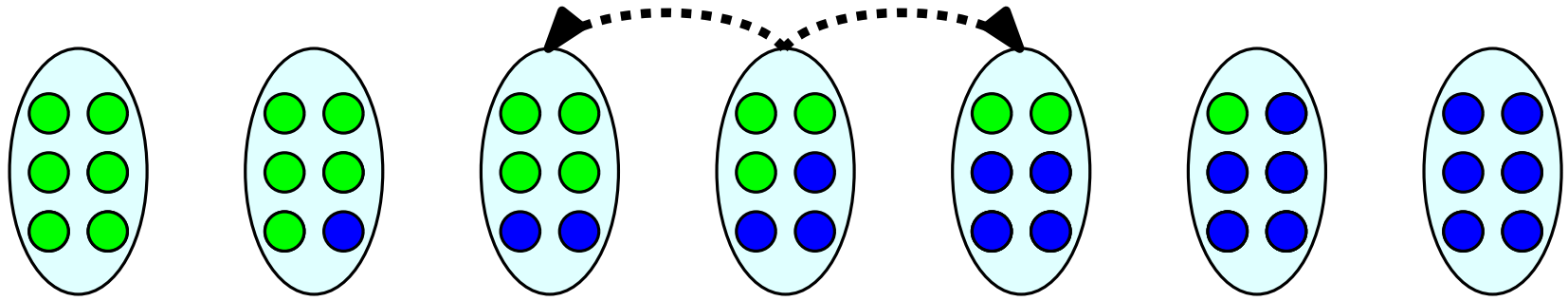
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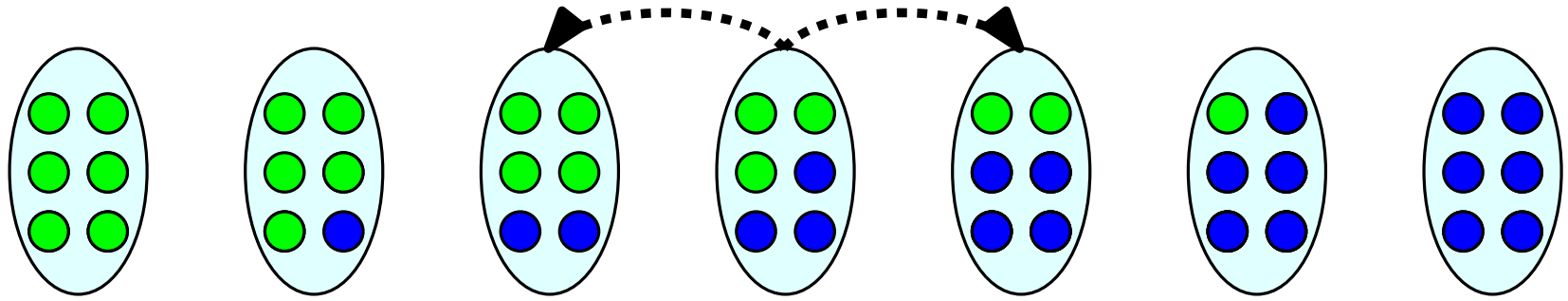
Discrete time (parallel/synchronous) process. Initiated the study of Plurality Consensus in Computer Science.

Asynchronous vs Synchronous

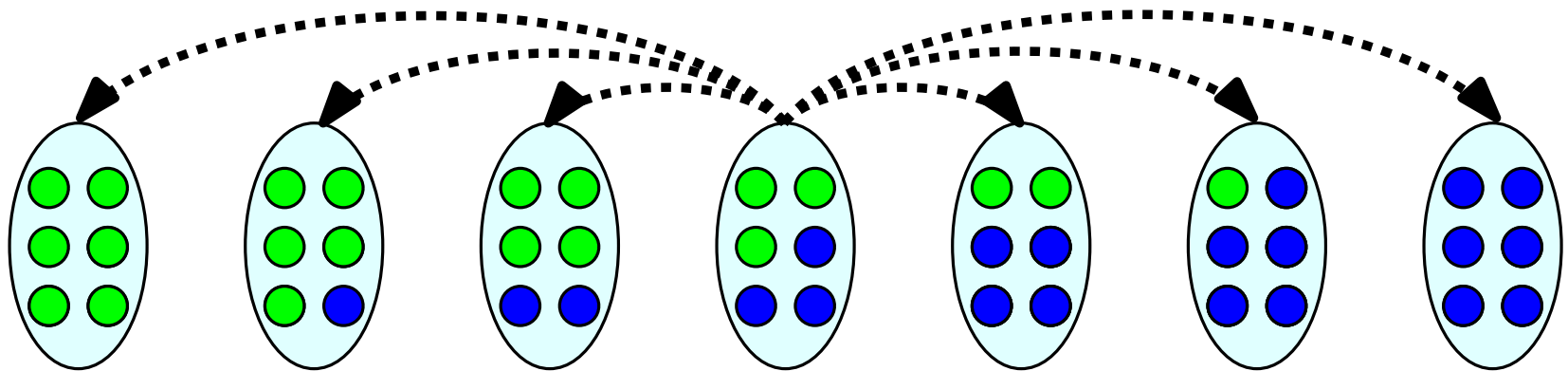


Asynchronous Case

Asynchronous vs Synchronous



Asynchronous Case



Synchronous Case

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- **Local memory and message size:** $O(\log n)$.

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Gossip model with neighbors chosen randomly:
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Censor-Hillel et al. (STOC '12):

Every task that can be solved in the *Local* model in T rounds, can be solved in $O(T + \text{polylog}n)$ rounds in the *Gossip* model.

But...

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But... using the preceding theorem, message size grows dramatically!

(Some) Related Works

	Mem. & mess. size	# of colors	Time efficiency	Comm. Model
Kempe <small>et al.</small> FOCS '03	$O(k \log n)$	any	$O(\log n)$	<i>GOSSIP</i>
Angluin <small>et al.</small> DISC '07 Perron <small>et al.</small> INFOCOM '09	$\Theta(1)$	2	$O(\log n)$	Sequential
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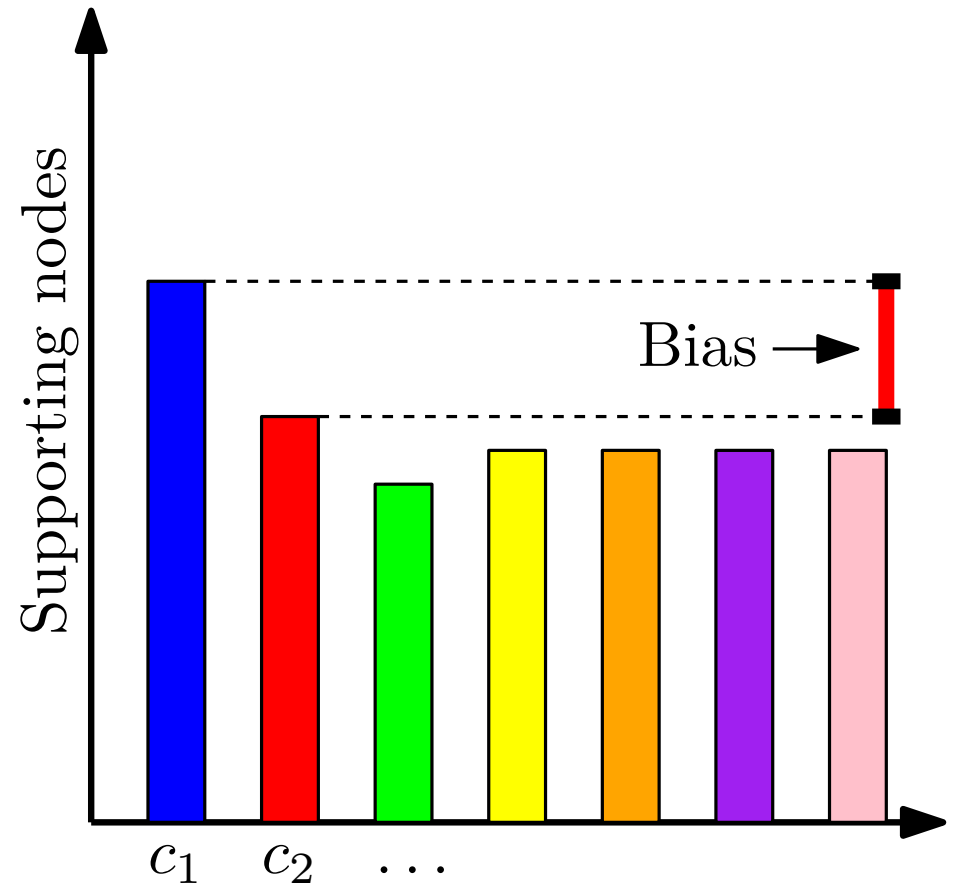
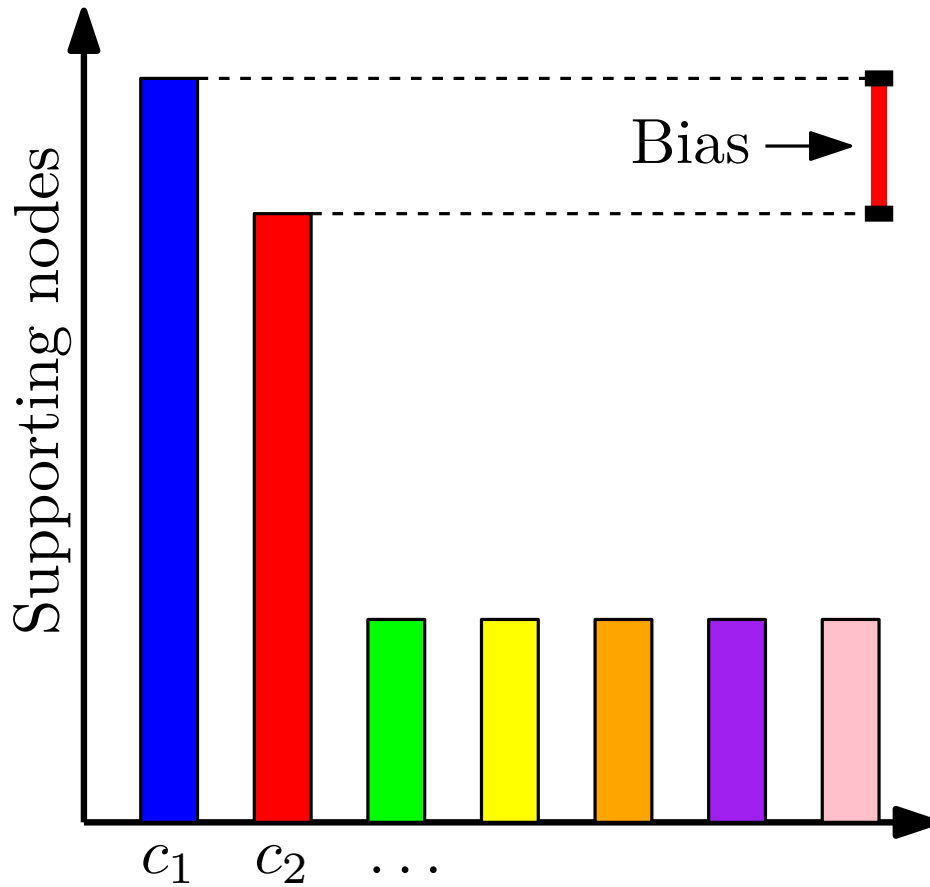
Characterizing the Initial Bias

$$c_i^{(t)} := |\{i\text{-colored nodes}\}| \quad \text{color 1 is the plurality}$$

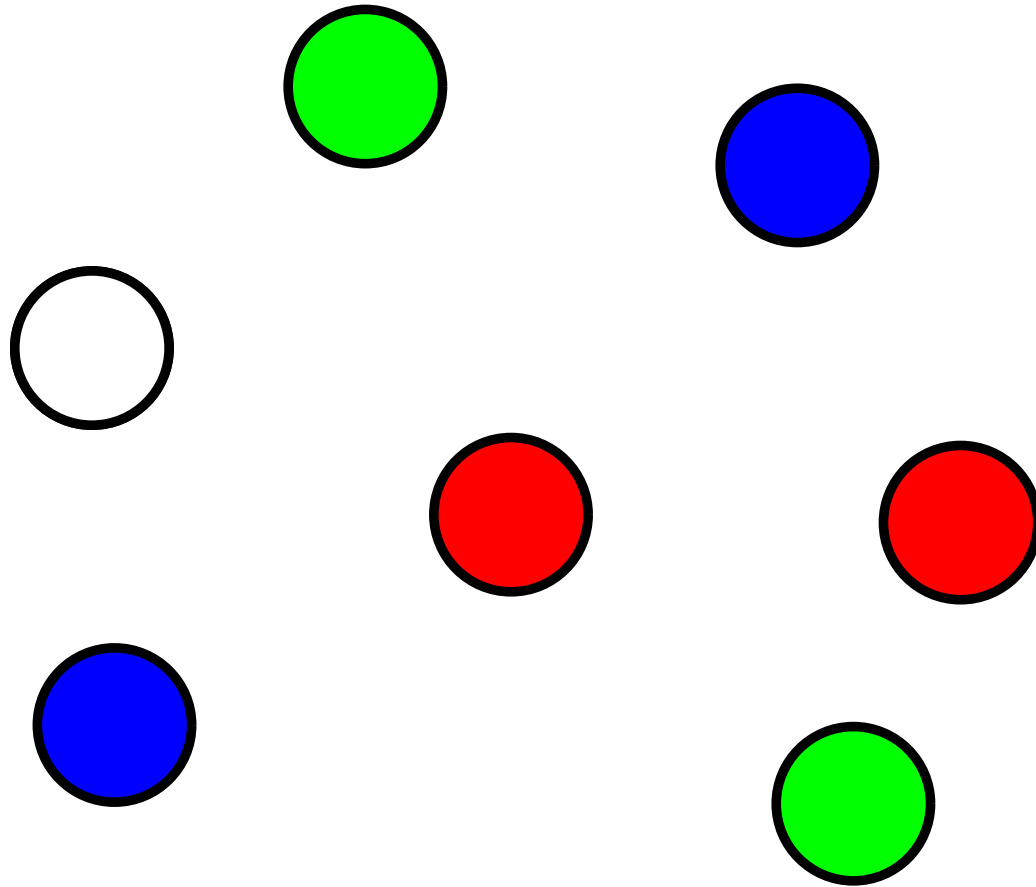
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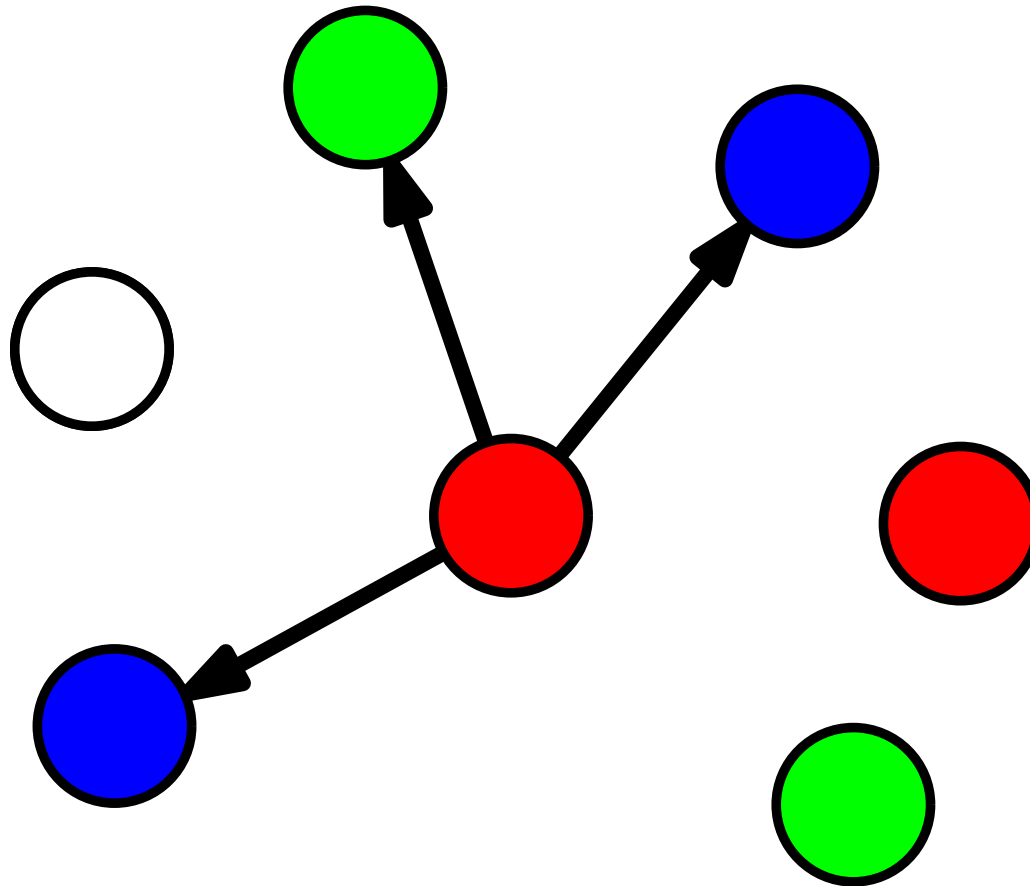
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The 3-Majority Dynamics

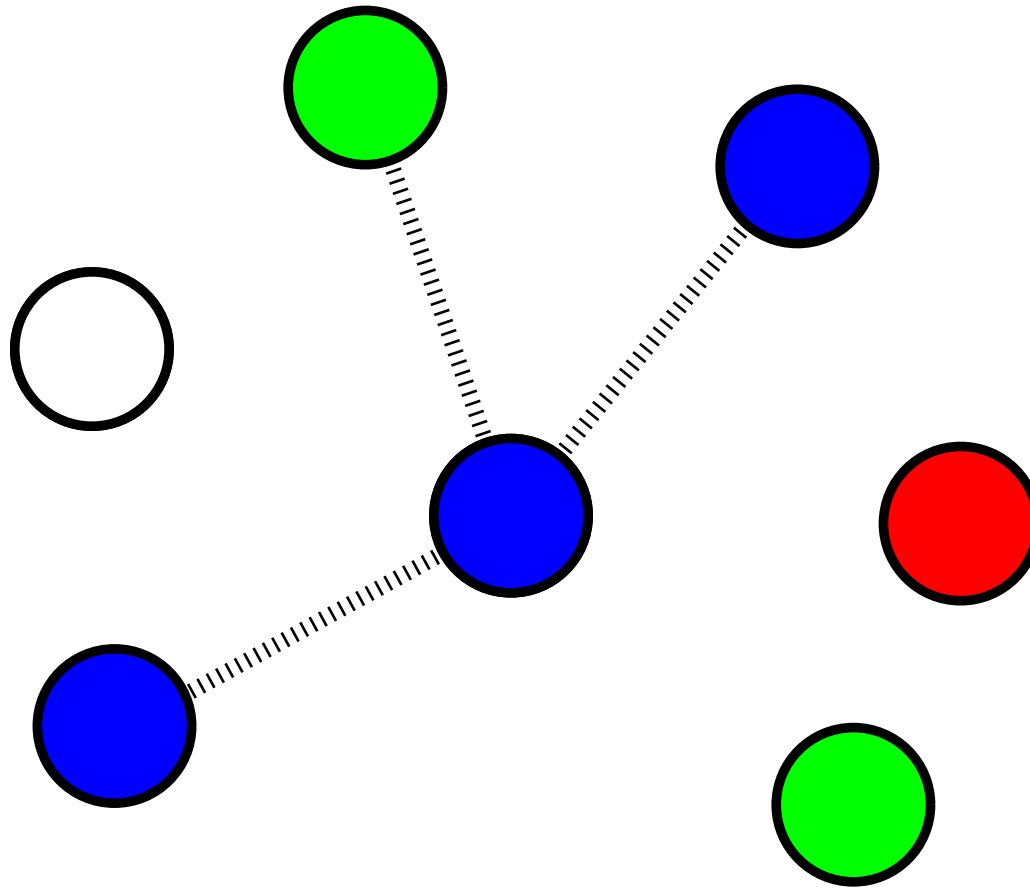


The 3-Majority Dynamics



Each node observes the color of three other nodes
chosen u.a.r....

The 3-Majority Dynamics



...and changes its color according to the majority of these three (breaking ties u.a.r.).

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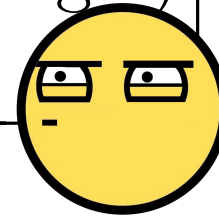
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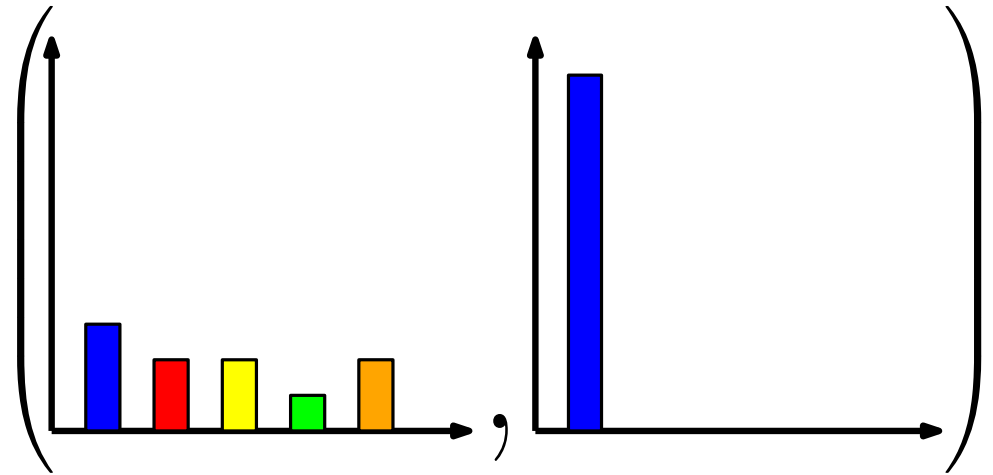
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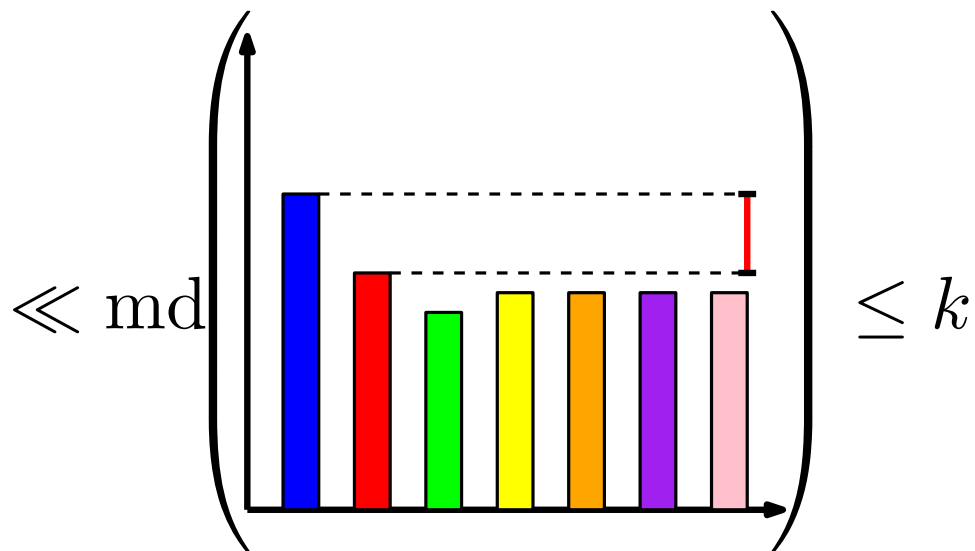
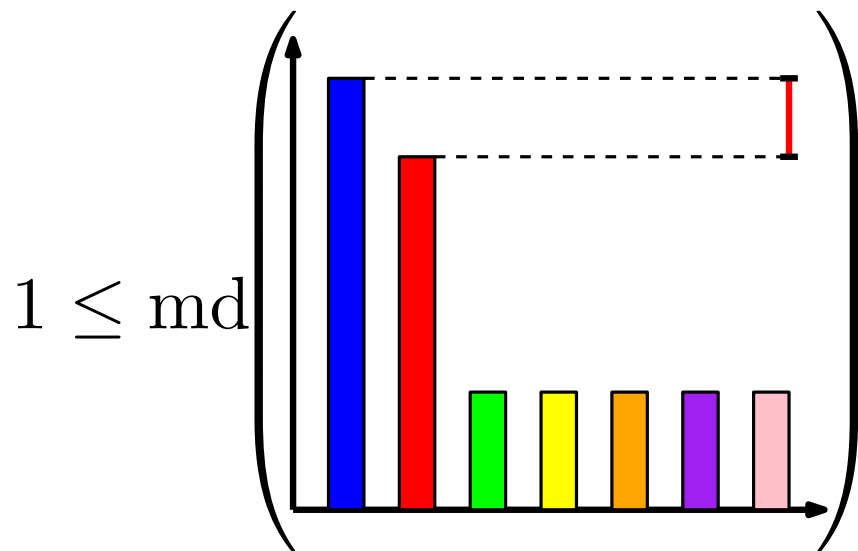
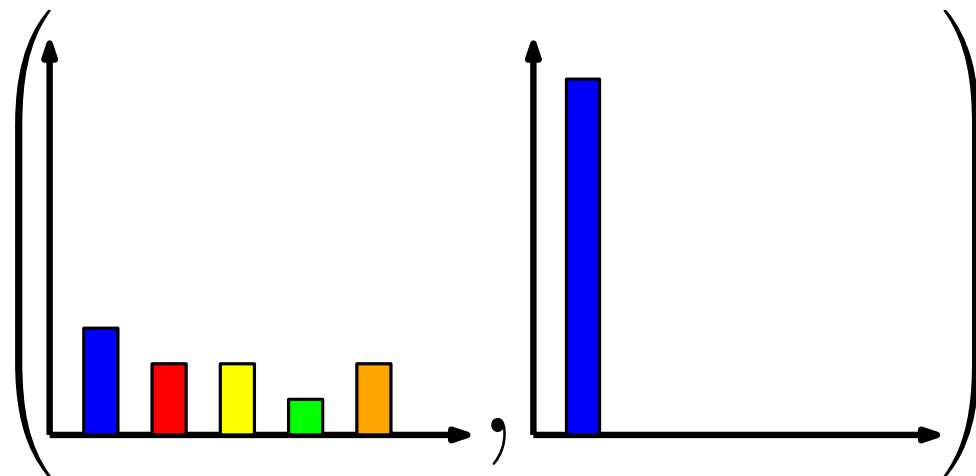
The Monochromatic Distance

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Our Results

First analysis for $k = \omega(1)$ of the Undecided-State Dynamics:
(Angluin et al., Perron et al.,
Babae et al., Jung et al.)

Upper Bound

If $k = O((n/\log n)^{1/3})$ and $c_1 \geq (1 + \epsilon) \cdot c_2$ with $\epsilon > 0$,
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plurality consensus in $O(\text{md}(\mathbf{c}^{(0)}) \cdot \log n)$ rounds.

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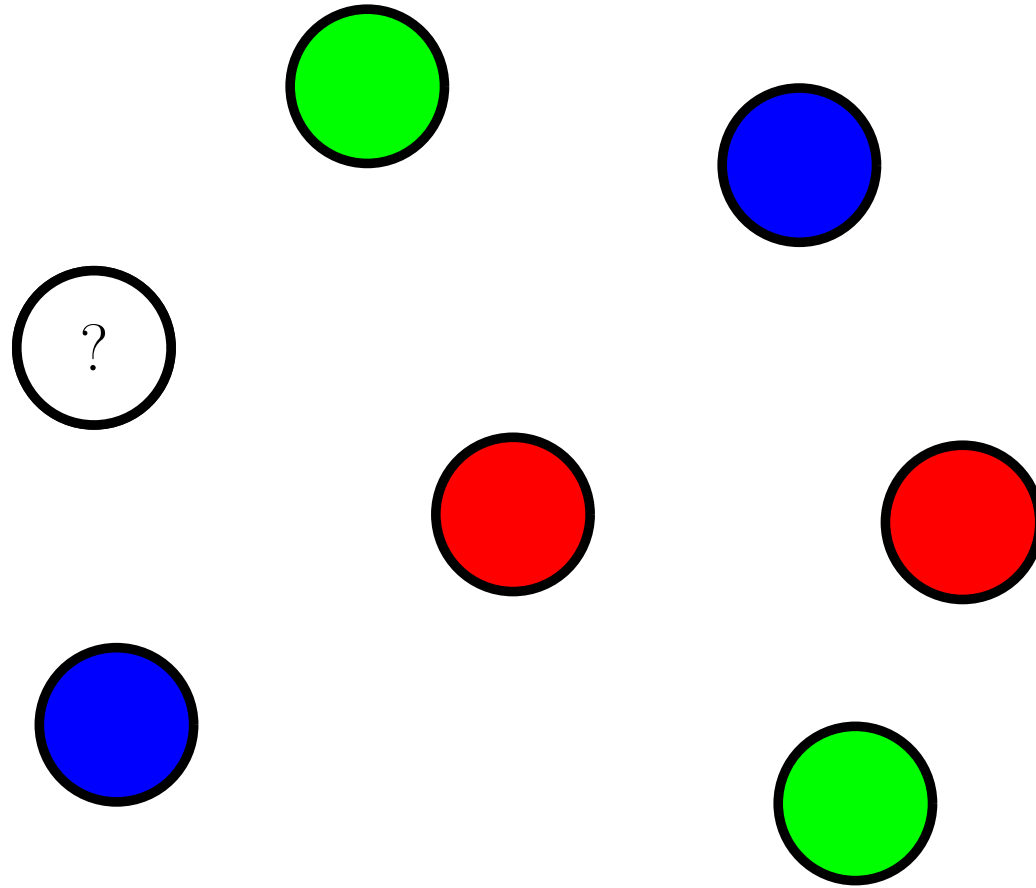
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Lower Bound

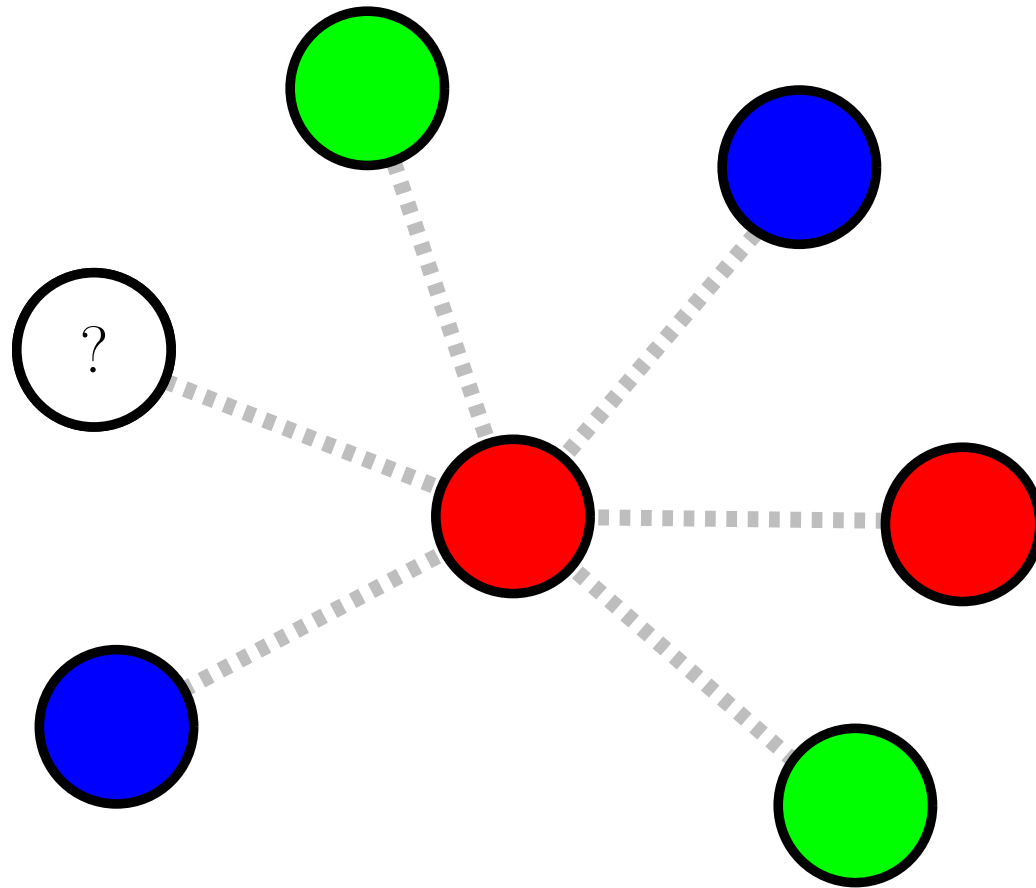
If $k = O((n/\log n)^{1/6})$ then w.h.p. the Undecided-State Dynamics converges after at least $\Omega(\text{md}(\mathbf{c}^{(0)}))$ rounds.

The Undecided-State Dynamics



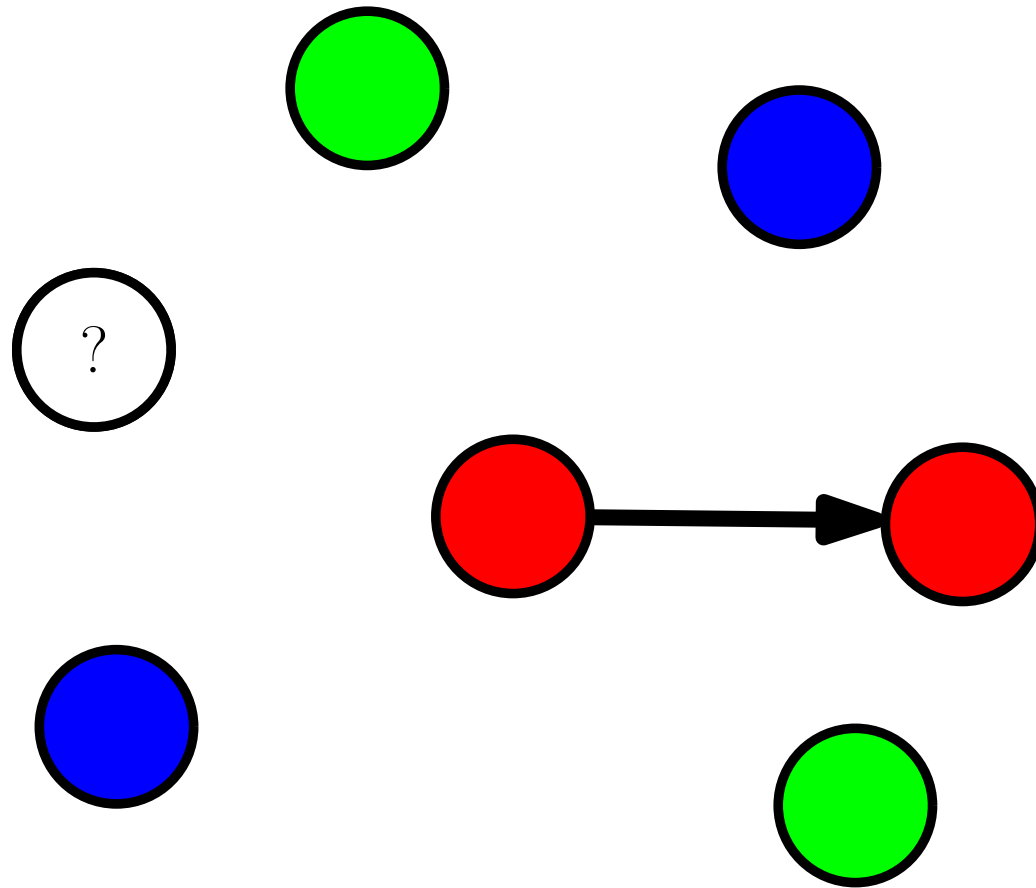
Some nodes can be “undecided”.

The Undecided-State Dynamics



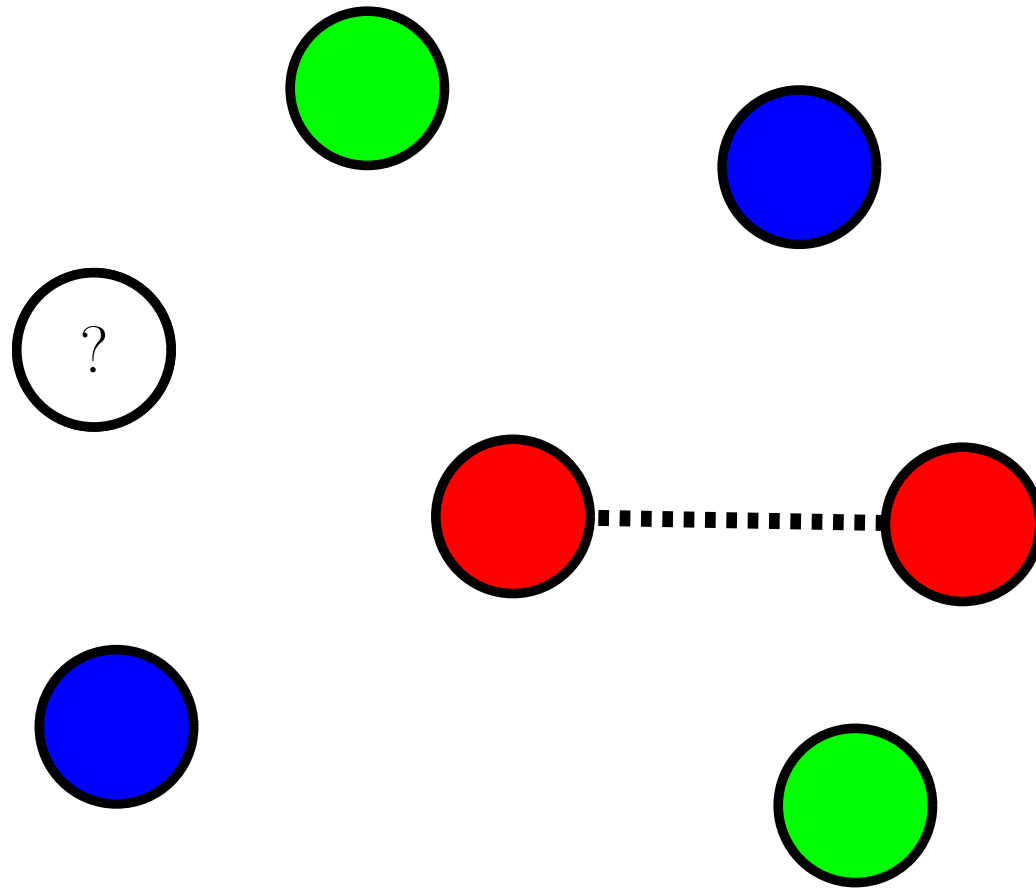
At the beginning of each round, each node observes a neighbor picked uniformly at random.

The Undecided-State Dynamics



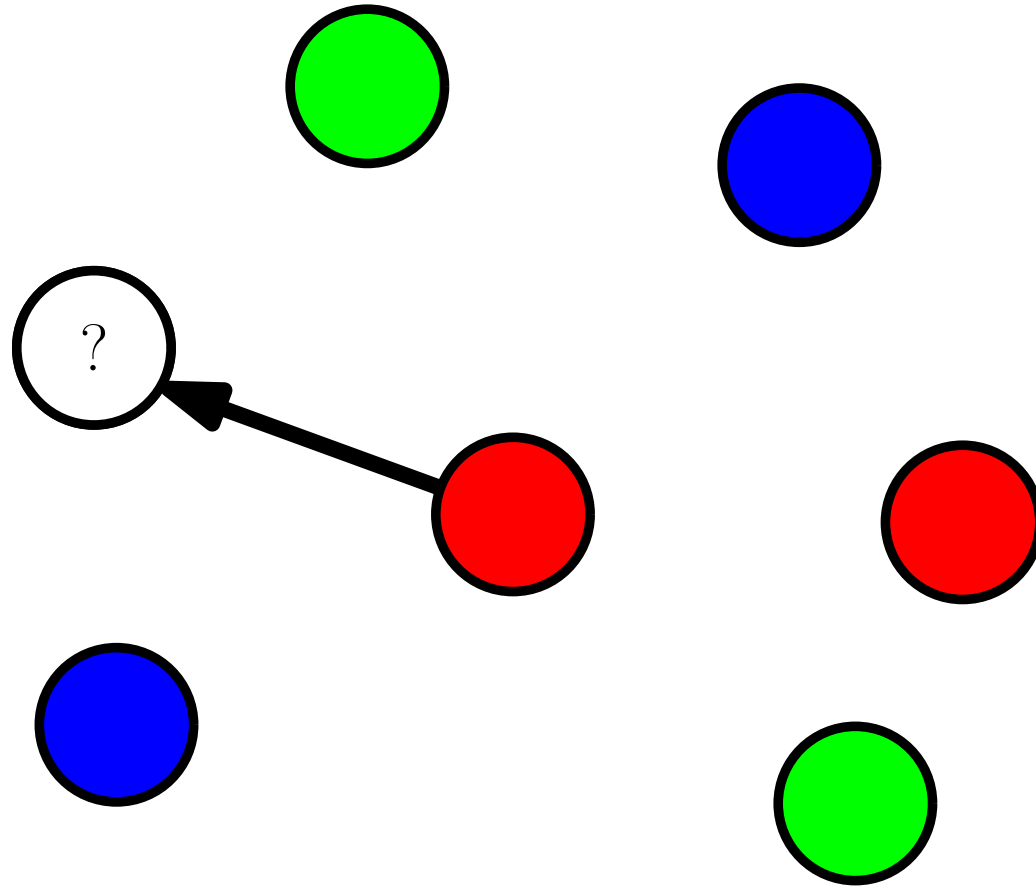
If the observed node shares the same color...

The Undecided-State Dynamics



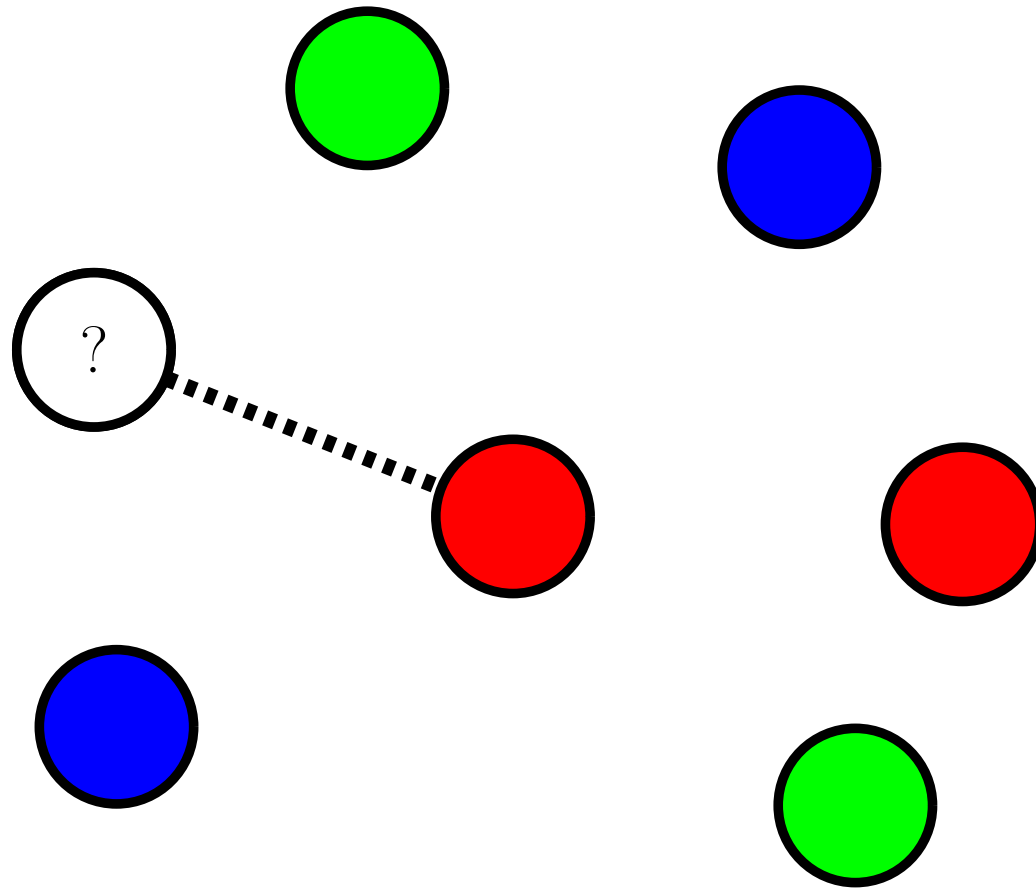
... nothing happens;

The Undecided-State Dynamics



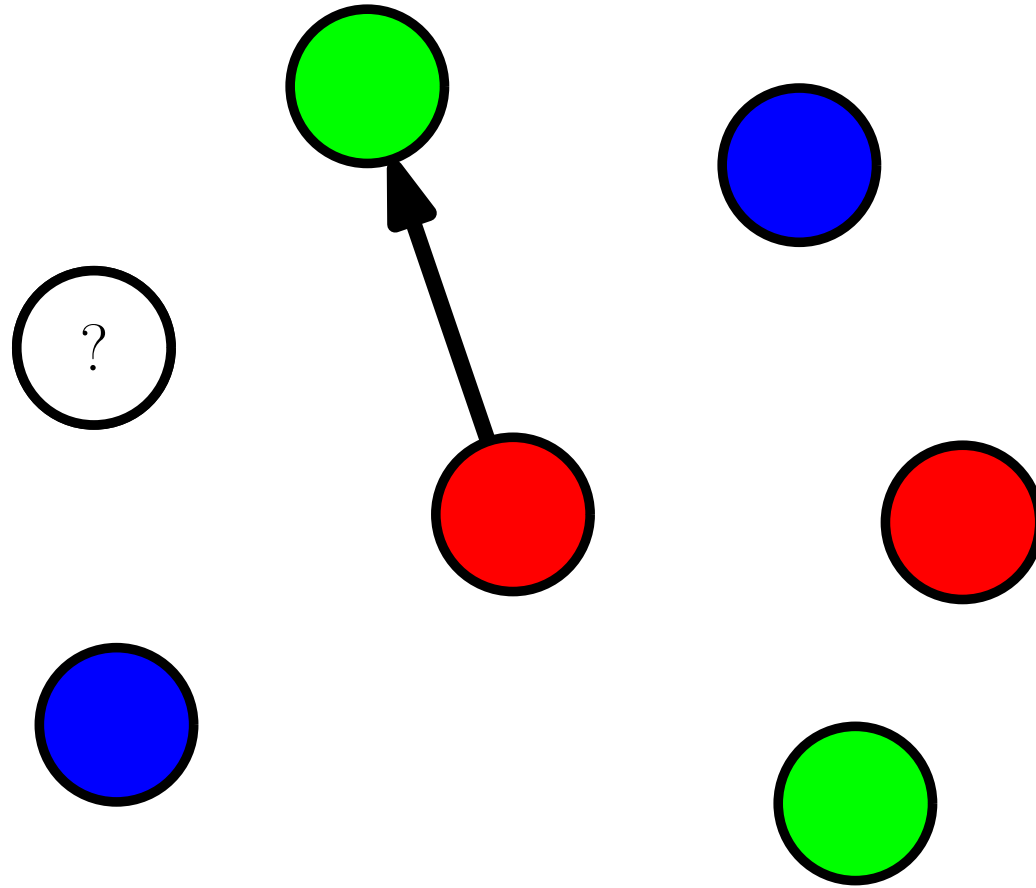
if the node observes an undecided one...

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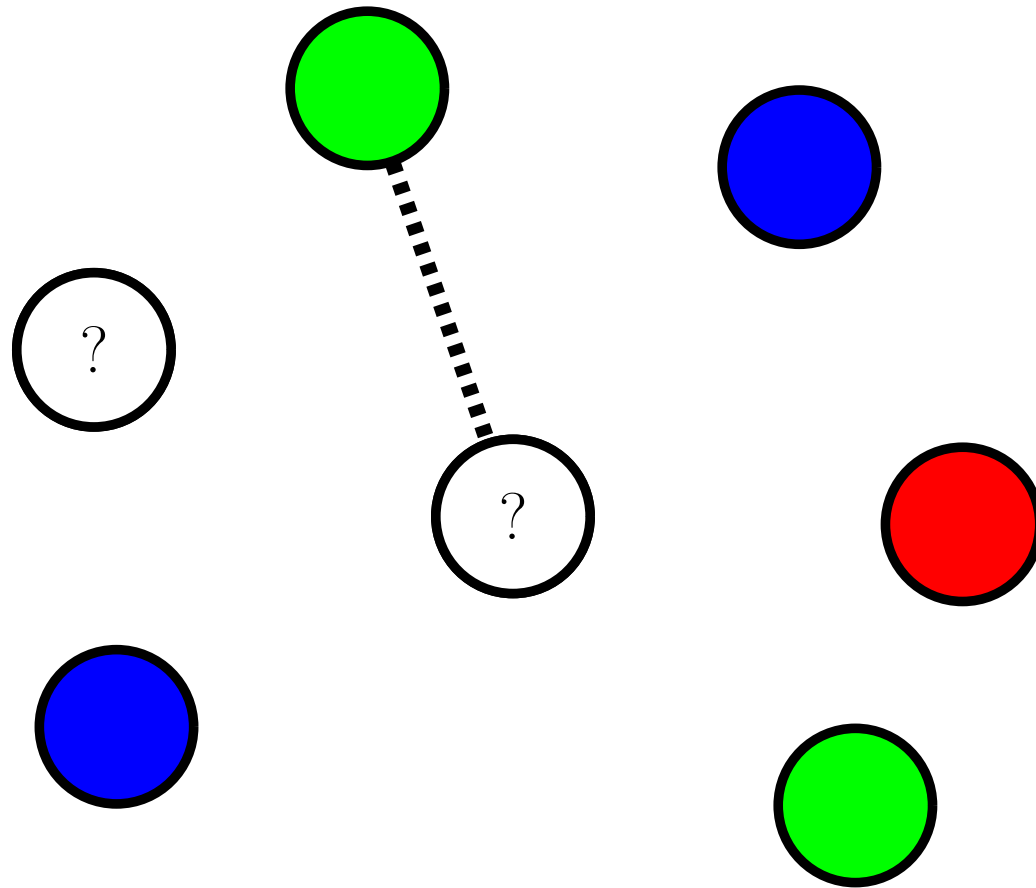
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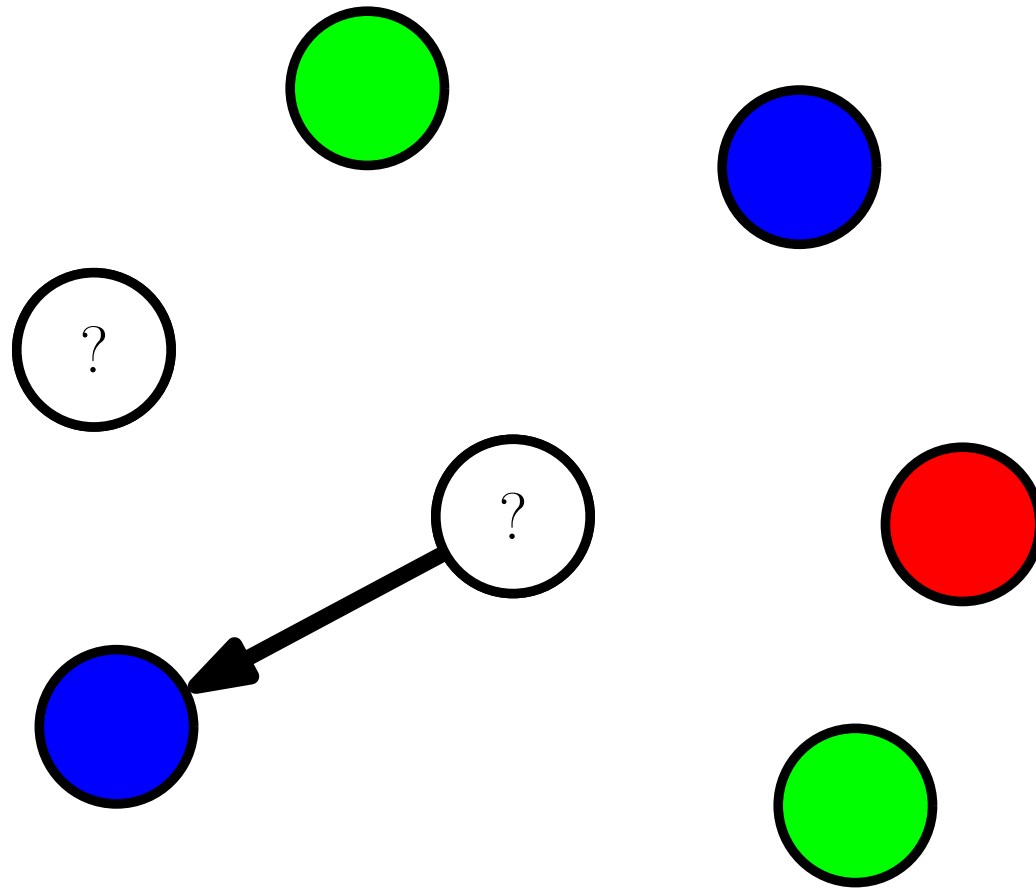
but, if the observed node has a different color...

The Undecided-State Dynamics



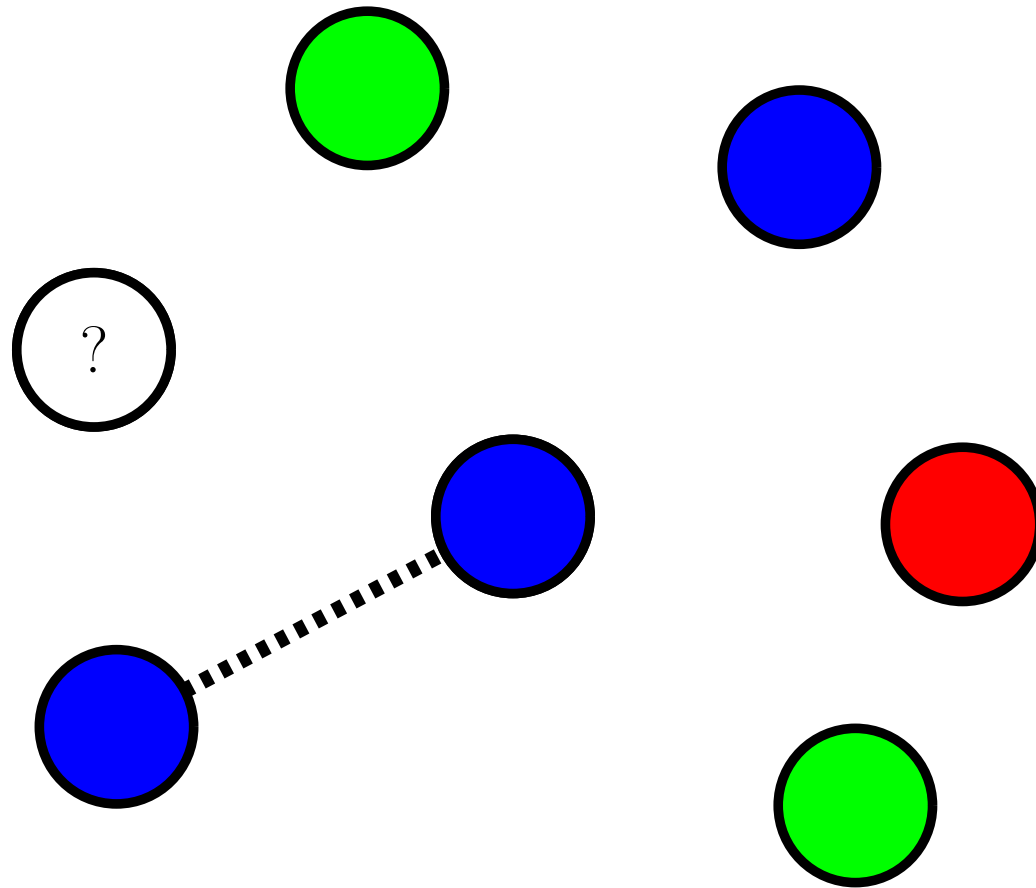
... then the node becomes undecided.

The Undecided-State Dynamics



Once undecided...

The Undecided-State Dynamics



... the node copies the first color it sees.

Overview of the Process

$c_i^{(t)} := |\{i\text{-colored nodes}\}|$, color 1 is the plurality,

$q^{(t)} := |\{\text{undecided nodes}\}|$, $\mathbf{c}^{(t)} := \left(c_1^{(t)}, \dots, c_k^{(t)}, q^{(t)} \right)$.

$$\mathbf{E} \left[c_i^{(t+1)} \mid \mathbf{c}^{(t)} \right] = c_i^{(t)} \cdot \underbrace{\frac{c_i^{(t)} + 2q^{(t)}}{n}}_{\text{Growth factor}}$$

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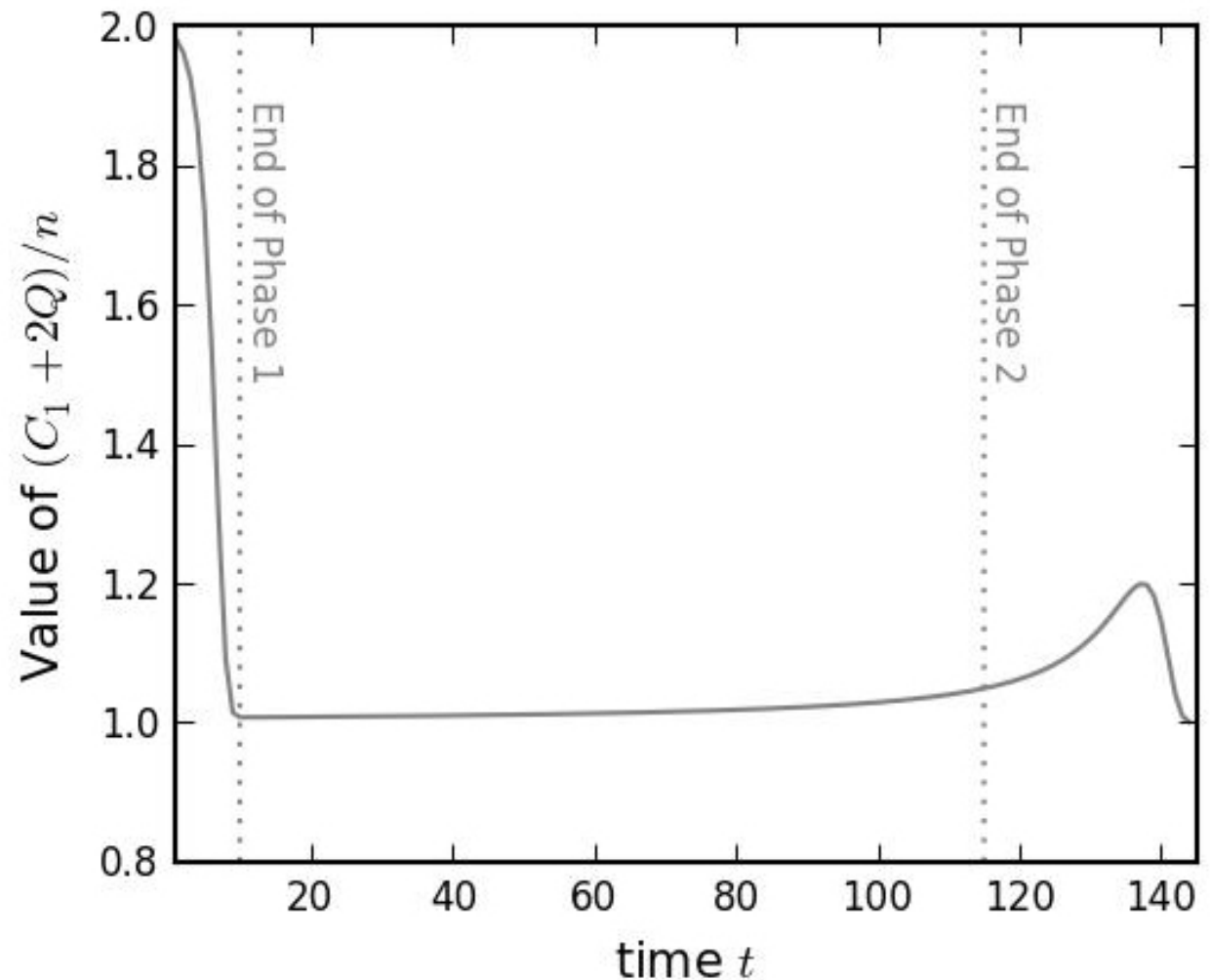
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Remarks

W.h.p.

- Plurality does not change.
- Growth factor of plurality is > 1 .

Simulation of the growth factor:



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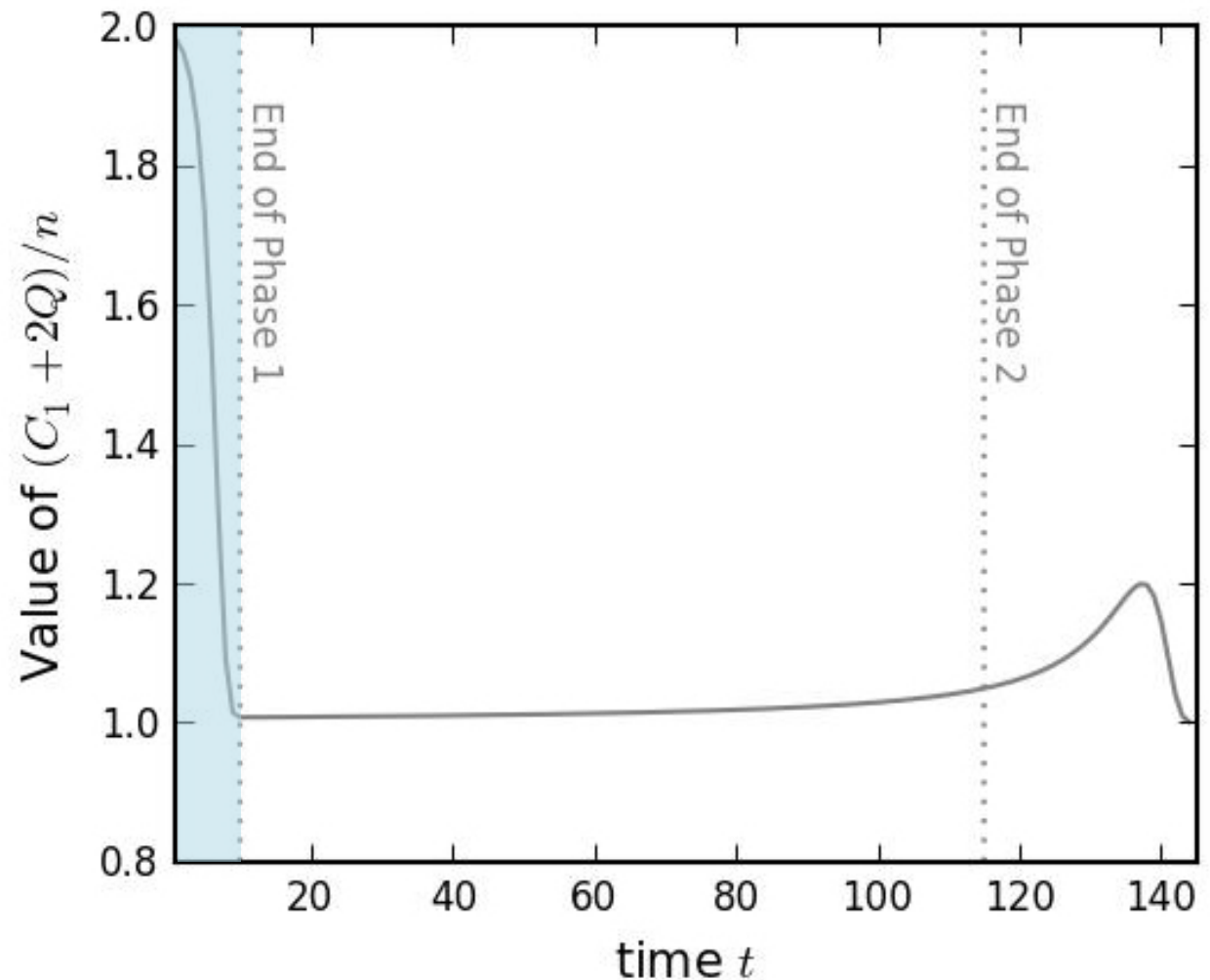
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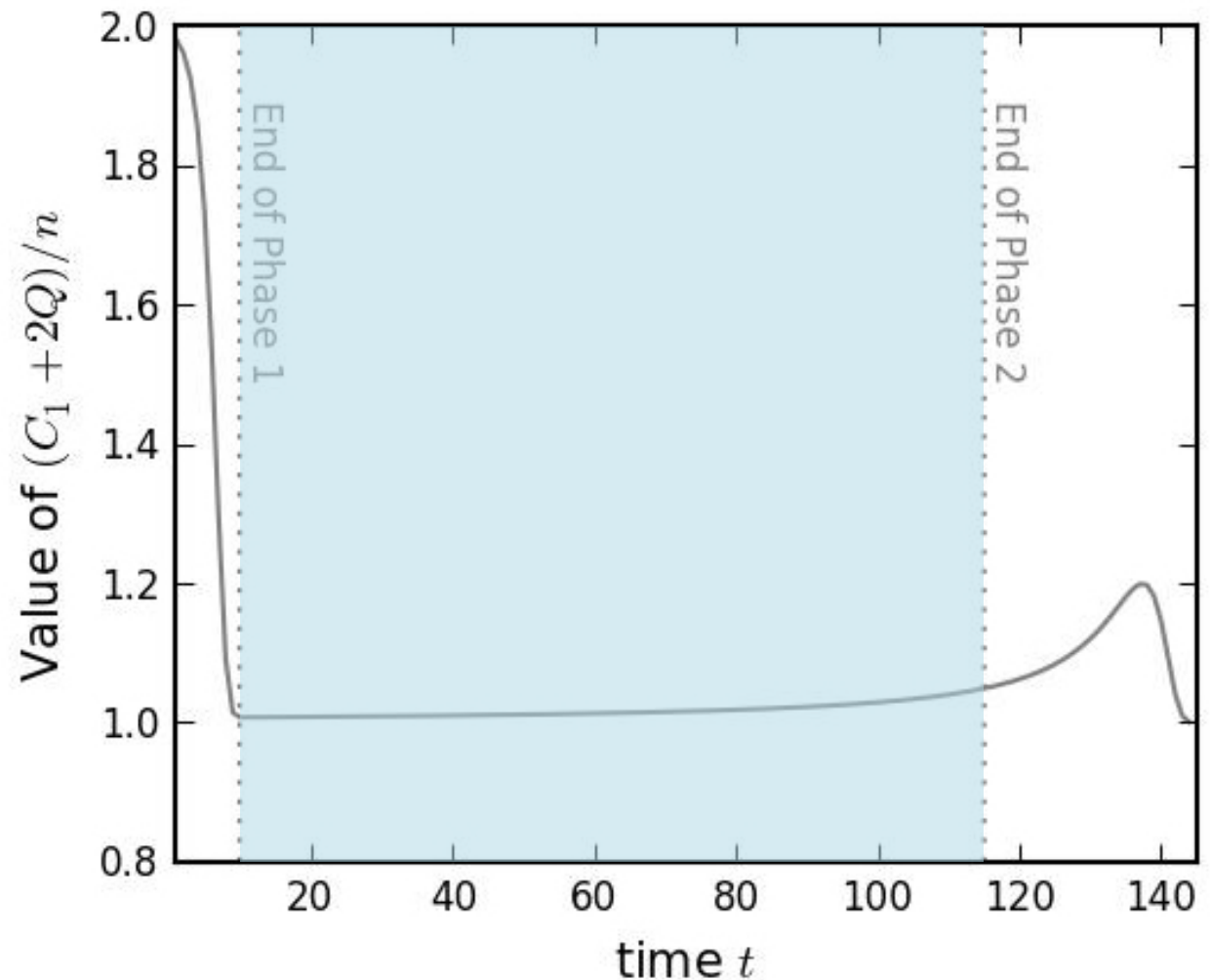
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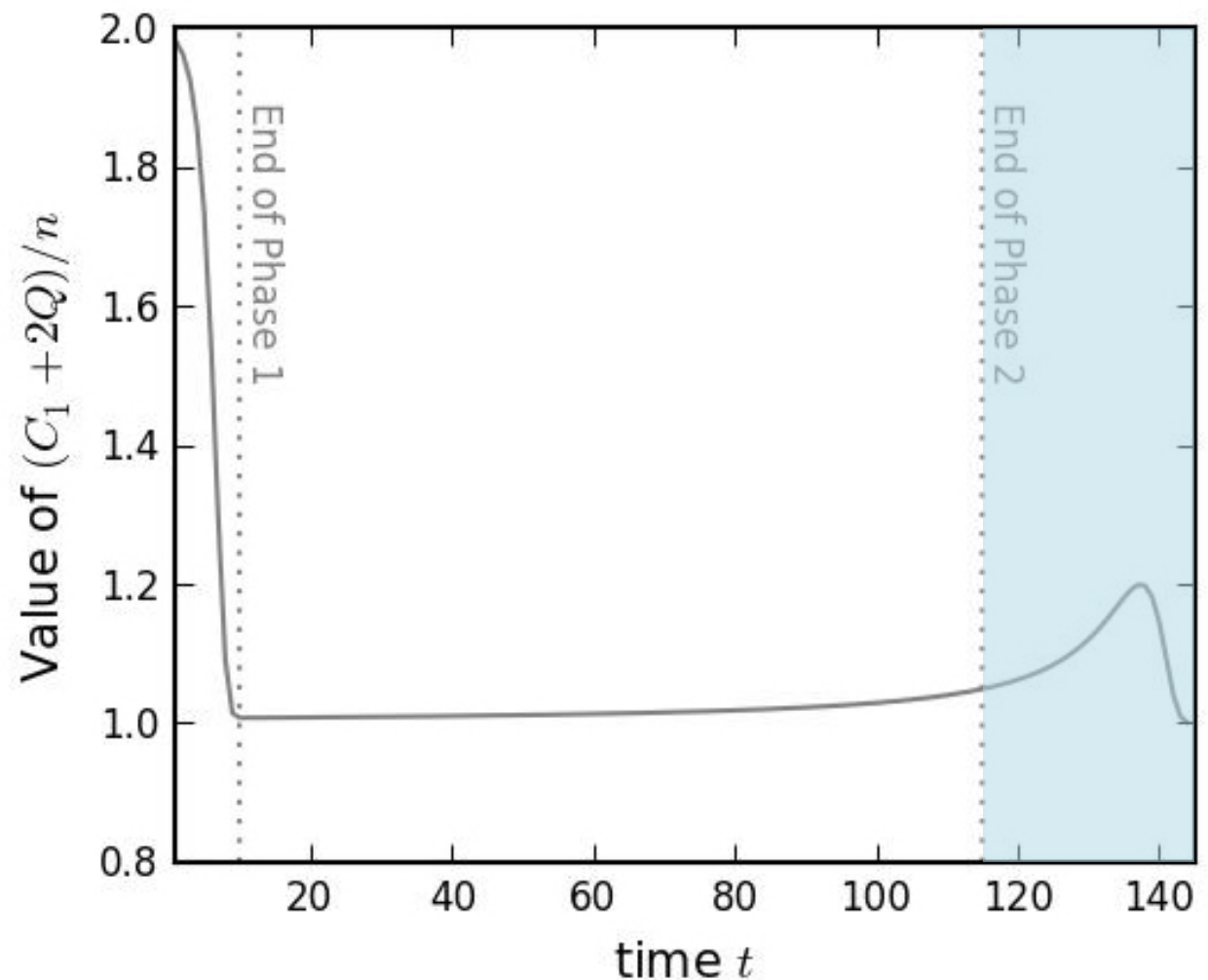
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Expected Behaviour of the Process

$$\left\{ \begin{array}{l} \mathbf{E} \left[q^{(t+1)} \mid \mathbf{c}^{(t)} \right] = \frac{1}{n} \left[\left(q^{(t)} \right)^2 + \left(n - q^{(t)} \right)^2 - \sum_i \left(c_i^{(t)} \right)^2 \right] \\ \mathbf{E} \left[c_1^{(t+1)} \mid \mathbf{c}^{(t)} \right] = c_1^{(t)} \cdot \frac{c_1^{(t)} + 2q^{(t)}}{n} \\ \vdots \\ \mathbf{E} \left[c_k^{(t+1)} \mid \mathbf{c}^{(t)} \right] = c_k^{(t)} \cdot \frac{c_k^{(t)} + 2q^{(t)}}{n} \end{array} \right.$$

Key Idea

Tip: Look for $md(\mathbf{c}^{(t)})$ and $R(\mathbf{c}^{(t)}) := \sum_{i=1}^k \frac{c_i^{(t)}}{c_1^{(t)}}$.

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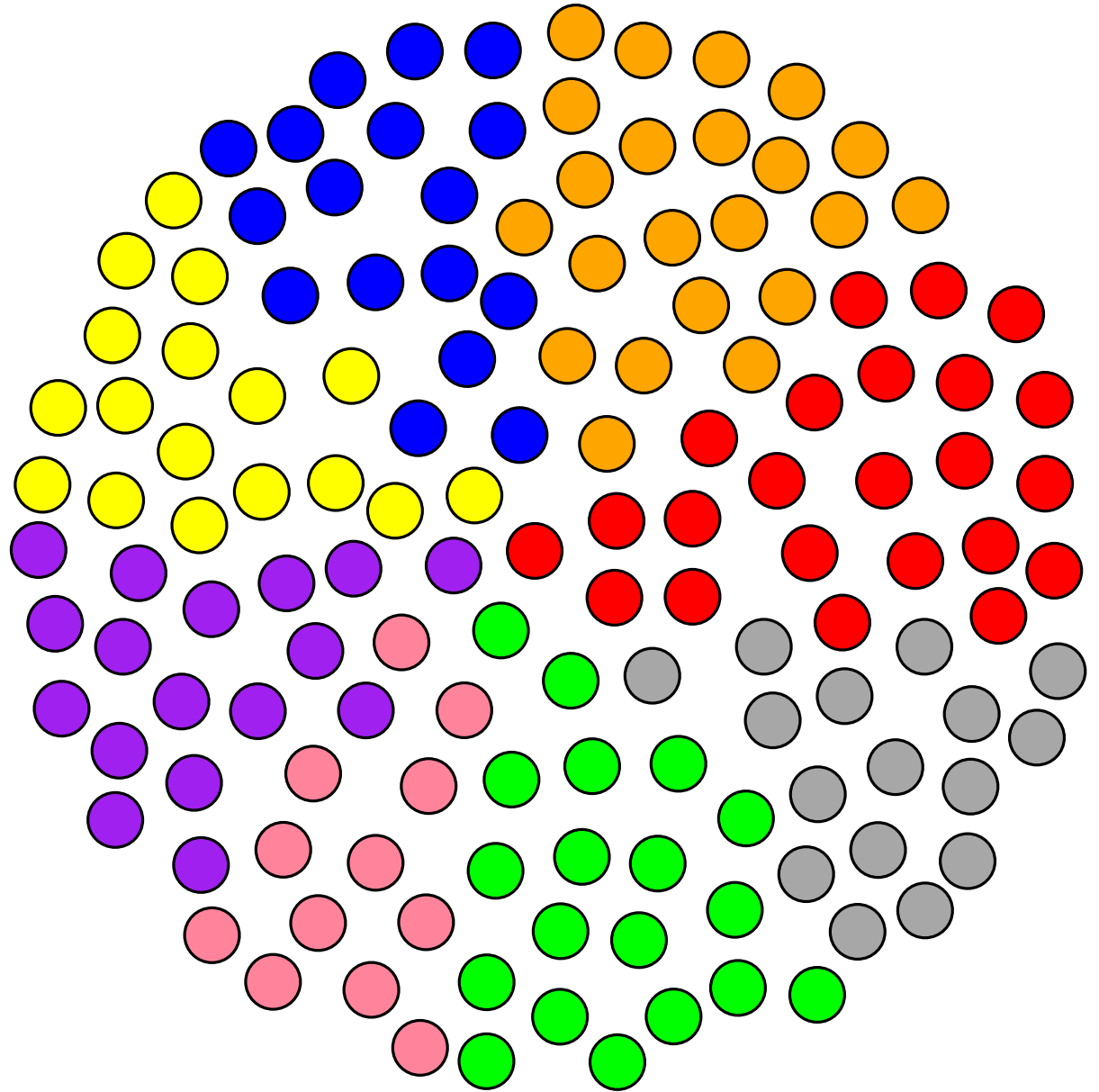
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$$\begin{aligned} \mathbf{E} \left[\frac{c_1^{(t+1)} + 2q^{(t+1)}}{n} \mid \mathbf{c}^{(t)} \right] &= \\ &= 1 + \frac{\left(n - 2q^{(t)} - c_1^{(t)} \right)^2}{n^2} + \frac{2 \left(R(\mathbf{c}^{(t)}) - md(\mathbf{c}^{(t)}) \right) \cdot (c_1)^2}{n^2} \end{aligned}$$

First Round

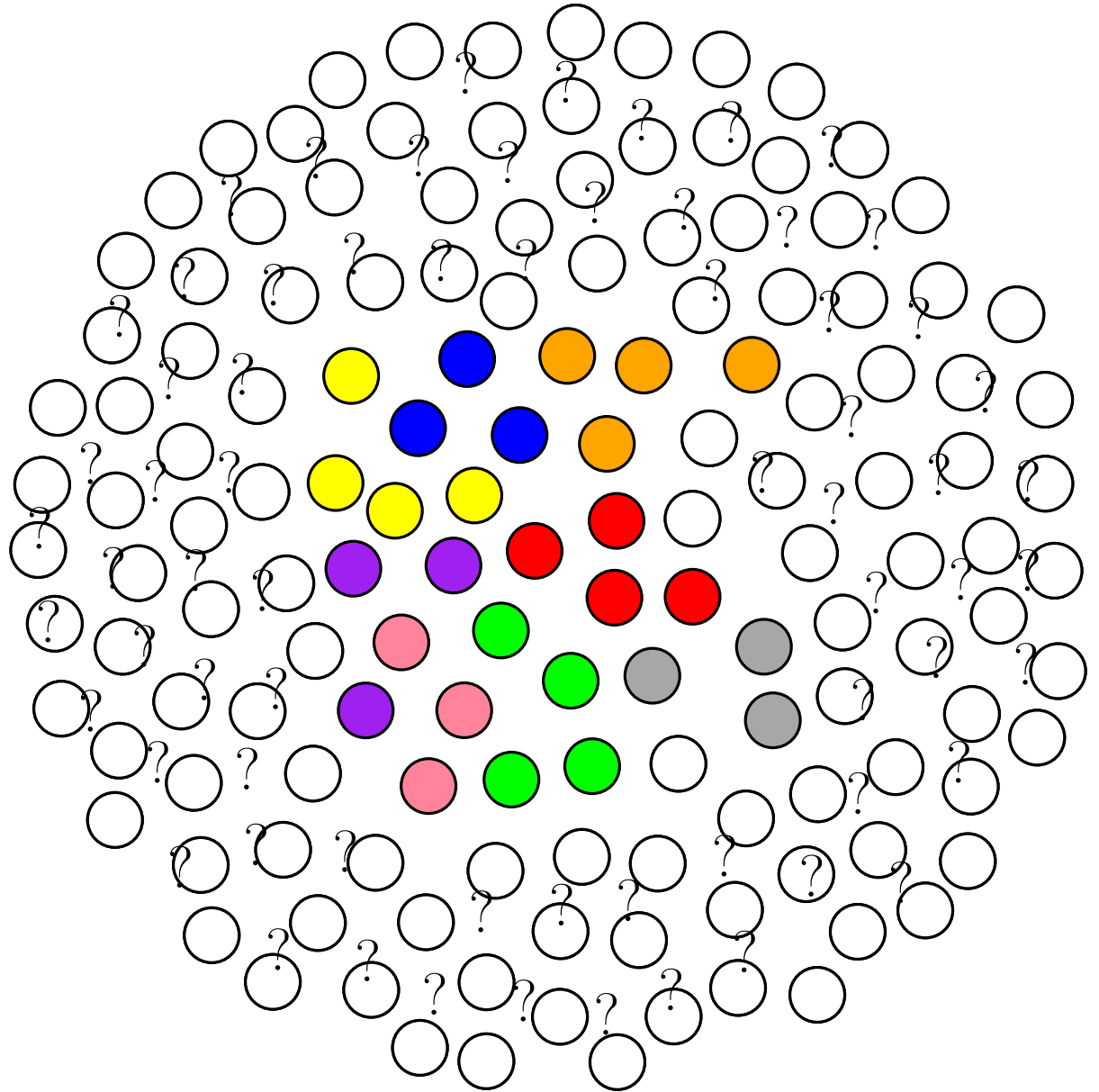
Round 1:

Each node observes another random one. The larger the number of colors and the more uniform the initial distribution, the higher the expected number of undecided nodes.

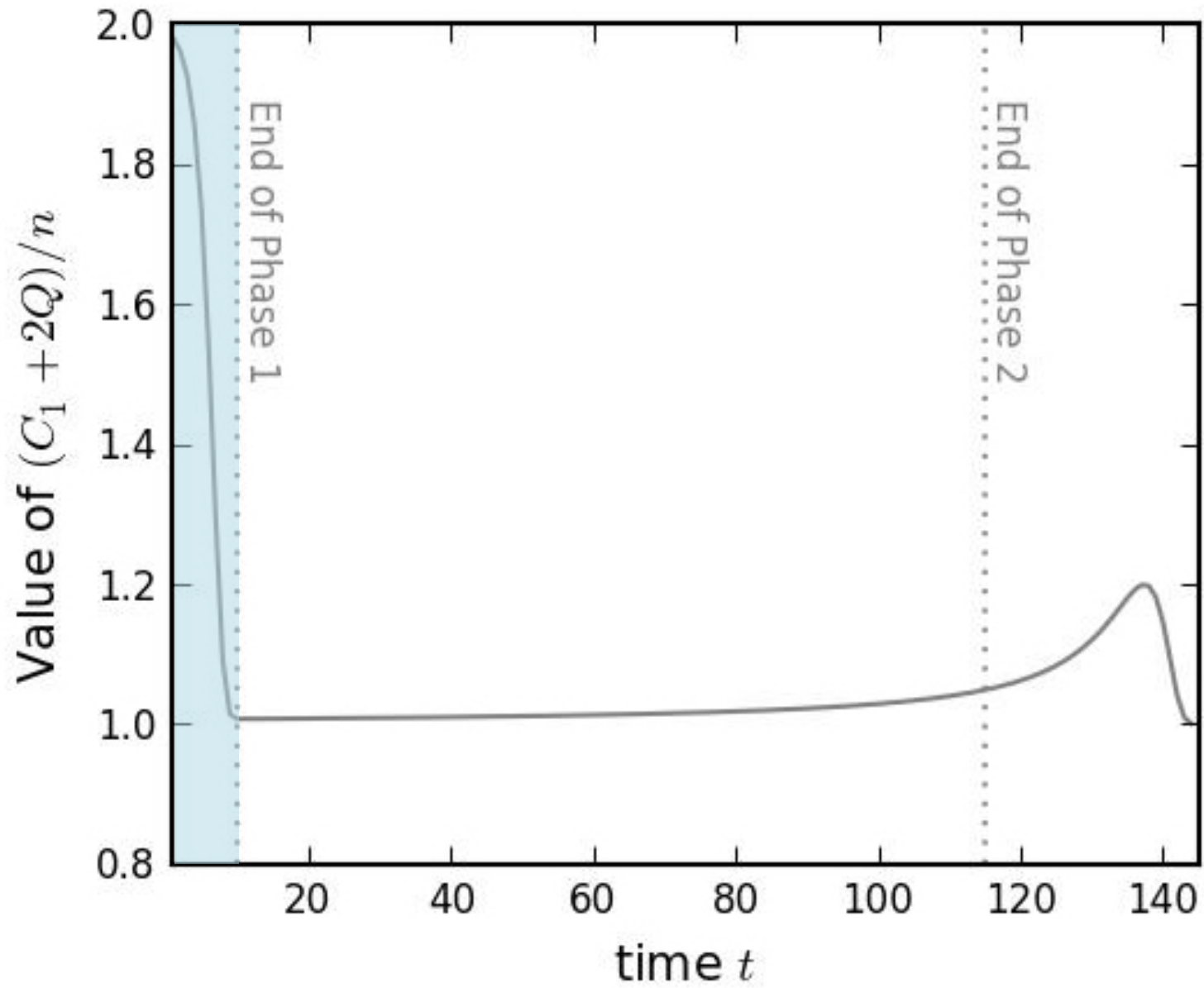


First Round

The size of each color is reduced to $\frac{(c_i^{(0)})^2}{n}$.
Colors with $c_i^{(0)} = O(\sqrt{n})$ nodes are likely to disappear.

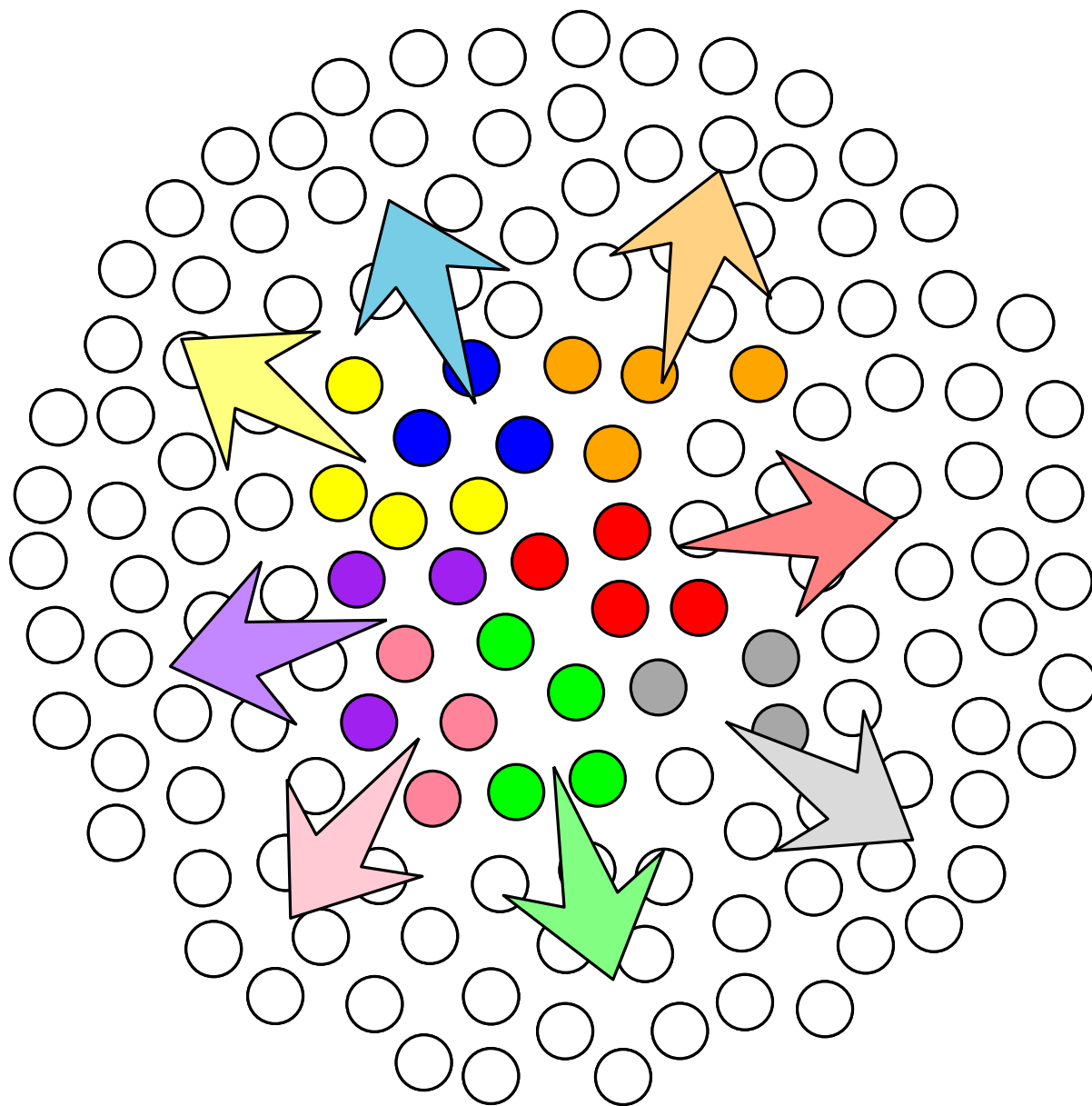


Phase 1



Phase 1

If the initial distribution is quite uniform there are $\Omega(n)$ undecided nodes. Undecided nodes take the first color they pull, causing colors to spread very fast.



Phase 1

Lemma

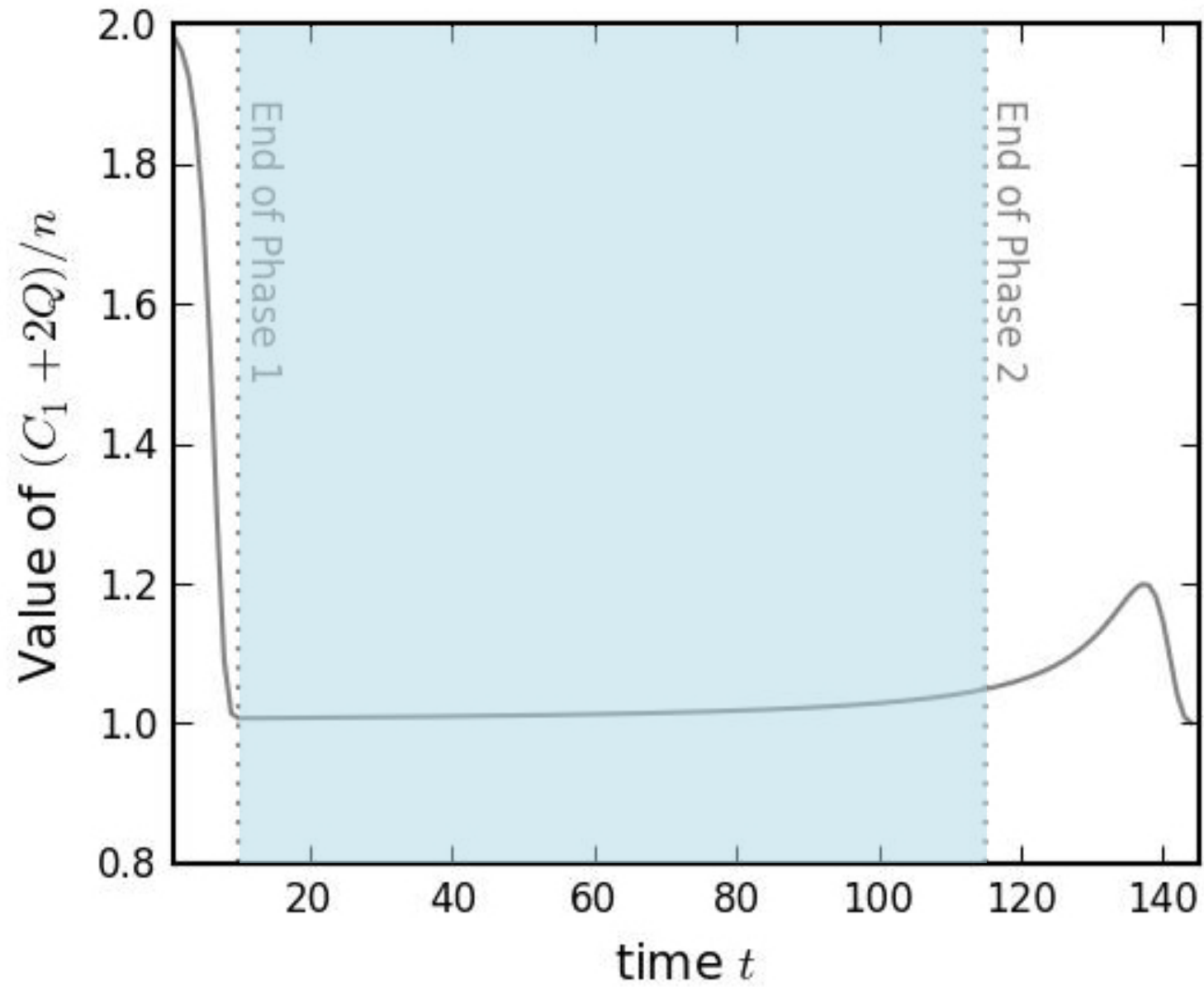
Within $T = O\left(\log \frac{R(\mathbf{c})^2}{\text{md}(\mathbf{c})}\right)$ rounds the system reaches a configuration such that w.h.p.

$$c_1^{(T)} = \Theta\left(\frac{n}{\text{md}(\mathbf{c})}\right)$$

$$q^{(T)} = \frac{n}{2} \left(1 \pm \Theta\left(\frac{1}{\text{md}(\mathbf{c})}\right)\right)$$

and, for every i , $c_1^{(0)}/c_i^{(0)}$ is approximately preserved.

Phase 2

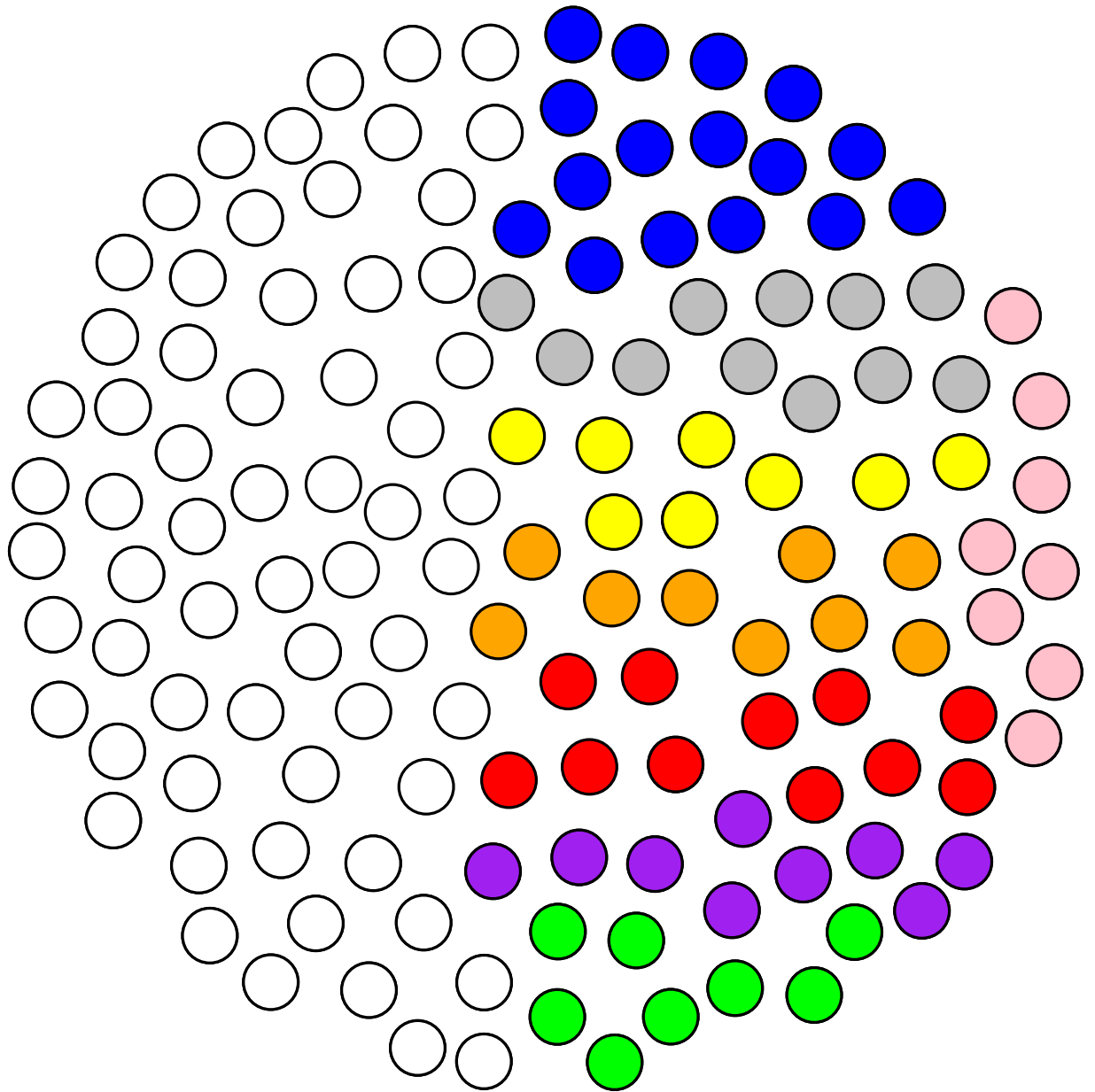


Phase 2

new colored

\approx

new undecided.

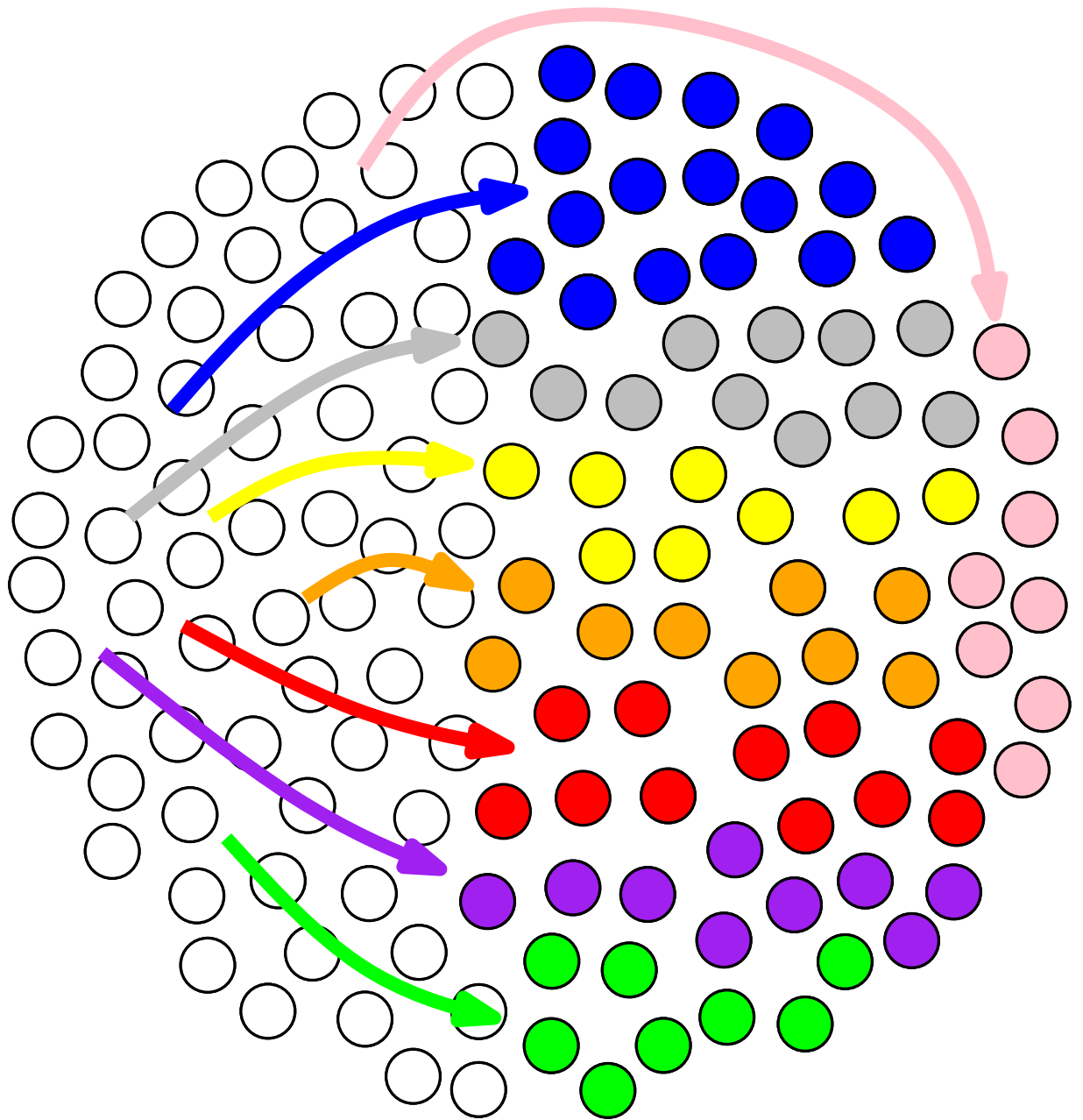


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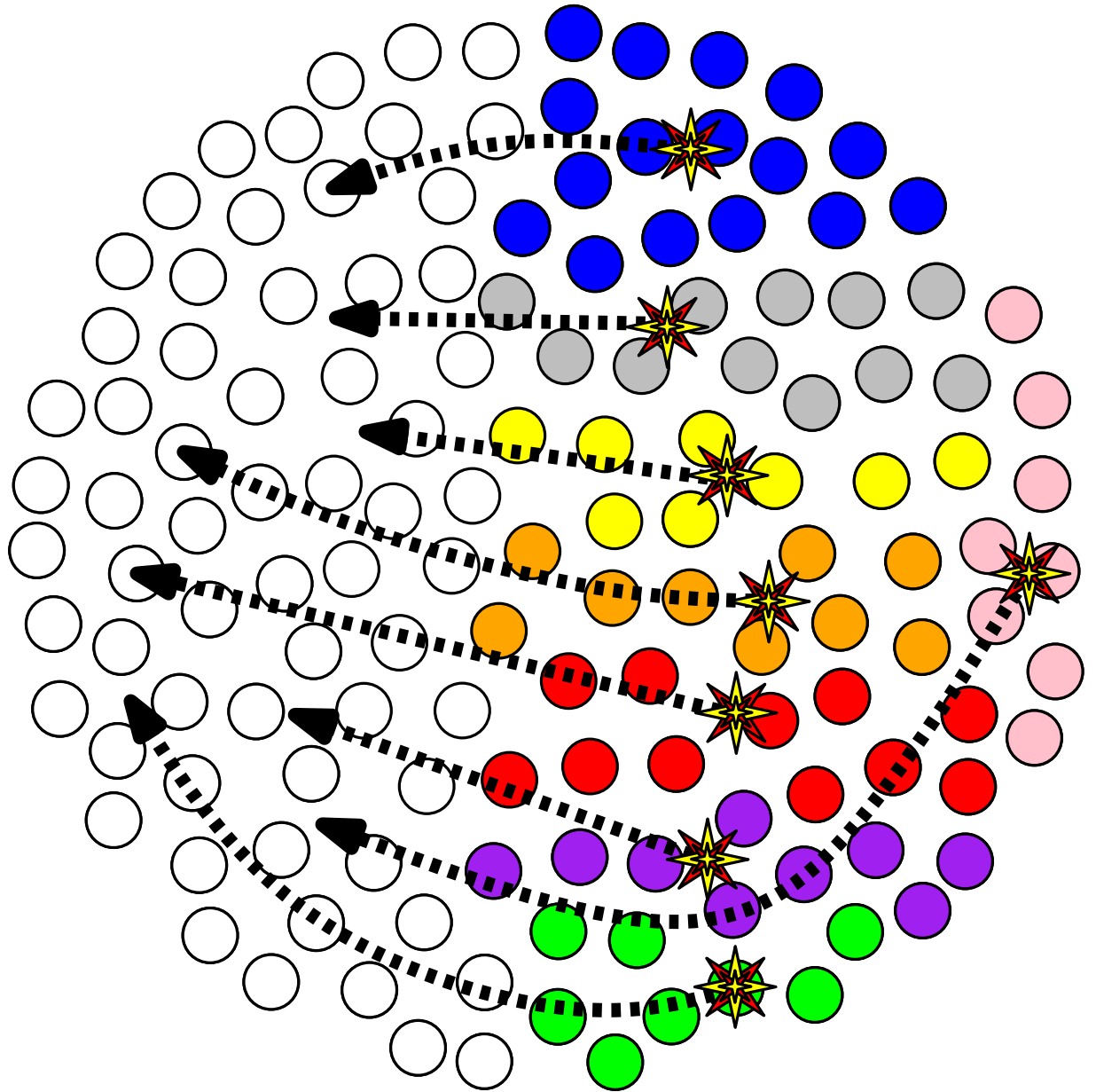


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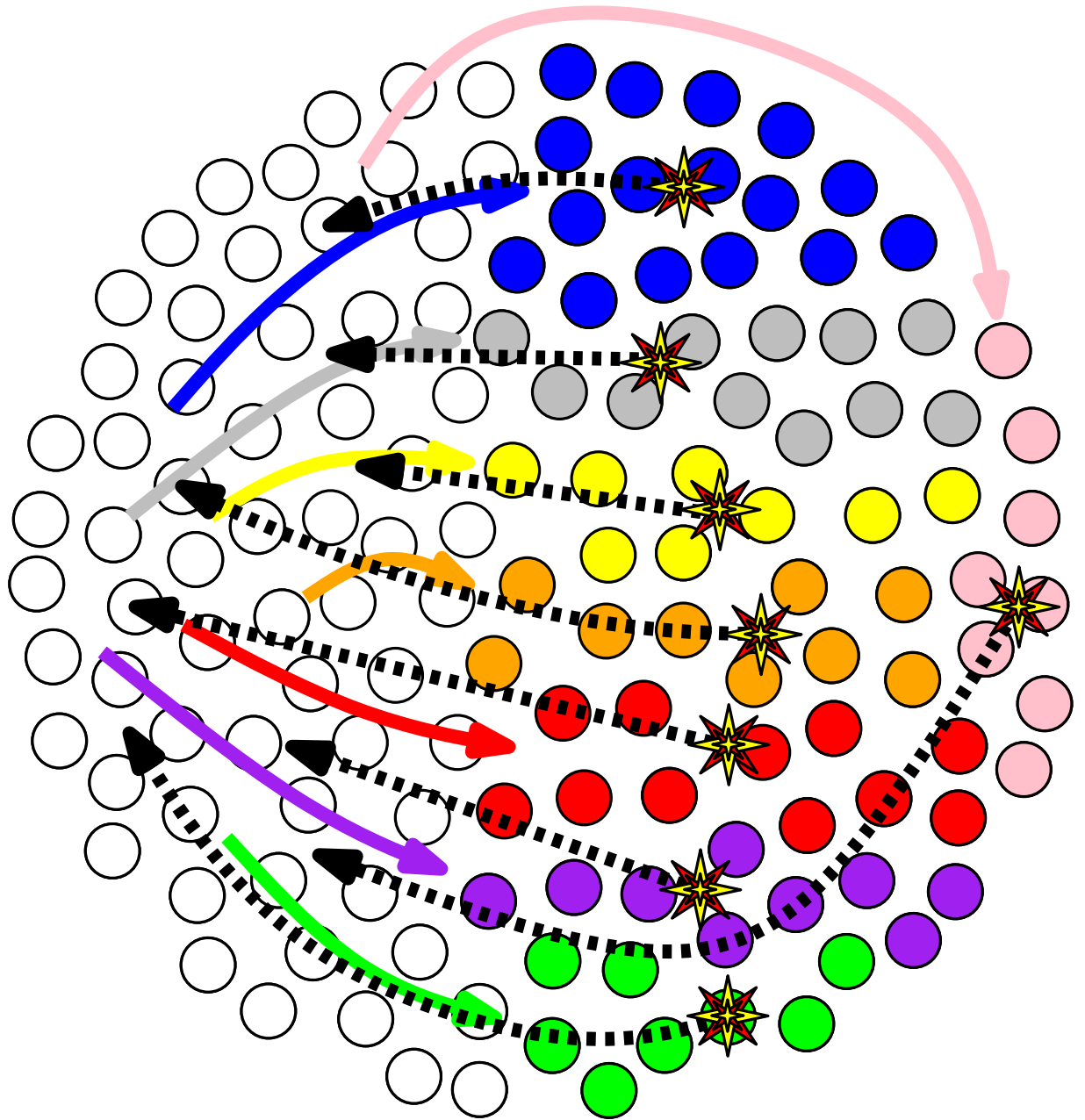


Phase 2

new colored

\approx

new undecided.



Phase 2

Average Growth:

$$\mathbf{E} \left[c_1^{(t+1)} \mid \mathbf{c}^{(t)} \right] \approx c_1^{(t)} \left(1 + \Theta \left(\frac{1}{\text{md}(\mathbf{c})} \right) \right)$$

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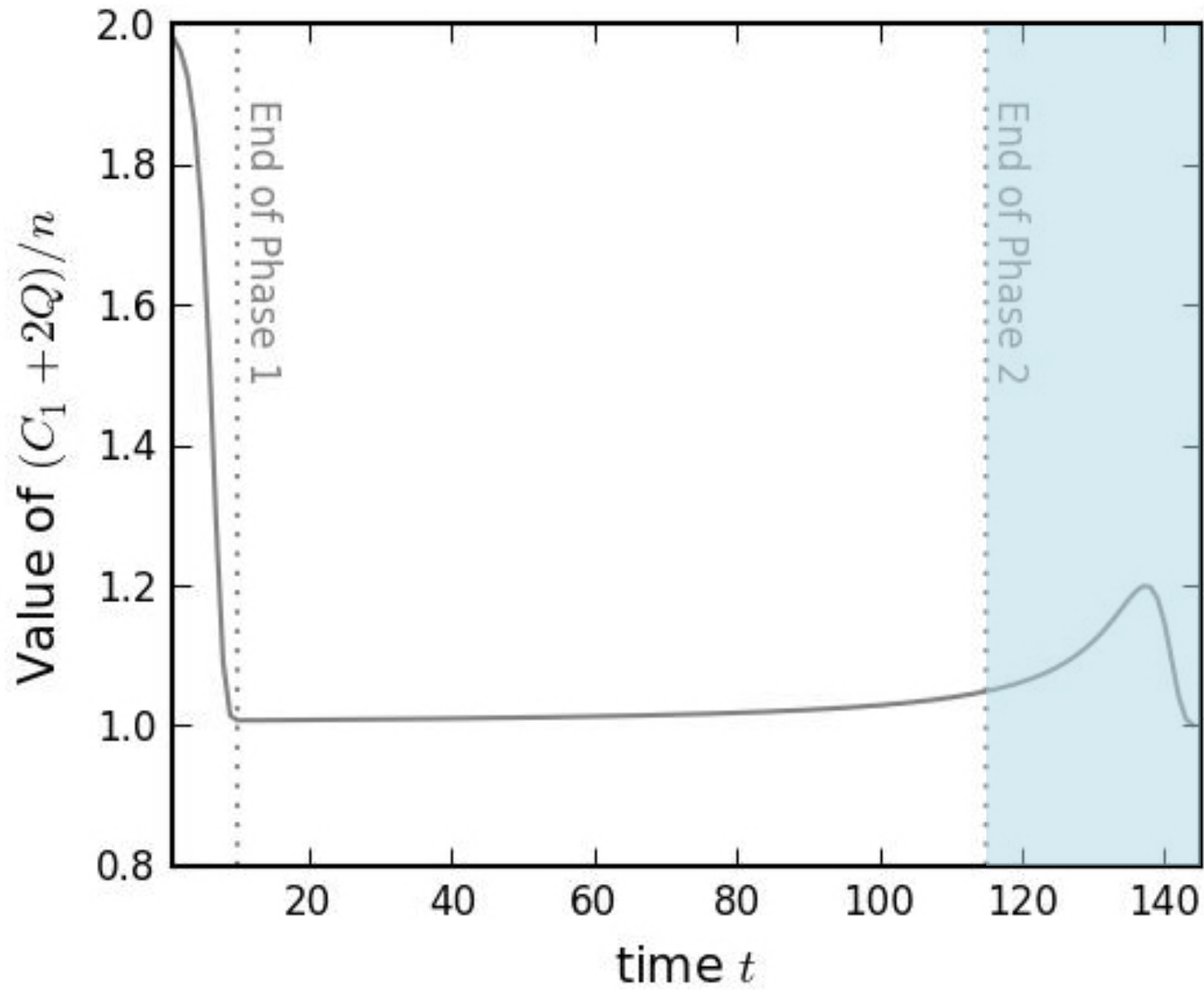
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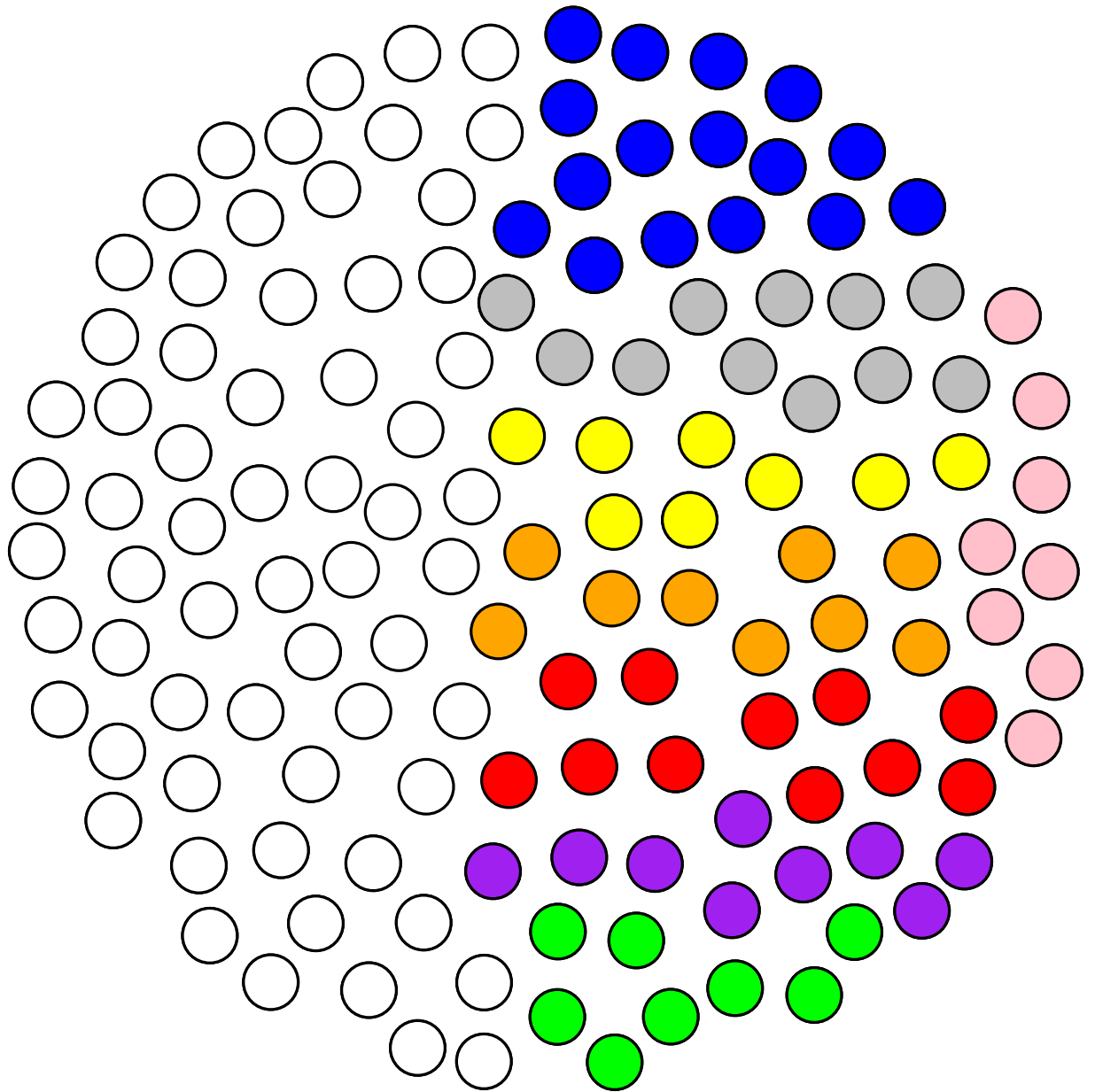
\implies Lower bound of $\Omega(\text{md}(\mathbf{c}))$.

Phase 3



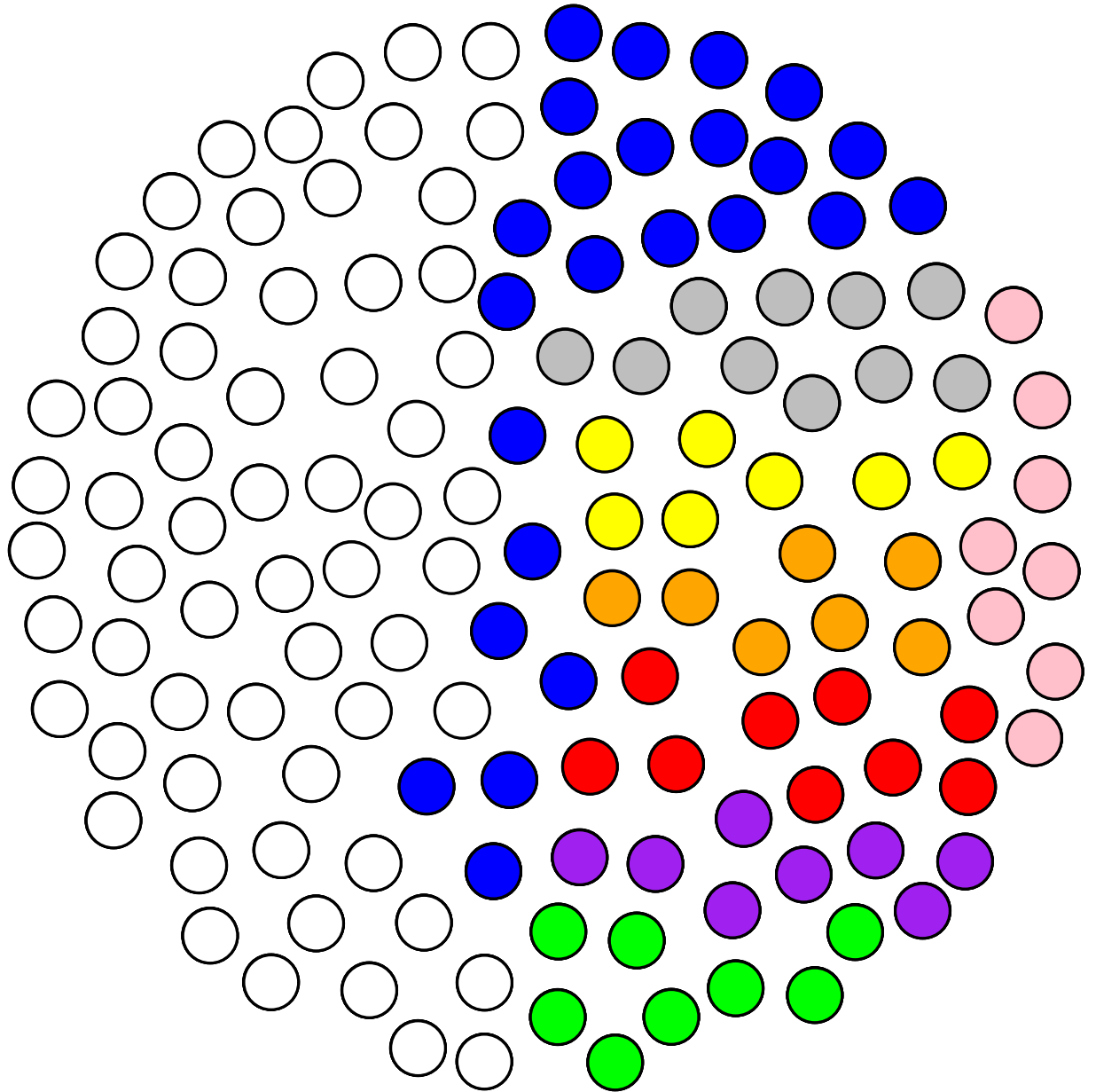
Phase 3

The plurality has a
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 \implies after long time
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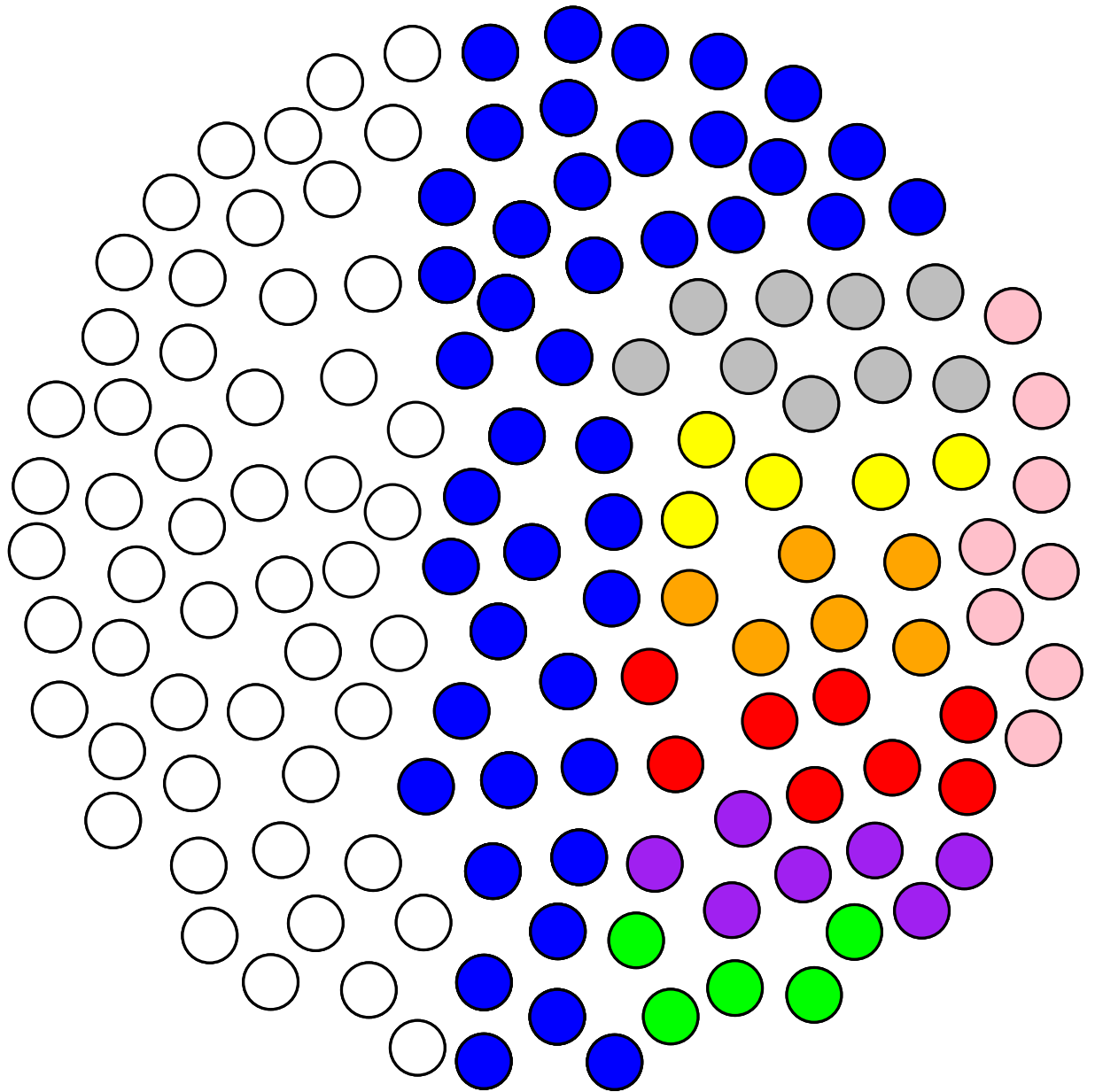
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$$\mathbf{E} \left[c_1^{(t + \text{md}(\mathbf{c}))} \mid \mathbf{c}^{(t)} \right] \approx c_1^{(t)} \left(1 + \Theta \left(\frac{1}{\text{md}(\mathbf{c})} \right) \right)^{\text{md}(\mathbf{c})}$$

$$\mathbf{E} \left[q^{(t + \text{md}(\mathbf{c}))} \mid \mathbf{c}^{(t)} \right] \approx \frac{n}{2} \left(1 - \Theta \left(\frac{1}{\text{md}(\mathbf{c})} \right) \right)^{\text{md}(\mathbf{c})}$$

\implies After $O(\text{md}(\mathbf{c}) \log n)$ rounds, $R(\mathbf{c}^{(t)}) = 1 + o(1)$.

Phase 3

$$R(\mathbf{c}^{(t)}) = 1 + o(1) \implies c_1^{(t)} = \frac{n - q^{(t)}}{R(\mathbf{c}^{(t)})} \approx n - q^{(t)}$$

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\implies Plurality Consensus is reached within $O(\log n)$ rounds.

Extension to d -Regular Expanders

Theorem

Given a d -regular expander graph, $k = O((n/\log n)^{1/3})$ and $c_1 \geq (1 + \epsilon) \cdot c_2$ with $\epsilon > 0$, using polylogarithmic memory and message size the plurality consensus problem can be solved in w.h.p. $O(\text{md}(\mathbf{c})\text{polylog}(n))$ rounds.

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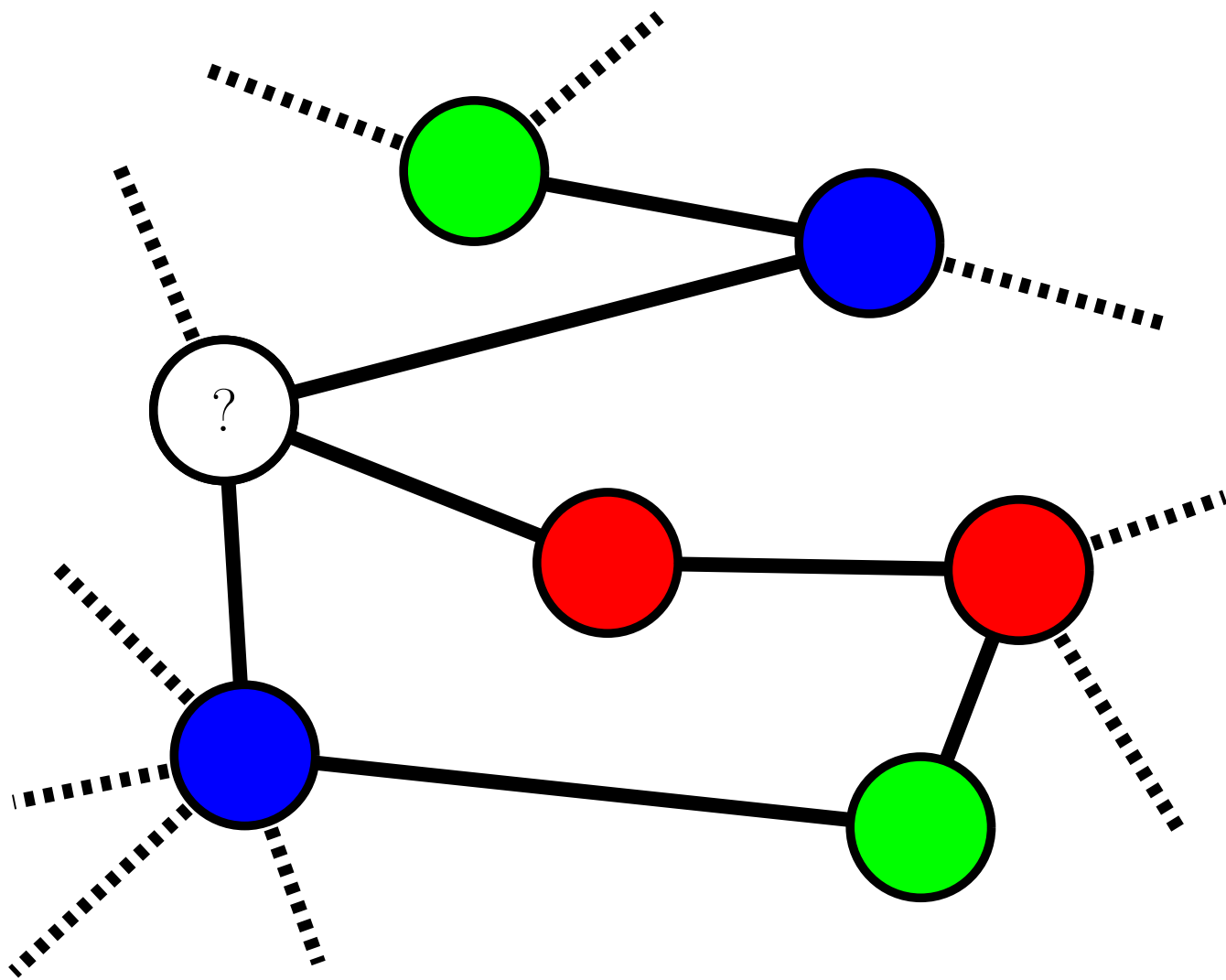
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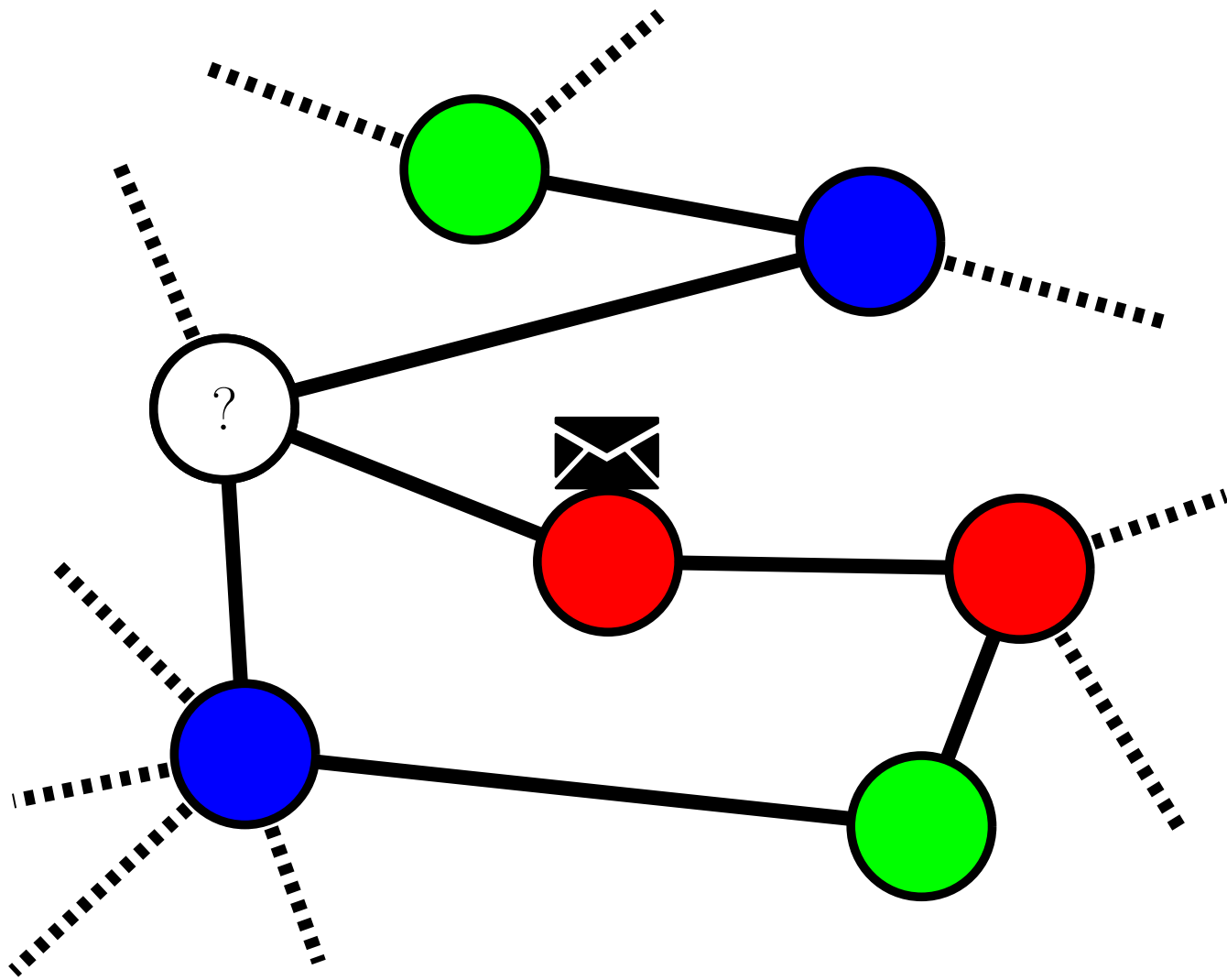
Idea

Simulate Undecided-State Dynamics on complete graph by sampling via n parallel random walks.
(Rapidly mixing property)

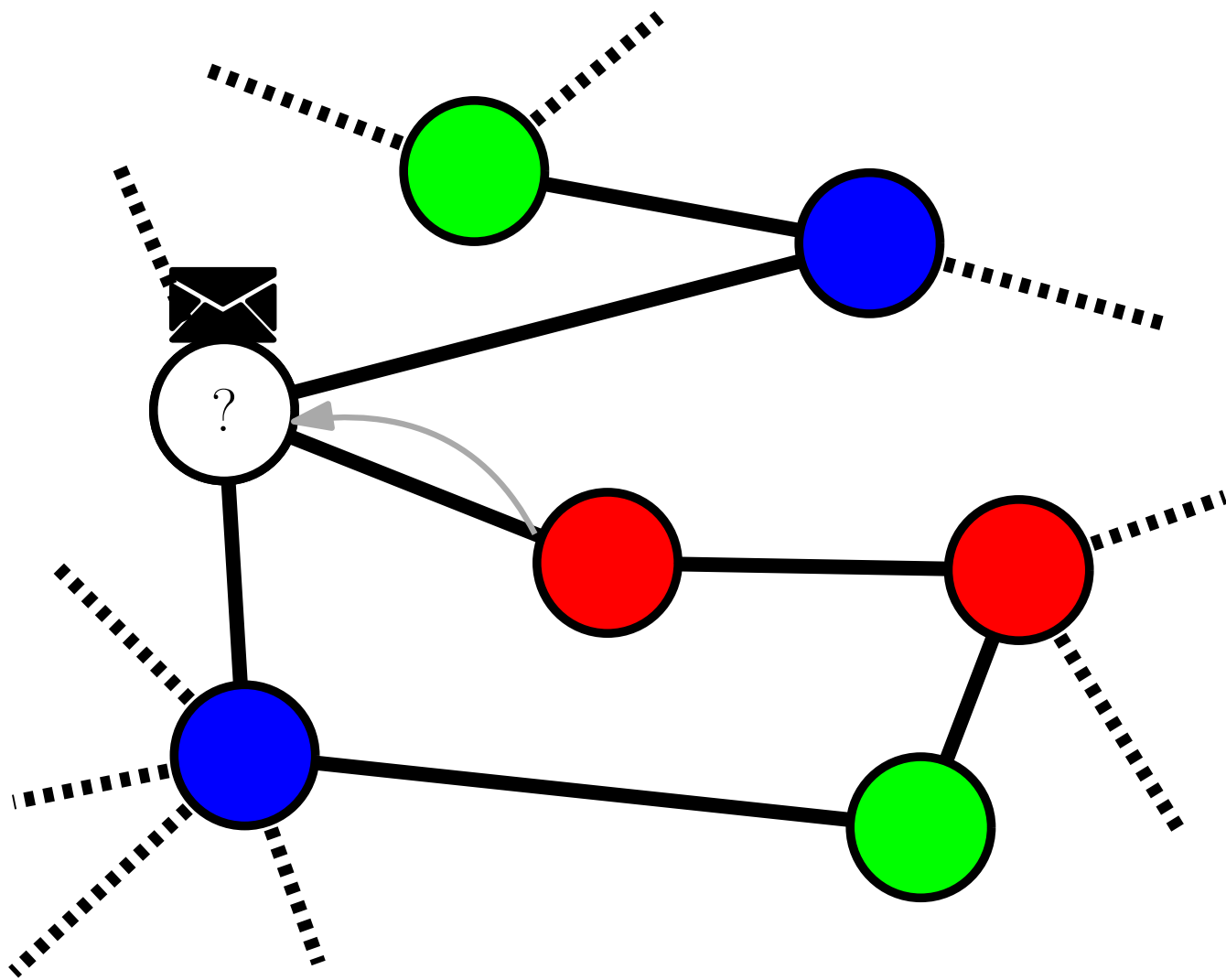
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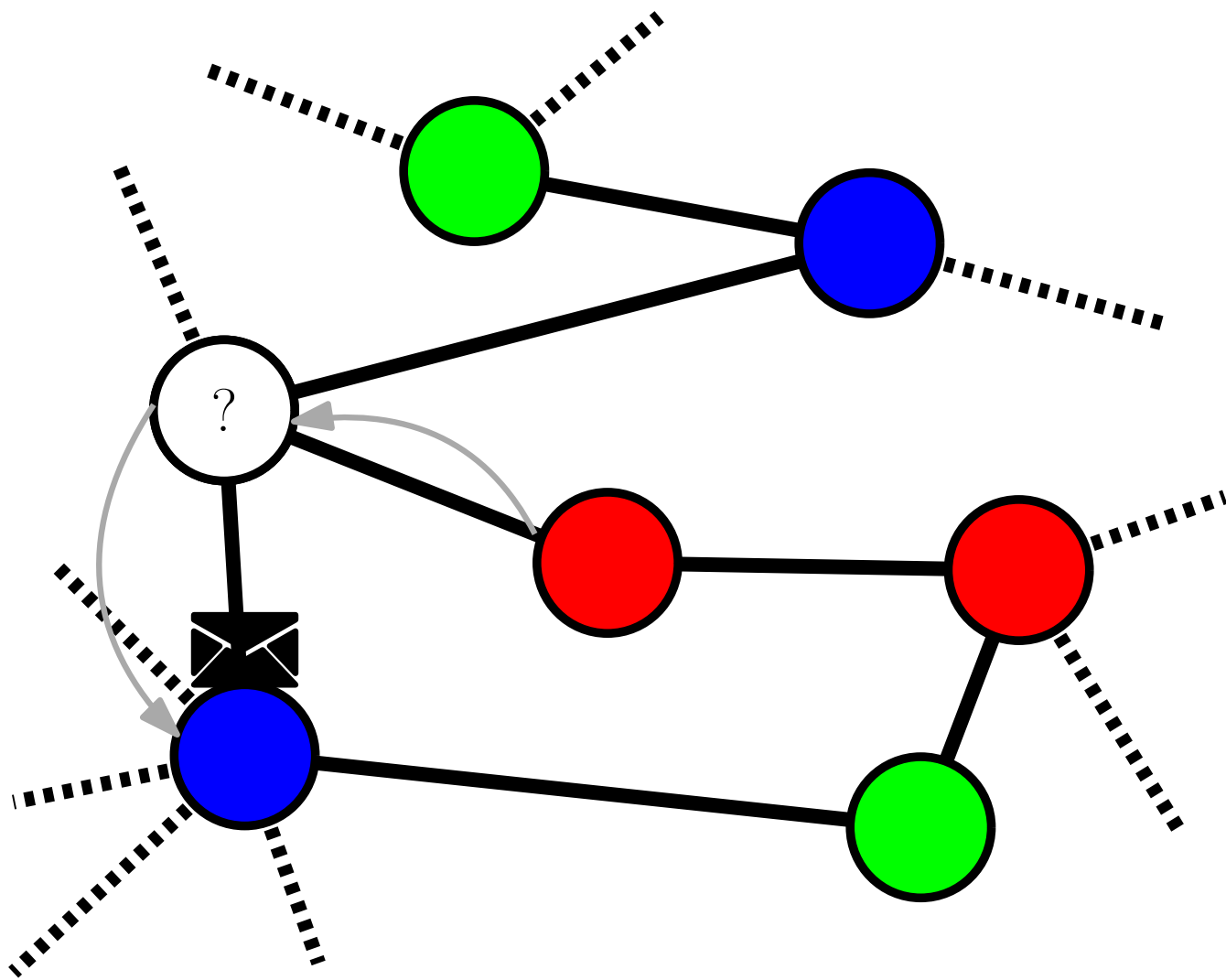
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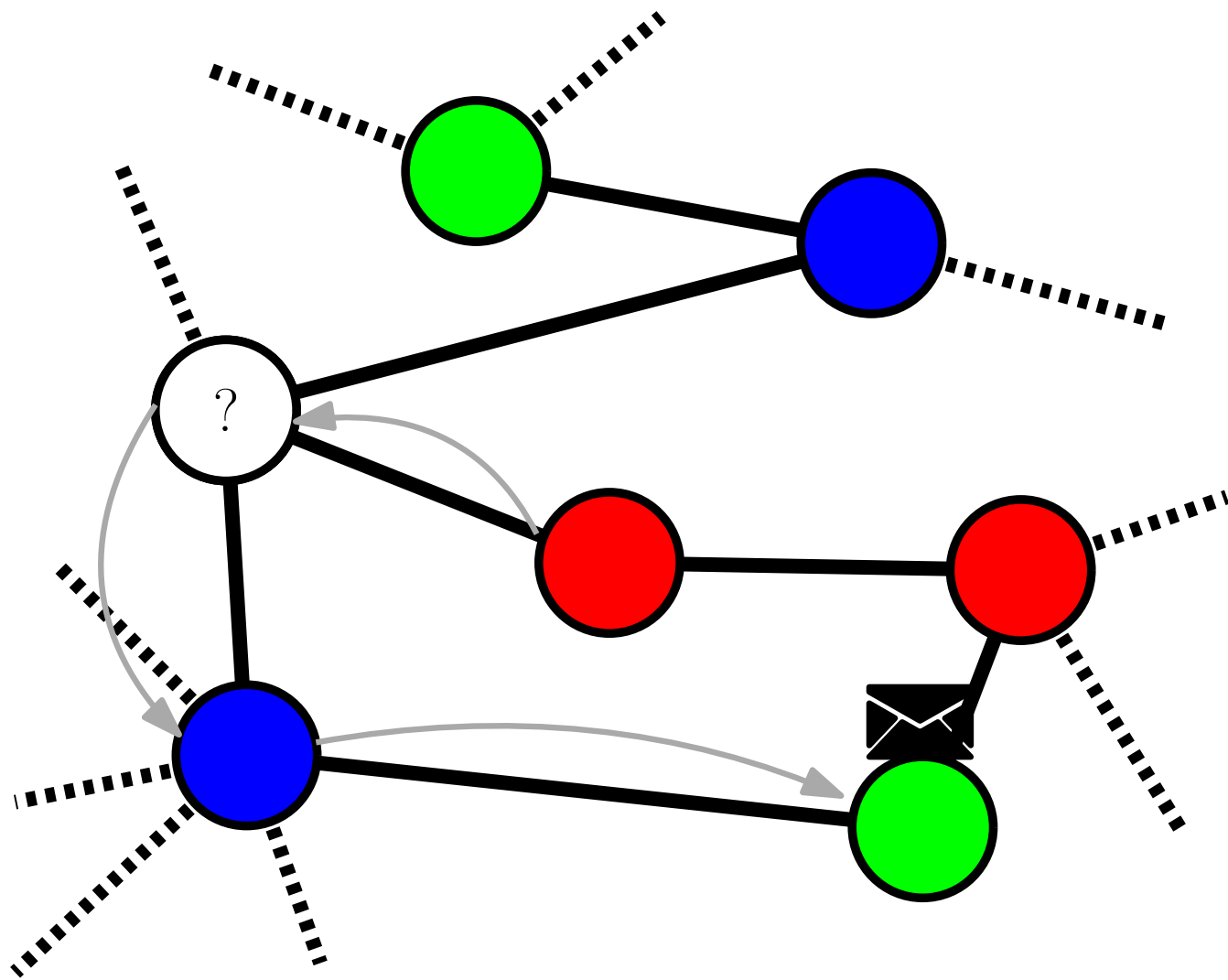
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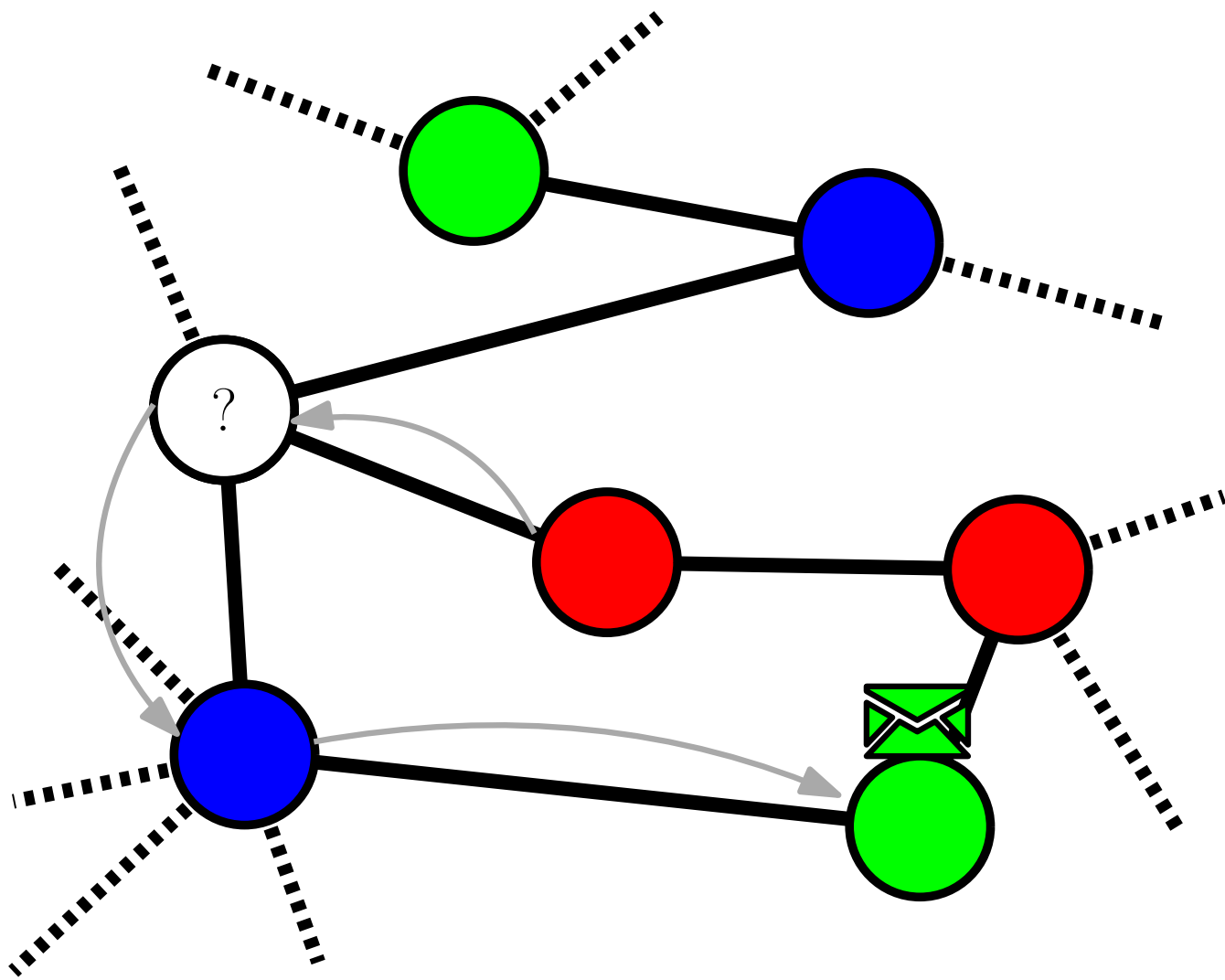
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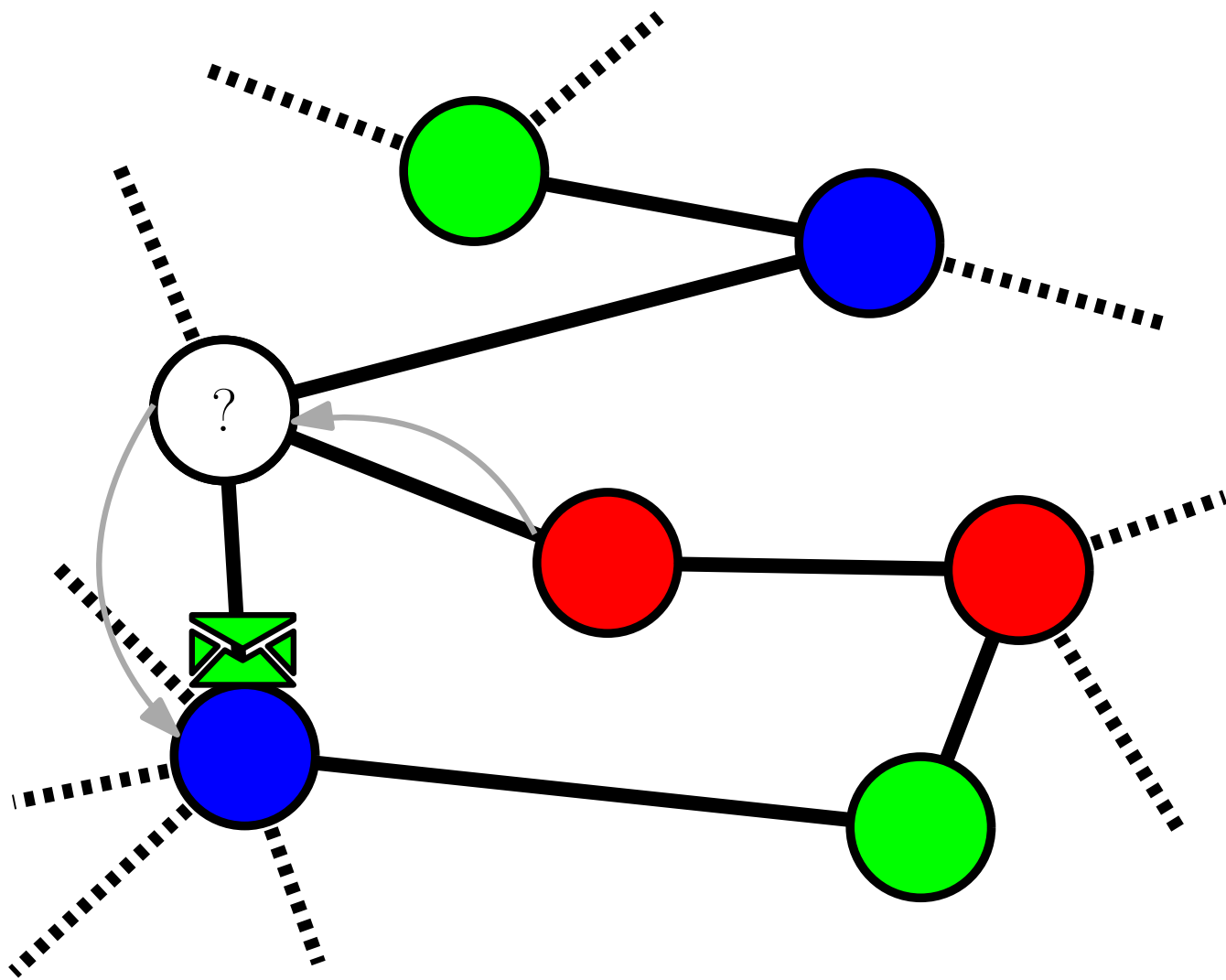
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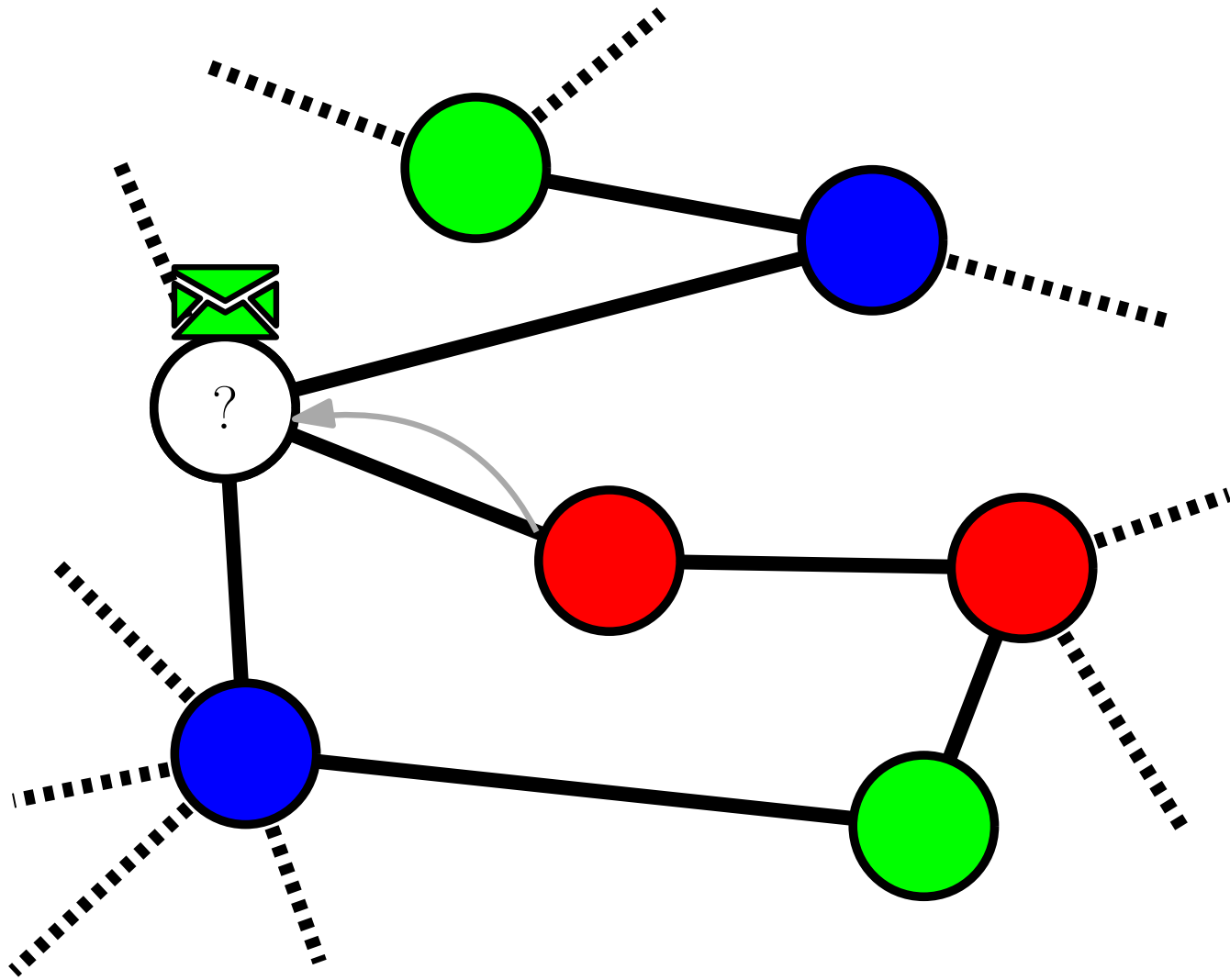
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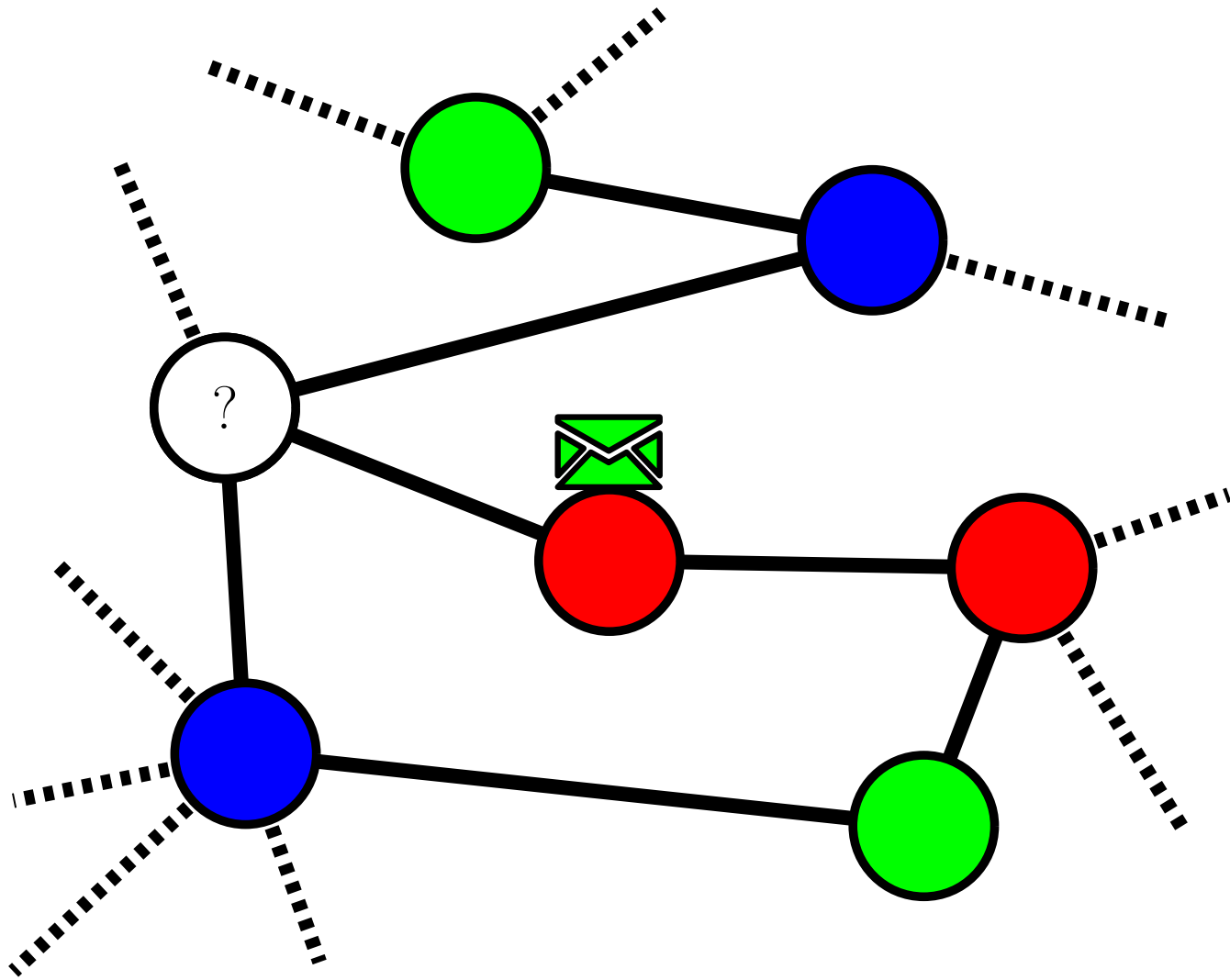
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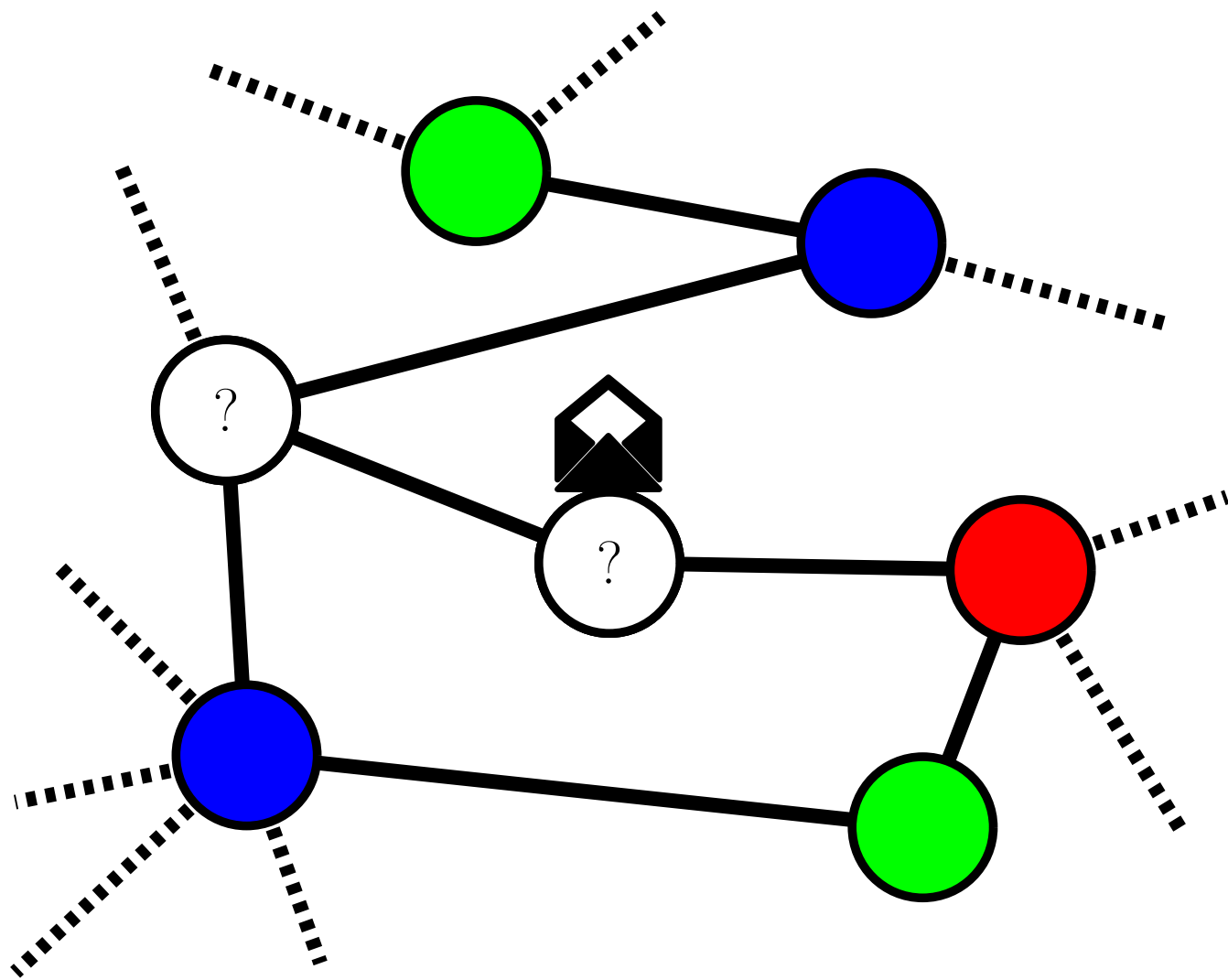
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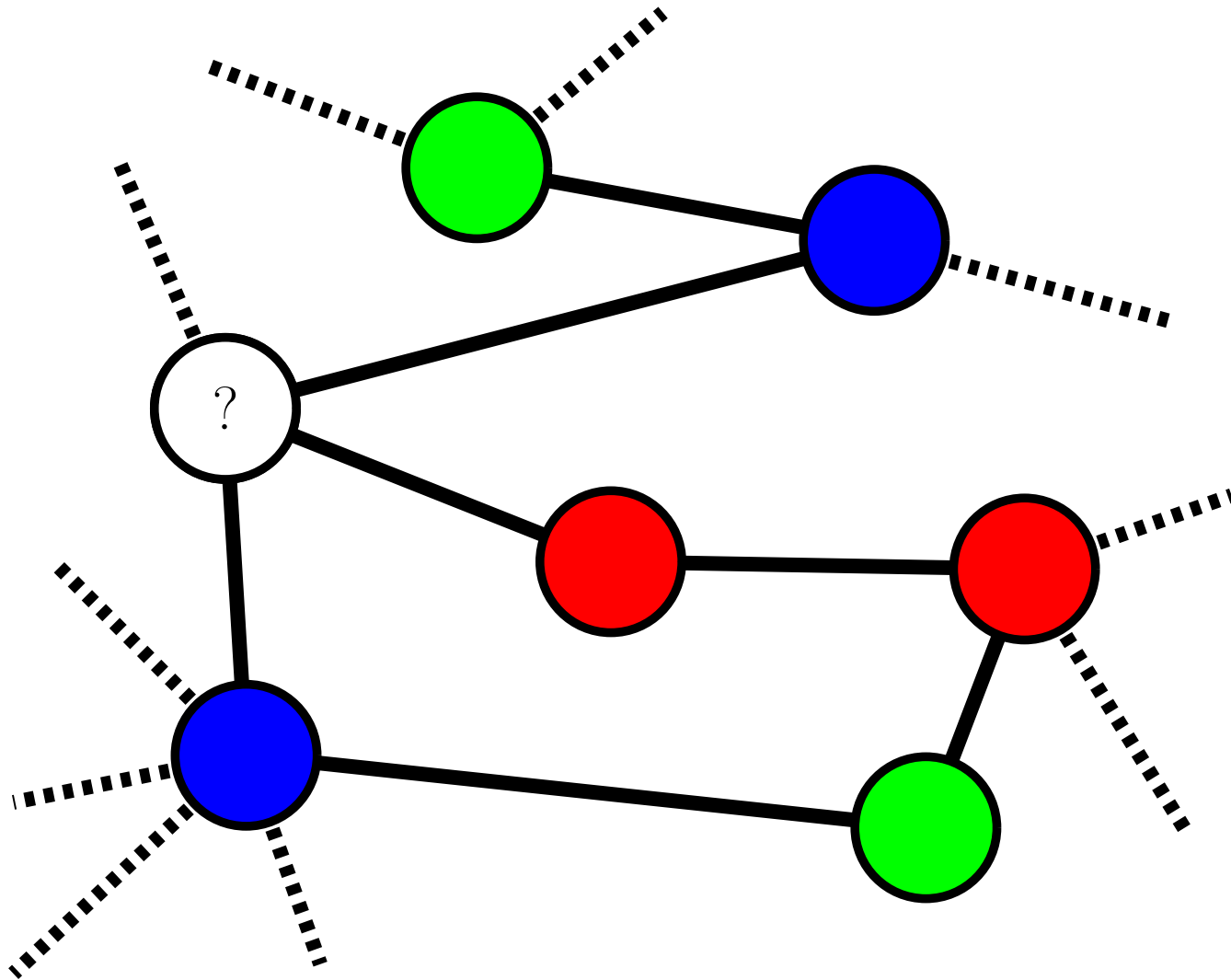


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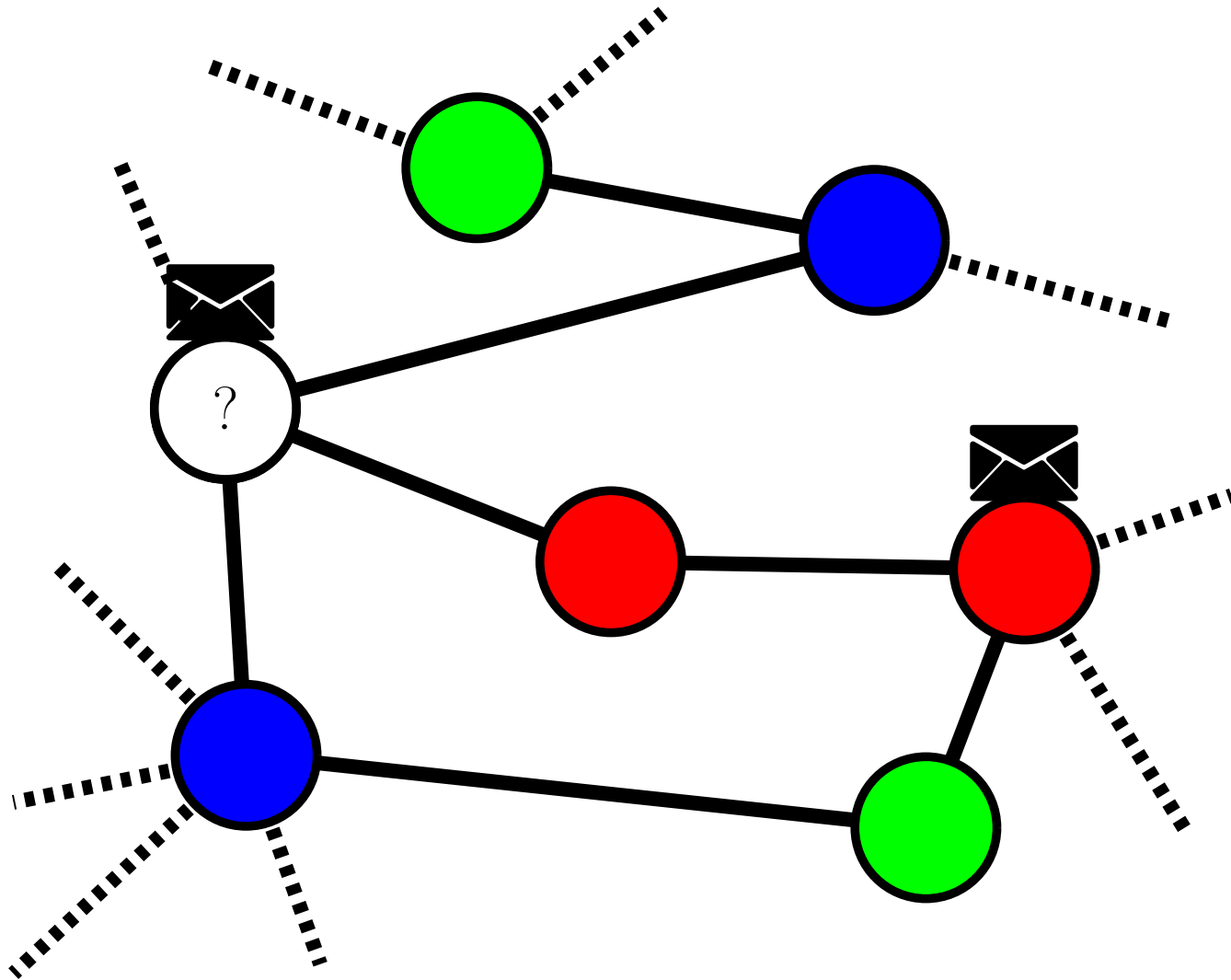
Random Walks in the *Gossip* Model

Issue. The *Gossip* model with $O(\text{polylog}n)$ limit on message size: congestion when random walks meet.



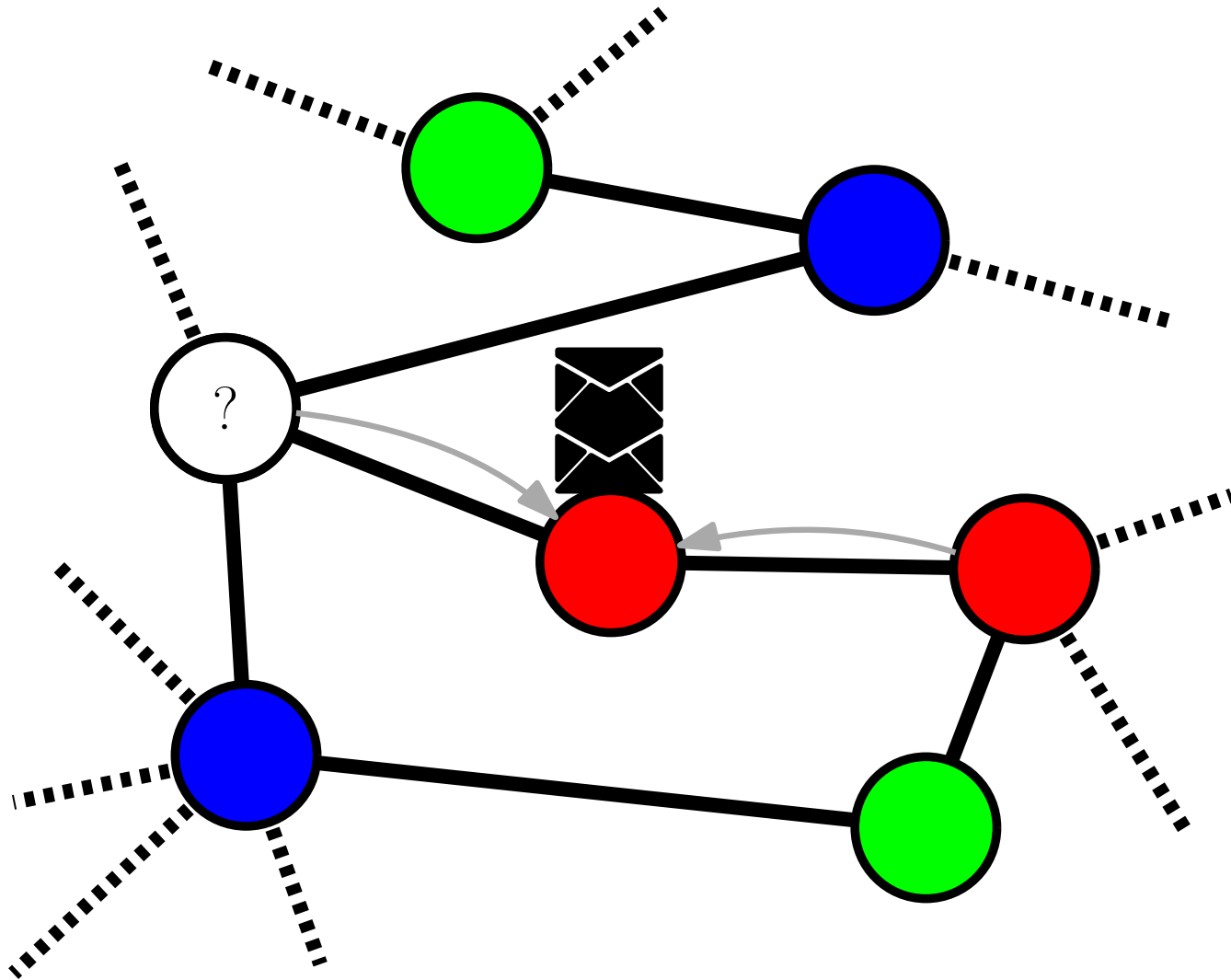
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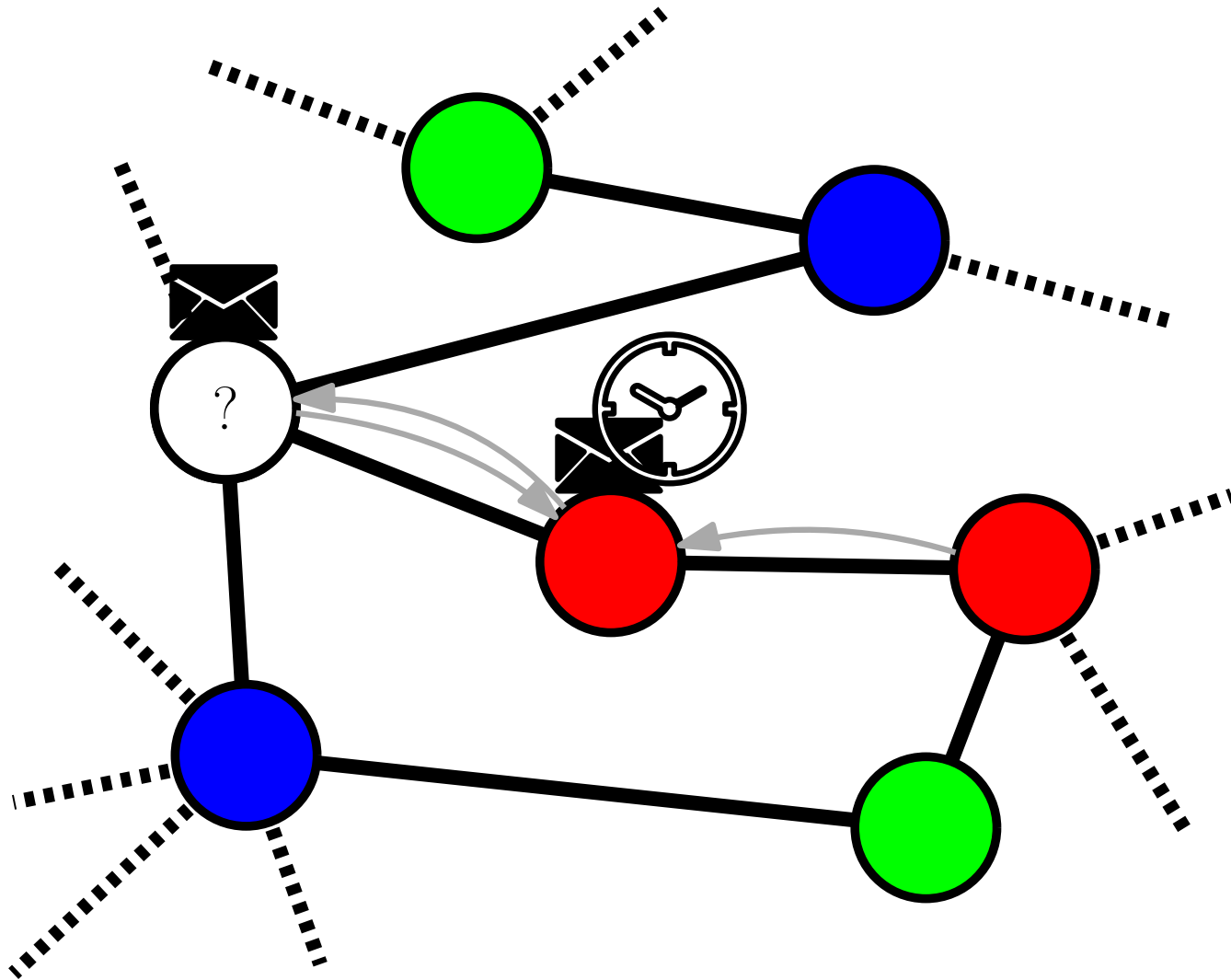
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Stochastic dependence: positions of tokens.

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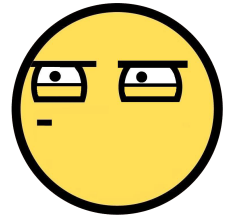
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Self-Stabilizing Repeated Balls-into-Bins. (Submitted).

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Theorem

Consider the "*Gossip*" random walks process on a complete graph with n nodes, and n tokens initially distributed in an arbitrary way.

After $O(n)$ rounds, w.h.p. the congestion is at most $O(\log n)$. Moreover, w.h.p. it keeps below $O(\log n)$ for $t = O(n^c)$ rounds (for any $c > 0$).

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Open Problem: bound the congestion on graphs other than the complete one.

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- $\text{md}(\mathbf{c})$: global measure of bias, key of the Undecided-State Dynamic.
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- Undecided-State Dynamics + sampling via random walks = efficient protocol for regular expander graphs. Similar protocols for other classes of graphs...?

Vielen Dank!